

## ODE

### Sample Midterm 3 Math 3331 (Summer 2014)

July 2, 2014

50 points

1. Find the solution of the initial-value problem

$$\begin{aligned}x' &= -3x \\y' &= -5x + 6y - 4z \\z' &= -5x + 2y\end{aligned}$$

with  $x(0) = -1$ ,  $y(0) = 0$  and  $z(0) = 1$ .

*Solution* In matrix form, the system is

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix}' = \begin{pmatrix} -3 & 0 & 0 \\ -5 & 6 & -4 \\ -5 & 2 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

The eigen-pairs of  $A = \begin{pmatrix} -3 & 0 & 0 \\ -5 & 6 & -4 \\ -5 & 2 & 0 \end{pmatrix}$  are

$$\begin{aligned}\lambda_1 &= 4, & \lambda_2 &= -3, & \lambda_3 &= 2 \\v_1 &= (0, 2, 1)^T, & v_2 &= (1, 1, 1)^T, & v_3 &= (0, 1, 1)^T.\end{aligned}$$

The general solution is

$$\begin{pmatrix} x(t) \\ y(t) \\ z(t) \end{pmatrix} = c_1 e^{4t} \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix} + c_2 e^{-3t} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + c_3 e^{2t} \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$$

If  $x(0) = -1$ ,  $y(0) = 0$  and  $z(0) = 1$ , then

$$\begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} = c_1 \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + c_3 \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$$

We find that  $c_1 = -1$ ,  $c_2 = -1$ , and  $c_3 = 3$ . Hence the solution is

$$\begin{pmatrix} x(t) \\ y(t) \\ z(t) \end{pmatrix} = -e^{4t} \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix} - e^{-3t} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + 3e^{2t} \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} -e^{-3t} \\ -2e^{4t} - e^{-3t} + 3e^{2t} \\ -e^{4t} - e^{-3t} + 3e^{2t} \end{pmatrix}$$

50 points

2. Find the solution of the initial-value problem

$$\begin{aligned}x' &= 6x - 4z \\y' &= 8x - 2y \\z' &= 8x - 2z\end{aligned}$$

with  $x(0) = -2$ ,  $y(0) = -1$  and  $z(0) = 0$ .

*Solution* In matrix form, the system is

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix}' = \begin{pmatrix} 6 & 0 & -4 \\ 8 & -2 & 0 \\ 8 & 0 & -2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

The eigen-pairs of  $A = \begin{pmatrix} 6 & 0 & -4 \\ 8 & -2 & 0 \\ 8 & 0 & -2 \end{pmatrix}$  are

$$\lambda_1 = -2, \quad \lambda_2 = 2 + 4i, \quad \lambda_3 = 2 - 4i$$

$$v_1 = (0, 1, 0)^T, \quad v_2 = (1 + i, 2, 2)^T, \quad v_3 = (1 - i, 2, 2)^T.$$

The general solution is

$$\begin{pmatrix} x(t) \\ y(t) \\ z(t) \end{pmatrix} = c_1 e^{-2t} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + c_2 e^{2t} \begin{pmatrix} \cos 4t - \sin 4t \\ 2 \cos 4t \\ 2 \cos 4t \end{pmatrix} + c_3 e^{2t} \begin{pmatrix} \cos 4t + \sin 4t \\ 2 \sin 4t \\ 2 \sin 4t \end{pmatrix}$$

If  $x(0) = -2$ ,  $y(0) = -1$  and  $z(0) = 0$ , then

$$\begin{pmatrix} -2 \\ -1 \\ 0 \end{pmatrix} = c_1 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix} + c_3 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

We find that  $c_1 = -1$ ,  $c_2 = 0$ , and  $c_3 = -2$ . Hence the solution is

$$\begin{pmatrix} x(t) \\ y(t) \\ z(t) \end{pmatrix} = -e^{-2t} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} - 2e^{2t} \begin{pmatrix} \cos 4t + \sin 4t \\ 2 \sin 4t \\ 2 \sin 4t \end{pmatrix} = \begin{pmatrix} -2e^{2t}(\cos 4t + \sin 4t) \\ -e^{-2t} - 4e^{2t} \sin 4t \\ -4e^{2t} \sin 4t \end{pmatrix}$$

20 points

3. (**BONUS PROBLEM**) Classify the equilibrium point of the system  $y' = Ay$ . Sketch the phase portrait by hand.

$$(1) A = \begin{pmatrix} -16 & 9 \\ -18 & 11 \end{pmatrix} \quad (2) A = \begin{pmatrix} 2 & 1 \\ -10 & -5 \end{pmatrix}$$

*Solution* (1) If

$$A = \begin{pmatrix} -16 & 9 \\ -18 & 11 \end{pmatrix}$$

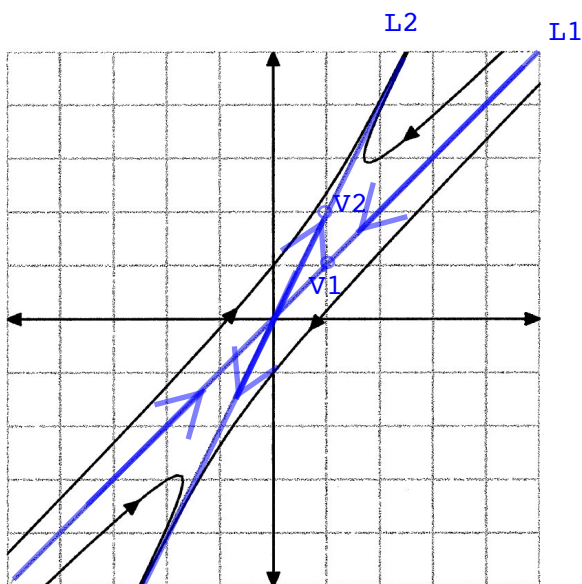
then the trace is  $T = -5$  and the determinant is  $D = -14 < 0$ . Hence, the equilibrium point at the origin is a saddle. The eigen-pairs of  $A = \begin{pmatrix} -16 & 9 \\ -18 & 11 \end{pmatrix}$  are

$$\begin{aligned}\lambda_1 &= -7, & v_1 &= (1, 1)^T, \\ \lambda_2 &= 2, & v_2 &= (1, 2)^T.\end{aligned}$$

The general solution is

$$y(t) = c_1 e^{-7t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + c_2 e^{2t} \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

Solutions approach the halfline generated by  $c_2(1, 2)^T$  as they move forward in time, but they approach the halfline generated by  $c_1(1, 1)^T$  as they move backward in time. A hand sketch follows



(2) If

$$A = \begin{pmatrix} 2 & 1 \\ -10 & -5 \end{pmatrix}$$

then the trace is  $T = -3 < 0$  and the determinant is  $D = 0$ . Thus, this degenerate case lies on the horizontal axis in the trace-determinant plane, separating the saddles from the nodal sinks. The eigen-pairs of  $A = \begin{pmatrix} 2 & 1 \\ -10 & -5 \end{pmatrix}$  are

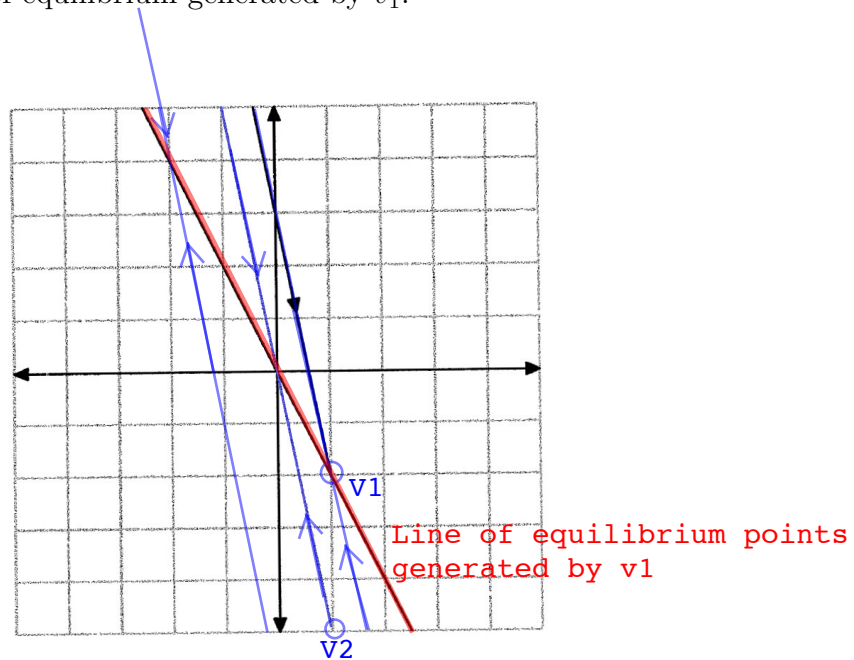
$$\begin{aligned}\lambda_1 &= 0, & v_1 &= (1, -2)^T, \\ \lambda_2 &= -3, & v_2 &= (1, -5)^T.\end{aligned}$$

The general solution is

$$y(t) = c_1 \begin{pmatrix} 1 \\ -2 \end{pmatrix} + c_2 e^{-3t} \begin{pmatrix} 1 \\ -5 \end{pmatrix}$$

Each Solution in this family is the sum of a fixed multiple of  $(1, -2)^T$  and a decaying multiple of  $(1, -5)^T$ . Thus, as  $t \rightarrow \infty$ , solutions move in lines parallel to  $(1, -5)^T$ , decaying into the line of equilibrium generated by  $v_1$ .

A hand sketch follows



Infinitely many half line  
solutions on straight lines  
parallel to line generated by  
 $v_2$

**Eigenvalues and eigenvectors of matrices**

- The eigen-pairs of  $A = \begin{pmatrix} 2 & 1 \\ -10 & -5 \end{pmatrix}$  are

$$\begin{aligned}\lambda_1 &= 0, & v_1 &= (1, -2)^T, \\ \lambda_2 &= -3, & v_2 &= (1, -5)^T.\end{aligned}$$

- The eigen-pairs of  $A = \begin{pmatrix} -16 & 9 \\ -18 & 11 \end{pmatrix}$  are

$$\begin{aligned}\lambda_1 &= -7, & v_1 &= (1, 1)^T, \\ \lambda_2 &= 2, & v_2 &= (1, 2)^T.\end{aligned}$$

- The eigen-pairs of  $A = \begin{pmatrix} 6 & 0 & -4 \\ 8 & -2 & 0 \\ 8 & 0 & -2 \end{pmatrix}$  are

$$\begin{aligned}\lambda_1 &= -2, & v_1 &= (0, 1, 0)^T, \\ \lambda_2 &= 2 + 4i, & v_2 &= (1 + i, 2, 2)^T, \\ \lambda_3 &= 2 - 4i, & v_3 &= (1 - i, 2, 2)^T.\end{aligned}$$

- The eigen-pairs of  $A = \begin{pmatrix} -3 & 0 & 0 \\ -5 & 6 & -4 \\ -5 & 2 & 0 \end{pmatrix}$  are

$$\begin{aligned}\lambda_1 &= 4, & v_1 &= (0, 2, 1)^T, \\ \lambda_2 &= -3, & v_2 &= (1, 1, 1)^T, \\ \lambda_3 &= 2, & v_3 &= (0, 1, 1)^T.\end{aligned}$$