# Math 3321 <br> Introduction to Second Order Linear ODEs 

University of Houston

Lecture 07

## Outline

(1) Basic Terminology
(2) Second Order Linear Homogeneous Equations
(3) Examples

## Basic Terminology

Second order differential equations can be written as

$$
F\left(x, y^{\prime}, y^{\prime \prime}\right)=0
$$

This chapter is concerned with a specific type of second order equations. These are the second order linear equations.

## Definition

A second order linear differential equation is an equation which can be written in the form

$$
\begin{equation*}
y^{\prime \prime}+p(x) y^{\prime}+q(x) y=f(x) \tag{1}
\end{equation*}
$$

where $p, q$, and $f$ are continuous functions on some interval $I$.

## Basic Terminology

## Definitions

Given a second order linear differential equation (1), we have the following terminology. The functions $p$ and $q$ are called the coefficients of the equation. The function $f$ is called the forcing function or the nonhomogeneous term.

Examples:

1. $y^{\prime \prime}+6 y^{\prime}+8 y=e^{3 x}+\cos (2 x)$
2. $x^{2} y^{\prime \prime}+7 x y^{\prime}+8 y=x^{2}$
3. $x^{2} y^{\prime \prime}+3 x y^{3} y^{\prime}-y=e^{x}$

## Basic Terminology

## Existence and Uniqueness

Given a second order linear equation (1). Let $a$ be any point in the interval $I$, and let $\alpha$ and $\beta$ be any two real numbers. The IVP

$$
y^{\prime \prime}+p(x) y^{\prime}+q(x) y=f(x), y(a)=\alpha, y^{\prime}(a)=\beta
$$

has a unique solution.

## Remark

Unlike the case of first order linear equations where we can always find a solution, there is no general method for solving second (or higher) order linear differential equations. There will be methods for solving certain types of second order linear equations and these will be the focus of this chapter.

## Basic Terminology

## Definitions

The linear ODE (1) is homogeneous if the function $f$ on the right side of the equations is 0 for all $x \in I$. In this case, equation (1) becomes

$$
\begin{equation*}
y^{\prime \prime}+p(x) y^{\prime}+q(x) y=0 \tag{H}
\end{equation*}
$$

The equation (1) is nonhomogeneous if $f$ is not the zero function on $I$.
As we will see moving forward, most of our attention will be devoted to solving homogeneous equations.

## Second Order Linear Homogeneous Equations

## Terminology

The first thing we note about $(\mathrm{H})$ is that the zero function $y \equiv 0$ is a solution:

$$
y \equiv 0 \text { gives } y^{\prime} \equiv 0 \text { and } y^{\prime \prime} \equiv 0
$$

therefore we have

$$
0+p(x) 0+q(x) 0=0
$$

We call the zero function the trivial solution. Our interest is in finding nontrivial solutions. Unless otherwise stated, the term "solution" will mean "nontrivial solution."

## Second Order Linear Homogeneous Equations

## Theorem 1

Given any two solutions $y=y_{1}(x)$ and $y=y_{2}(x)$ for (H), then $u(x)=y_{1}(x)+y_{2}(x)$ is also a solution for (H).

## Second Order Linear Homogeneous Equations

## Theorem 1

Given any two solutions $y=y_{1}(x)$ and $y=y_{2}(x)$ for (H), then $u(x)=y_{1}(x)+y_{2}(x)$ is also a solution for (H).

Denote the ODE as a differential operator

$$
L(y)=y^{\prime \prime}+p(x) y^{\prime}+q(x) y
$$

As we have seen before, $L$ is linear.
Hence

$$
L\left(y_{1}+y_{2}\right)=L\left(y_{1}\right)+L\left(y_{2}\right)
$$

So,

$$
L\left(y_{1}\right)=0 \text { and } L\left(y_{2}\right)=0 \text { implies } L\left(y_{1}+y_{2}\right)=0
$$

## Second Order Linear Homogeneous Equations

## Theorem 2

Given any solution $y=y(x)$ for $(\mathrm{H})$ and $C$ a real number, then $u(x)=C y(x)$ is also a solution for (H).

## Second Order Linear Homogeneous Equations

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As above, denote the ODE as a differential operator

$$
L(y)=y^{\prime \prime}+p(x) y^{\prime}+q(x) y
$$

By the linearity of $L$,

$$
L(C y)=C L(y)
$$

So,

$$
L(y)=0 \text { implies } L(C y)=0
$$

## Second Order Linear Homogeneous Equations

## Definition

Let $f=f(x)$ and $g=g(x)$ be functions defined on some interval $I$, and let $C_{1}$ and $C_{2}$ be real numbers. We call the expression

$$
C_{1} f(x)+C_{2} g(x)
$$

a linear combination of $f$ and $g$.

## Theorem 3

Given any two solutions $y=y_{1}(x)$ and $y=y_{2}(x)$ for $(\mathrm{H})$ as well as real numbers $C_{1}$ and $C_{2}$, then

$$
y(x)=C_{1} y_{1}(x)+C_{2} y_{2}(x)
$$

is also a solution for $(\mathrm{H})$.

## Second Order Linear Homogeneous Equations

## Note

Theorem 3 tells us that any linear combination of solutions of $(H)$ is also a solution of $(\mathrm{H})$.

## Fact

The function $y=C_{1} y_{1}(x)+C_{2} y_{2}(x)$ is the general solution to $(\mathrm{H})$ if and only if

$$
y_{1}(x) y_{2}^{\prime}(x)-y_{2}(x) y_{1}^{\prime}(x) \neq 0 .
$$

## Second Order Linear Homogeneous Equations

## Definition

Let $y=y_{1}(x)$ and $y=y_{2}(x)$ be solutions of (H). The function $W$ defined by

$$
W\left[y_{1}, y_{2}\right](x)=y_{1}(x) y_{2}^{\prime}(x)-y_{2}(x) y_{1}^{\prime}(x)
$$

is called the Wronskian of $y_{1}$ and $y_{2}$.
We use the notation $W\left[y_{1}, y_{2}\right](x)$ to emphasize that the Wronskian is a function of $x$ that is determined by two solutions $y_{1}, y_{2}$ of equation $(\mathrm{H})$. When there is no danger of confusion, we will shorten the notation to $W(x)$.

There is a short-hand way to represent the Wronskian of two solutions of equation (H) using the determinant of a $2 \times 2$ matrix. We will write

$$
W(x)=\left|\begin{array}{ll}
y_{1}(x) & y_{2}(x) \\
y_{1}^{\prime}(x) & y_{2}^{\prime}(x)
\end{array}\right|=y_{1}(x) y_{2}^{\prime}(x)-y_{2}(x) y_{1}^{\prime}(x)
$$

## Second Order Linear Homogeneous Equations

Examples: Find the Wronskian for the following functions.

1. $y_{1}=e^{3 x}$ and $y_{2}=e^{-x}$

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\begin{aligned}
W(x) & =y_{1}(x) y_{2}^{\prime}(x)-y_{2}(x) y_{1}^{\prime}(x) \\
& =-e^{3 x} e^{-x}-e^{-x} 3 e^{3 x}=-4 e^{2 x}
\end{aligned}
$$

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2. $y_{1}=x^{3}$ and $y_{2}=5 e^{3 x}$

$$
\begin{aligned}
W(x) & =y_{1}(x) y_{2}^{\prime}(x)-y_{2}(x) y_{1}^{\prime}(x) \\
& =x^{3}\left(15 e^{3 x}\right)-5 e^{3 x}\left(3 x^{2}\right)=15 e^{3 x} x^{2}(x-1)
\end{aligned}
$$

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& =x^{3}\left(15 x^{2}\right)-5 x^{3}\left(3 x^{2}\right)=15 x^{5}-15 x^{5}=0
\end{aligned}
$$

## Second Order Linear Homogeneous Equations

## Theorem 4

Let $y=y_{1}(x)$ and $y=y_{2}(x)$ be solutions of $(\mathrm{H})$, and let $W(x)$ be their Wronskian. Exactly one of the following holds:
(i) $W(x)=0$ for all $x \in I$ and $y_{1}$ is a constant multiple of $y_{2}$ (or vice versa).
(ii) $W(x) \neq 0$ for all $x \in I$ and $y=C_{1} y_{1}(x)+C_{2} y_{2}(x)$ is the general solution of (H).

## Second Order Linear Homogeneous Equations

## Second Order Linear Homogeneous Equations

## Definitions

A pair of solutions $y=y_{1}(x)$ and $y=y_{2}(x)$ of equation $(\mathrm{H})$ is a fundamental set of solutions if

$$
W\left[y_{1}, y_{2}\right](x) \neq 0 \text { for all } x \in I .
$$

A fundamental set of solutions is also called a solution basis.

## Second Order Linear Homogeneous Equations


#### Abstract

Definitions Given two functions $f=f(x)$ and $g=g(x)$ defined on an interval $I$, we say that $f$ and $g$ are linearly dependent on $I$ if there exists a number $\lambda$ such that $g(x)=\lambda f(x)$ for all $x \in I$. When the functions are not linearly dependent, we say $f$ and $g$ are linearly independent.


## Second Order Linear Homogeneous Equations

## Definitions

Given two functions $f=f(x)$ and $g=g(x)$ defined on an interval $I$, we say that $f$ and $g$ are linearly dependent on $I$ if there exists a number $\lambda$ such that $g(x)=\lambda f(x)$ for all $x \in I$. When the functions are not linearly dependent, we say $f$ and $g$ are linearly independent.

Example 1. Consider the functions $f(x)=2 x^{2}, g(x)=-x^{2}$
Clearly, we have that

$$
g(x)=-\frac{1}{2} f(x), \quad \text { for all } x
$$

This shows that $f$ and $g$ are linearly dependent.

## Second Order Linear Homogeneous Equations

## Definitions

Given two functions $f=f(x)$ and $g=g(x)$ defined on an interval $I$, we say that $f$ and $g$ are linearly dependent on $I$ if there exists a number $\lambda$ such that $g(x)=\lambda f(x)$ for all $x \in I$. When the functions are not linearly dependent, we say $f$ and $g$ are linearly independent.

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Clearly, we have that

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$$

This shows that $f$ and $g$ are linearly dependent.
Example 2. Consider the functions $f(x)=2 x^{2}, g(x)=x$
Suppose that there is a $\lambda \neq 0$ such that

$$
g(x)=\lambda f(x) \Rightarrow x=\lambda 2 x^{2} \Rightarrow x(1-2 \lambda x)=0
$$

on an interval. This is false for any $\lambda$.
This shows that $f$ and $g$ are linearly independent.

## Second Order Linear Homogeneous Equations

## Theorem 5

Let $f=f(x)$ and $g=g(x)$ be differentiable functions on an interval $I$. If $f$ and $g$ are linearly dependent on $I$, then $W(x)=0$ for all $x \in I$.

Equivalently, we can say:
Let $f=f(x)$ and $g=g(x)$ be differentiable functions on an interval $I$. If $W(x) \neq 0$ for at least one $x \in I$, then $f$ and $g$ are linearly independent on $I$.

## Second Order Linear Homogeneous Equations

## Theorem 4 Restated

Let $y=y_{1}(x)$ and $y=y_{2}(x)$ be solutions of $(\mathrm{H})$, and let $W(x)$ be their Wronskian. Exactly one of the following holds:
(i) $W(x)=0$ for all $x \in I ; y_{1}$ and $y_{2}$ are linearly dependent.
(ii) $W(x) \neq 0$ for all $x \in I$; $y_{1}$ and $y_{2}$ are linearly independent and $y=C_{1} y_{1}(x)+C_{2} y_{2}(x)$ is the general solution of $(\mathrm{H})$.

## Examples

1. Verify that the given functions $y_{1}$ and $y_{2}$ are solutions of the given differential equation. Do they constitute a fundamental set of solutions of the equation?

$$
y^{\prime \prime}-y^{\prime}-6 y=0 ; y_{1}=e^{3 x}, y_{2}=e^{-2 x}
$$

## Examples

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$$

We have

$$
y_{1}^{\prime}(x)=3 e^{3 x}, y_{1}^{\prime \prime}(x)=9 e^{3 x}
$$

Hence

$$
y_{1}^{\prime \prime}-y_{1}^{\prime}-6 y_{1}=9 e^{3 x}-3 e^{3 x}-6 e^{3 x}=0
$$

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We have

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$$

Hence

$$
y_{1}^{\prime \prime}-y_{1}^{\prime}-6 y_{1}=9 e^{3 x}-3 e^{3 x}-6 e^{3 x}=0
$$

Similarly,

$$
y_{2}^{\prime}(x)=-2 e^{-2 x}, y_{2}^{\prime \prime}(x)=4 e^{-2 x}
$$

Hence

$$
y_{2}^{\prime \prime}-y_{2}^{\prime}-6 y_{2}=4 e^{-2 x}+2 e^{-2 x}-6 e^{-2 x}=0
$$

## Examples

Do they constitute a fundamental set of solutions of the equation?

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$$
\begin{aligned}
W(x) & =y_{1}(x) y_{2}^{\prime}(x)-y_{2}(x) y_{1}^{\prime}(x) \\
& =e^{3 x}(-2) e^{-2 x}-e^{-2 x} 3 e^{3 x}=-5 e^{x}
\end{aligned}
$$

Yes, they do form a fundamental set of solutions.

## Examples

2. Verify that the given functions $y_{1}$ and $y_{2}$ are solutions of the given differential equation. Do they constitute a fundamental set of solutions of the equation?

$$
y^{\prime \prime}+4 y=0 ; y_{1}=\cos (2 x), y_{2}=\sin (2 x)
$$

## Examples

2. Verify that the given functions $y_{1}$ and $y_{2}$ are solutions of the given differential equation. Do they constitute a fundamental set of solutions of the equation?

$$
y^{\prime \prime}+4 y=0 ; y_{1}=\cos (2 x), y_{2}=\sin (2 x)
$$

We have

$$
y_{1}^{\prime}(x)=-2 \sin (2 x), y_{1}^{\prime \prime}(x)=-4 \cos (2 x)
$$

Hence

$$
y_{1}^{\prime \prime}+4 y_{1}=-4 \cos (2 x)+4 \cos (2 x)=0
$$

## Examples

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y^{\prime \prime}+4 y=0 ; y_{1}=\cos (2 x), y_{2}=\sin (2 x)
$$

We have

$$
y_{1}^{\prime}(x)=-2 \sin (2 x), y_{1}^{\prime \prime}(x)=-4 \cos (2 x)
$$

Hence

$$
y_{1}^{\prime \prime}+4 y_{1}=-4 \cos (2 x)+4 \cos (2 x)=0
$$

Similarly,

$$
y_{2}^{\prime}(x)=2 \cos (2 x), y_{2}^{\prime \prime}(x)=-4 \sin (2 x)
$$

Hence

$$
y_{2}^{\prime \prime}+4 y_{2}=-4 \sin (2 x)+4 \sin (2 x)=0
$$

## Examples

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$$
\begin{aligned}
W(x) & =y_{1}(x) y_{2}^{\prime}(x)-y_{2}(x) y_{1}^{\prime}(x) \\
& =\cos (2 x) 2 \cos (2 x)-\sin (2 x)(-2) \sin (2 x) \\
& =2\left(\cos ^{2}(2 x)+\sin ^{2}(2 x)\right)=2
\end{aligned}
$$

Yes, they do form a fundamental set of solutions.

## Examples

3. Show that the given functions are linearly independent on an interval $I$ and find a second-order linear homogeneous equation having the pair as a fundamental set of solutions.

$$
y_{1}=e^{3 x}, y_{2}=e^{-x}
$$

## Examples

3. Show that the given functions are linearly independent on an interval $I$ and find a second-order linear homogeneous equation having the pair as a fundamental set of solutions.

$$
y_{1}=e^{3 x}, y_{2}=e^{-x}
$$

Proof 1. $y_{1}$ and $y_{2}$ are linearly independent on an interval $I$ if there is no $\lambda \neq 0$ such that $y_{1}(x)=\lambda y_{2}(x)$.
However, $e^{3 x}=\lambda e^{-x}$ on an interval implies $e^{4 x}=\lambda$ on an interval, which is false.

## Examples

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Proof 1. $y_{1}$ and $y_{2}$ are linearly independent on an interval $I$ if there is no $\lambda \neq 0$ such that $y_{1}(x)=\lambda y_{2}(x)$.
However, $e^{3 x}=\lambda e^{-x}$ on an interval implies $e^{4 x}=\lambda$ on an interval, which is false.
Proof 2. We compote the Wronskian: $W(x)=y_{1}(x) y_{2}^{\prime}(x)-y_{2}(x) y_{1}^{\prime}(x)$ We find:

$$
W(x)=-e^{3 x} e^{-x}-e^{-x} 3 e^{3 x}=-4 e^{2 x}
$$

Since $W(x) \neq 0$ then the given functions are linearly independent on an interval $I$.

## Examples

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y_{1}=e^{3 x}, y_{2}=e^{-x}
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## Examples

3. Show that the given functions are linearly independent on an interval $I$ and find a second-order linear homogeneous equation having the pair as a fundamental set of solutions.

$$
y_{1}=e^{3 x}, y_{2}=e^{-x}
$$

If the second-order linear homogeneous equation

$$
y^{\prime \prime}+a y^{\prime}+b y=0
$$

has 2 solutions of the form $e^{r x}$, then

$$
r^{2} e^{r x}+a r e^{r x}+b e^{r x}=0
$$

Hence it must be

$$
r^{2}+a r+b=0
$$

with solutions $r=3,-1$. Thus it must be

$$
r^{2}+a r+b=(r-3)(r+1)=r^{2}-2 r-3
$$

Thus is must be $y^{\prime \prime}-2 y^{\prime}-3 y=0$

