

# Math 2331 – Linear Algebra

## 6.1 Inner Product, Length & Orthogonality

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## 6.1 Inner Product, Length & Orthogonality

- Inner Product: Examples, Definition, Properties
- Length of a Vector: Examples, Definition, Properties
- Orthogonal
  - Orthogonal Vectors
  - The Pythagorean Theorem
  - Orthogonal Complements
- Row, Null and Columns Spaces



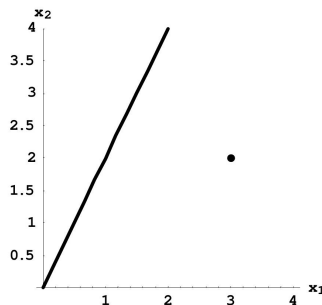
# Motivation: Example

Not all linear systems have solutions.

## Example

No solution to  $\begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$  exists. Why?

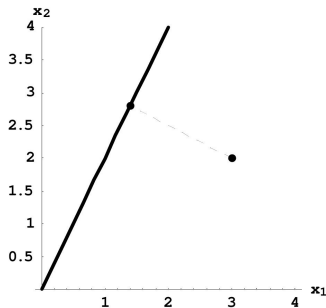
$A\mathbf{x}$  is a point on the line spanned by  $\left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right\}$  and  $\mathbf{b}$  is not on the line. So  $A\mathbf{x} \neq \mathbf{b}$  for all  $\mathbf{x}$ .



# Motivation: Example (cont.)

Instead find  $\hat{\mathbf{x}}$  so that  $A\hat{\mathbf{x}}$  lies "closest" to  $\mathbf{b}$ . Using information we will learn in this chapter, we will find that

$$\hat{\mathbf{x}} = \begin{bmatrix} 1.4 \\ 0 \end{bmatrix}, \text{ so that } A\hat{\mathbf{x}} = \begin{bmatrix} 1.4 \\ 2.8 \end{bmatrix}.$$



Segment joining  $A\hat{\mathbf{x}}$  and  $\mathbf{b}$  is *perpendicular* (or *orthogonal*) to the set of solutions to  $A\mathbf{x} = \mathbf{b}$ .

Need to develop fundamental ideas of *length*, *orthogonality* and *orthogonal projections*.



# Inner Product

## Inner Product

Inner product or dot product of

$$\mathbf{u} = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix} \quad \text{and} \quad \mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} :$$

$$\begin{aligned} \mathbf{u} \cdot \mathbf{v} &= \mathbf{u}^T \mathbf{v} = \begin{bmatrix} u_1 & u_2 & \cdots & u_n \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} \\ &= u_1 v_1 + u_2 v_2 + \cdots + u_n v_n \end{aligned}$$

$$\mathbf{v} \cdot \mathbf{u} = \mathbf{v}^T \mathbf{u} = \mathbf{u}^T \mathbf{v} = \mathbf{u} \cdot \mathbf{v}$$



# Inner Product: Properties

## Theorem (1)

Let  $\mathbf{u}, \mathbf{v}$  and  $\mathbf{w}$  be vectors in  $\mathbf{R}^n$ , and let  $c$  be any scalar. Then

- $\mathbf{u} \cdot \mathbf{v} = \mathbf{v} \cdot \mathbf{u}$
- $(\mathbf{u} + \mathbf{v}) \cdot \mathbf{w} = \mathbf{u} \cdot \mathbf{w} + \mathbf{v} \cdot \mathbf{w}$
- $(c\mathbf{u}) \cdot \mathbf{v} = c(\mathbf{u} \cdot \mathbf{v}) = \mathbf{u} \cdot (c\mathbf{v})$
- $\mathbf{u} \cdot \mathbf{u} \geq 0$ , and  $\mathbf{u} \cdot \mathbf{u} = 0$  if and only if  $\mathbf{u} = \mathbf{0}$ .

Combining parts b and c, one can show

$$(c_1\mathbf{u}_1 + \cdots + c_p\mathbf{u}_p) \cdot \mathbf{w} = c_1(\mathbf{u}_1 \cdot \mathbf{w}) + \cdots + c_p(\mathbf{u}_p \cdot \mathbf{w})$$



# Length of a Vector

## Length of a Vector

For  $\mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$ , the **length** or **norm of  $\mathbf{v}$**  is the nonnegative scalar  $\|\mathbf{v}\|$  defined by

$$\|\mathbf{v}\| = \sqrt{\mathbf{v} \cdot \mathbf{v}} = \sqrt{v_1^2 + v_2^2 + \cdots + v_n^2} \quad \text{and} \quad \|\mathbf{v}\|^2 = \mathbf{v} \cdot \mathbf{v}.$$

For any scalar  $c$ ,

$$\|c\mathbf{v}\| = |c| \|\mathbf{v}\|$$



# Length of a Vector: Example

## Example

If  $\mathbf{v} = \begin{bmatrix} a \\ b \end{bmatrix}$ , then  $\|\mathbf{v}\| = \sqrt{a^2 + b^2}$  (distance between  $\mathbf{0}$  and  $\mathbf{v}$ ).

Picture:





# Distance

## Distance

The **distance between  $\mathbf{u}$  and  $\mathbf{v}$**  in  $\mathbf{R}^n$ :

$$\text{dist}(\mathbf{u}, \mathbf{v}) = \|\mathbf{u} - \mathbf{v}\|.$$

## Example

This agrees with the usual formulas for  $\mathbf{R}^2$  and  $\mathbf{R}^3$ . Let  $\mathbf{u} = (u_1, u_2)$  and  $\mathbf{v} = (v_1, v_2)$ .

Then  $\mathbf{u} - \mathbf{v} = (u_1 - v_1, u_2 - v_2)$  and

$$\begin{aligned}\text{dist}(\mathbf{u}, \mathbf{v}) &= \|\mathbf{u} - \mathbf{v}\| = \|(u_1 - v_1, u_2 - v_2)\| \\ &= \sqrt{(u_1 - v_1)^2 + (u_2 - v_2)^2}\end{aligned}$$



# Orthogonal Vectors

$$[\text{dist}(\mathbf{u}, \mathbf{v})]^2 = \|\mathbf{u} - \mathbf{v}\|^2 = (\mathbf{u} - \mathbf{v}) \cdot (\mathbf{u} - \mathbf{v})$$

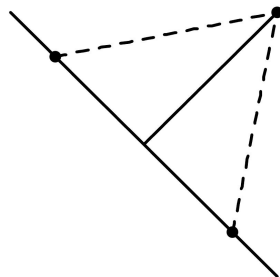
$$= (\mathbf{u}) \cdot (\mathbf{u} - \mathbf{v}) + (-\mathbf{v}) \cdot (\mathbf{u} - \mathbf{v}) =$$

$$= \mathbf{u} \cdot \mathbf{u} - \mathbf{u} \cdot \mathbf{v} + -\mathbf{v} \cdot \mathbf{u} + \mathbf{v} \cdot \mathbf{v}$$

$$= \|\mathbf{u}\|^2 + \|\mathbf{v}\|^2 - 2\mathbf{u} \cdot \mathbf{v}$$

$$\Rightarrow [\text{dist}(\mathbf{u}, \mathbf{v})]^2 = \|\mathbf{u}\|^2 + \|\mathbf{v}\|^2 - 2\mathbf{u} \cdot \mathbf{v}$$

$$\Rightarrow [\text{dist}(\mathbf{u}, -\mathbf{v})]^2 = \|\mathbf{u}\|^2 + \|\mathbf{v}\|^2 + 2\mathbf{u} \cdot \mathbf{v}$$



Since  $[\text{dist}(\mathbf{u}, -\mathbf{v})]^2 = [\text{dist}(\mathbf{u}, \mathbf{v})]^2$ ,  $\mathbf{u} \cdot \mathbf{v} = \text{-----}$ .

## Orthogonal

Two vectors  $\mathbf{u}$  and  $\mathbf{v}$  are said to be **orthogonal** (to each other) if  $\mathbf{u} \cdot \mathbf{v} = 0$ .



# The Pythagorean Theorem

## Theorem (2 The Pythagorean Theorem)

*Two vectors  $\mathbf{u}$  and  $\mathbf{v}$  are orthogonal if and only if*

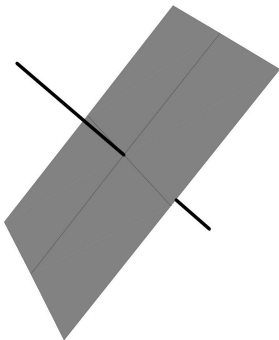
$$\|\mathbf{u} + \mathbf{v}\|^2 = \|\mathbf{u}\|^2 + \|\mathbf{v}\|^2$$



# Orthogonal Complements

## Orthogonal Complements

If a vector  $\mathbf{z}$  is orthogonal to every vector in a subspace  $W$  of  $\mathbf{R}^n$ , then  $\mathbf{z}$  is said to be **orthogonal to  $W$** . The set of vectors  $\mathbf{z}$  that are orthogonal to  $W$  is called the **orthogonal complement** of  $W$  and is denoted by  $W^\perp$  (read as “ $W$  perp”).



# Row, Null and Columns Spaces

## Theorem (3)

Let  $A$  be an  $m \times n$  matrix. Then the orthogonal complement of the row space of  $A$  is the nullspace of  $A$ , and the orthogonal complement of the column space of  $A$  is the nullspace of  $A^T$ :

$$(\text{Row } A)^\perp = \text{Nul } A, \quad (\text{Col } A)^\perp = \text{Nul } A^T.$$

**Why? (See complete proof in the text)** Note that

$$A\mathbf{x} = \begin{bmatrix} \mathbf{r}_1 \cdot \mathbf{x} \\ \mathbf{r}_2 \cdot \mathbf{x} \\ \vdots \\ \mathbf{r}_m \cdot \mathbf{x} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

and so  $\mathbf{x}$  is orthogonal to the row  $A$  since  $\mathbf{x}$  is orthogonal to  $\mathbf{r}_1, \dots, \mathbf{r}_m$ .



# Row, Null and Columns Spaces: Example

## Example

$$\text{Let } A = \begin{bmatrix} 1 & 0 & -1 \\ 2 & 0 & 2 \end{bmatrix}.$$

$$\text{Basis for Nul } A = \left\{ \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\} \text{ and Nul } A \text{ is a plane in } \mathbf{R}^3.$$

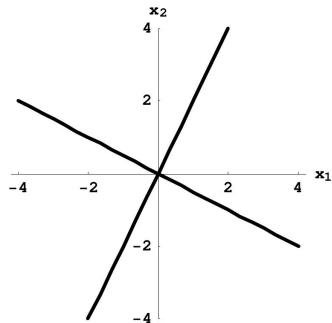
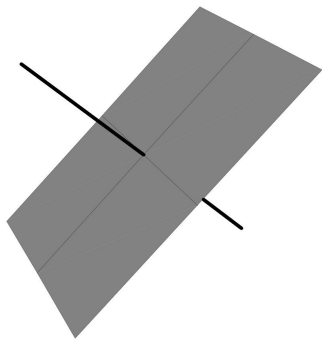
$$\text{Basis for Row } A = \left\{ \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} \right\} \text{ and Row } A \text{ is a line in } \mathbf{R}^3.$$

$$\text{Basis for Col } A = \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right\} \text{ and Col } A \text{ is a line in } \mathbf{R}^2.$$

$$\text{Basis for Nul } A^T = \left\{ \begin{bmatrix} -2 \\ 1 \end{bmatrix} \right\} \text{ and Nul } A^T \text{ is a line in } \mathbf{R}^2.$$



# Row, Null and Columns Spaces: Example (cont.)



Subspaces  $\text{Nul } A$  and  $\text{Row } A$       Subspaces  $\text{Nul } A^T$  and  $\text{Col } A$

