

Math 4377/6308 Advanced Linear Algebra

3.1 Elementary Matrix Operations and Elementary Matrix

Jiwen He

Department of Mathematics, University of Houston

`jiwenhe@math.uh.edu`
`math.uh.edu/~jiwenhe/math4377`



3.1 Elementary Matrix Operations and Elementary Matrix

- Elementary Matrix Operations
- Solving a System by Row Eliminations: Example
- Elementary Matrix
- Multiplication by Elementary Matrices
- Properties of Elementary Operations
- Inverses of Elementary Matrices



Elementary Matrix Operations

Definition (Elementary Matrix Operations)

Elementary row/column operations on an $m \times n$ matrix A :

- ① (*Interchange*) interchanging any two rows/columns
- ② (*Scaling*) multiplying any row/column by nonzero scalar
- ③ (*Replacement*) adding any scalar multiple of a row/column to another row/column

Row Equivalent Matrices

Two matrices where one matrix can be transformed into the other matrix by a sequence of elementary row operations.

Fact about Row Equivalence

If the augmented matrices of two linear systems are row equivalent, then the two systems have the same solution set.



Solving a System by Row Eliminations: Example (cont.)

Example (Row Eliminations to a Diagonal Form)

$$\begin{array}{rclcrcl} x_1 & - & 2x_2 & + & x_3 & = & 0 & \left[\begin{array}{cccc} 1 & -2 & 1 & 0 \\ 0 & 1 & -4 & 4 \\ 0 & 0 & 1 & 3 \end{array} \right] \\ & & x_2 & - & 4x_3 & = & 4 \\ & & & & x_3 & = & 3 \end{array}$$

$$\Downarrow$$

$$\begin{array}{rclcrcl} x_1 & - & 2x_2 & & & = & -3 & \left[\begin{array}{cccc} 1 & -2 & 0 & -3 \\ 0 & 1 & 0 & 16 \\ 0 & 0 & 1 & 3 \end{array} \right] \\ & & x_2 & & & = & 16 \\ & & & x_3 & = & 3 \end{array}$$

$$\Downarrow$$

$$\begin{array}{rclcrcl} x_1 & & & & & = & 29 & \left[\begin{array}{cccc} 1 & 0 & 0 & 29 \\ 0 & 1 & 0 & 16 \\ 0 & 0 & 1 & 3 \end{array} \right] \\ & & x_2 & & & = & 16 \\ & & & x_3 & = & 3 \end{array}$$

Solution: (29, 16, 3)



Elementary Matrix

Definition

An $n \times n$ elementary matrix is obtained by performing an elementary operation on I_n . It is of type 1, 2, or 3, depending on which elementary operation was performed.

Example

$$\text{Let } E_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}, E_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix},$$

$$E_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix} \text{ and } A = \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix}.$$

E_1 , E_2 , and E_3 are elementary matrices. Why?



Multiplication by Elementary Matrices

Observe the following products and describe how these products can be obtained by elementary row operations on A .

$$E_1A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix} = \begin{bmatrix} a & b & c \\ 2d & 2e & 2f \\ g & h & i \end{bmatrix}$$

$$E_2A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix} = \begin{bmatrix} a & b & c \\ g & h & i \\ d & e & f \end{bmatrix}$$

$$E_3A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix} \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix} = \begin{bmatrix} a & b & c \\ d & e & f \\ 3a+g & 3b+h & 3c+i \end{bmatrix}$$

If an elementary row operation is performed on an $m \times n$ matrix A , the resulting matrix can be written as EA , where the $m \times m$ matrix E is created by performing the same row operations on I_m .



Properties of Elementary Operations

Theorem (3.1)

Let $A \in M_{m \times n}(F)$, and B obtained from an elementary row (or column) operation on A . Then there exists an $m \times m$ (or $n \times n$) elementary matrix E s.t. $B = EA$ (or $B = AE$). This E is obtained by performing the same operation on I_m (or I_n). Conversely, for elementary E , then EA (or AE) is obtained by performing the same operation of A as that which produces E from I_m (or I_n).



Example: Row Eliminations to a Triangular Form - Step 2

$$\begin{array}{rclcl}
 x_1 & - & 2x_2 & + & x_3 & = & 0 & & \\
 & & 2x_2 & - & 8x_3 & = & 8 & & \\
 & - & 3x_2 & + & 13x_3 & = & -9 & &
 \end{array}
 \quad
 \begin{bmatrix}
 1 & -2 & 1 & 0 \\
 0 & 2 & -8 & 8 \\
 0 & -3 & 13 & -9
 \end{bmatrix}
 = A_1$$

$$\Downarrow E_2$$

$$\begin{array}{rclcl}
 x_1 & - & 2x_2 & + & x_3 & = & 0 & & \\
 & & x_2 & - & 4x_3 & = & 4 & & \\
 & - & 3x_2 & + & 13x_3 & = & -9 & &
 \end{array}
 \quad
 \begin{bmatrix}
 1 & -2 & 1 & 0 \\
 0 & 1 & -4 & 4 \\
 0 & -3 & 13 & -9
 \end{bmatrix}
 = A_2$$

$$A_2 = E_2 A_1, \quad E_2 = \begin{bmatrix} & & & \\ & & & \\ & & & \end{bmatrix}$$



Example: Row Eliminations to a Triangular Form - Step 3

$$\begin{array}{rclcl}
 x_1 & - & 2x_2 & + & x_3 & = & 0 & & \\
 & & x_2 & - & 4x_3 & = & 4 & & \\
 & - & 3x_2 & + & 13x_3 & = & -9 & &
 \end{array}
 \quad
 \begin{bmatrix}
 1 & -2 & 1 & 0 \\
 0 & 1 & -4 & 4 \\
 0 & -3 & 13 & -9
 \end{bmatrix}
 = A_2$$

$$\Downarrow E_3$$

$$\begin{array}{rclcl}
 x_1 & - & 2x_2 & + & x_3 & = & 0 & & \\
 & & x_2 & - & 4x_3 & = & 4 & & \\
 & & & & x_3 & = & 3 & &
 \end{array}
 \quad
 \begin{bmatrix}
 1 & -2 & 1 & 0 \\
 0 & 1 & -4 & 4 \\
 0 & 0 & 1 & 3
 \end{bmatrix}
 = A_3$$

$$A_3 = E_3 A_2, \quad E_3 = \begin{bmatrix} & & & \\ & & & \\ & & & \end{bmatrix}$$



Example: Row Eliminations to a Diagonal Form - Step 4

$$\begin{array}{rclcrcl} x_1 & - & 2x_2 & + & x_3 & = & 0 & & \\ & & x_2 & - & 4x_3 & = & 4 & & \\ & & & & x_3 & = & 3 & & \end{array} \quad \begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 1 & -4 & 4 \\ 0 & 0 & 1 & 3 \end{bmatrix} = A_3$$

$$\Downarrow E_4$$

$$\begin{array}{rclcrcl} x_1 & - & 2x_2 & & & = & -3 & & \\ & & x_2 & & & = & 16 & & \\ & & & x_3 & & = & 3 & & \end{array} \quad \begin{bmatrix} 1 & -2 & 0 & -3 \\ 0 & 1 & 0 & 16 \\ 0 & 0 & 1 & 3 \end{bmatrix} = A_4$$

$$A_4 = E_4 A_3, \quad E_4 = \begin{bmatrix} & & & \\ & & & \\ & & & \\ & & & \end{bmatrix}$$



Example: Row Eliminations to a Diagonal Form - Step 5

$$\begin{array}{rcl}
 x_1 - 2x_2 & = & -3 \\
 & x_2 & = 16 \\
 & & x_3 = 3
 \end{array}
 \quad
 \begin{bmatrix}
 1 & -2 & 0 & -3 \\
 0 & 1 & 0 & 16 \\
 0 & 0 & 1 & 3
 \end{bmatrix}
 = A_4$$

$$\Downarrow E_5$$

$$\begin{array}{rcl}
 x_1 & = & 29 \\
 & x_2 & = 16 \\
 & & x_3 = 3
 \end{array}
 \quad
 \begin{bmatrix}
 1 & 0 & 0 & 29 \\
 0 & 1 & 0 & 16 \\
 0 & 0 & 1 & 3
 \end{bmatrix}
 = A_5$$

$$A_5 = E_5 A_4, \quad E_5 = \begin{bmatrix} & & & \\ & & & \\ & & & \\ & & & \end{bmatrix}$$



Inverses of Elementary Matrices

Theorem (3.2)

Elementary matrices are invertible, and the inverse is an elementary matrix of the same type.

Elementary matrices are *invertible* because row operations are *invertible*. To determine the inverse of an elementary matrix E , determine the elementary row operation needed to transform E back into I and apply this operation to I to find the inverse.

Example

$$E_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix} \quad E_3^{-1} = \begin{bmatrix} & & \\ & & \\ & & \end{bmatrix}$$



Inverses of Elementary Matrices: Examples

Example

$$E_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad E_1^{-1} = \begin{bmatrix} & & \\ & & \\ & & \end{bmatrix}$$

Example

$$E_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \quad E_2^{-1} = \begin{bmatrix} & & \\ & & \\ & & \end{bmatrix}$$

