

1. a) A breakdown at step  $n$  ( $h_{n+1,n} = 0$ ) simplifies ✓

$$A Q_n = Q_{n+1} \tilde{H}_n$$

i.e.

$$[A] [q_1 | \dots | q_n] = [q_1 | \dots | q_{n+1}] \begin{bmatrix} h_{11} & \dots & h_{1n} \\ h_{21} & \dots & \vdots \\ \vdots & \ddots & \vdots \\ h_{m,n-1} & \dots & h_{mn} \\ h_{n+1,n} \end{bmatrix}$$

to

$$A Q_n = Q_n H_n \quad (\neq)$$

that is

$$[A] [q_1 | \dots | q_n] = [q_1 | \dots | q_n] \begin{bmatrix} h_{11} & \dots & h_{1n} \\ h_{21} & \dots & \vdots \\ \vdots & \ddots & \vdots \\ h_{m,n-1} & \dots & h_{mn} \end{bmatrix}$$

Then, a full  $m \times m$  Hessenberg reduction

$$A = Q H Q^T \quad (\neq \neq)$$

has the bloc upper-triangular structure for  $H$

$$H = \begin{pmatrix} H_n & H_{12} \\ 0 & H_{m-n} \end{pmatrix} \quad (\neq \neq)$$

where

$$H_{m-n} = \begin{pmatrix} h_{n+1,n+1} & \dots & h_{n+1,m} \\ h_{n+2,n+1} & \dots & \vdots \\ \vdots & \ddots & \vdots \\ h_{m,n-1} & \dots & h_{m,n} \end{pmatrix}, \quad H_{12} \in \mathbb{R}^{n \times n}$$

$$1. b) \quad K_n = \langle f_1, \dots, f_n \rangle$$

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It follows from (\*) that

$$\forall i=1, \dots, n-1, \quad A f_i = \sum_{j=1}^{i+1} h_{j,i} f_j \in K_n$$

$$A f_n = \sum_{j=1}^n h_{j,n} f_j \in K_n$$

Therefore

$$A K_n = \langle A f_1, \dots, A f_n \rangle \subseteq K_n$$

1. c) It follows that, from (\*\*),

$$A \underset{\mathbb{Q}}{\sim} H, \quad \text{i.e.,} \quad \Lambda(H) = \Lambda(A)$$

(unitarily similar)

↑      ↗  
set of ews.

from (\*\*\*), i.e.  $H$  being bloc-triangular,

$$\Lambda(H) = \Lambda(H_n) \cup \Lambda(H_{m-n}).$$

Therefore

$$\Lambda(H_n) \subseteq \Lambda(A)$$

i.e.

each ew of  $H_n$  is an ew of  $A$ .

1. d)  $A$  is non-singular. Its inverse has a full 3/4 Hessenberg reduction

$$A^{-1} = Q H^{-1} Q^*$$

where  $H^{-1}$  has the block upper-triangular structure

$$H^{-1} = \begin{pmatrix} H_n^{-1} & \tilde{H}_{12} \\ 0 & H_{m-n}^{-1} \end{pmatrix}, \quad \text{with } \tilde{H}_{12} \in \mathbb{R}^{n \times (m-n)}$$

Then the solution

$$x^\# = A^{-1} b = Q H^{-1} Q^* b$$

Note that  $b = \|b\| f_1$ .

$$Q^* b = \begin{pmatrix} f_1^* \\ \vdots \\ f_m^* \end{pmatrix} \|b\| f_1 = \|b\| \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} = \|b\| e_1 \in \mathbb{R}^m$$

$$\begin{aligned} H^{-1}(Q^* b) &= \|b\| H^{-1} e_1 = \|b\| \cdot \text{first col of } H \\ &= \|b\| \begin{pmatrix} \text{first col of } H_n^{-1} \\ 0 \in \mathbb{R}^{m-n} \end{pmatrix} = \|b\| \begin{pmatrix} H_n^{-1} e_1 \\ 0 \end{pmatrix} \\ &= \|b\| \begin{pmatrix} z \\ 0 \end{pmatrix} \quad \text{with } z = \text{first col of } H_n \\ & \quad = H_n^{-1} e_1 \in \mathbb{R}^n \end{aligned}$$

$$\text{Therefore } x^\# = Q (H^{-1} Q^* b) = \|b\| (Q_n, Q_{m-n}) \begin{pmatrix} z \\ 0 \end{pmatrix}$$

$$= \|b\| Q_n z \in \mathcal{K}_n$$

$$= \|b\| Q_n H_n^{-1} e_1,$$

That is,

the solution  $x$  lies in  $\mathcal{K}_n$ ,  $e_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \in \mathbb{R}^m$ .

1.5) Alternative proof.

For  $\forall x \in K_n = \langle f_1, \dots, f_n \rangle$

we have

$$x = Q_n y \quad \text{with} \quad Q_n = (f_1 | \dots | f_n)$$

Then

$$Ax = A Q_n y = Q_n H_n y \in K_n$$

Therefore  $A K_n \subseteq K_n$

1.5) Alternative proof

For  $\forall x \in A K_n = \langle A f_1 | \dots | A f_n \rangle$

we have

$$x = c_1 A f_1 + \dots + c_n A f_n$$

$$= A Q_n c \quad \text{with} \quad c = (c_1, \dots, c_n)^T$$

$$= Q_n H_n c$$

$$= Q_n y \quad \text{with} \quad y = H_n c$$

$$\in K_n$$

### 1.c) Alternative Proof:

Let  $(\lambda, v)$  be an eigenpair for  $H_n$ , i.e.

$$H_n v = \lambda v.$$

From 1.a).

$$A Q_n = Q_n H_n$$

it follows that

$$A(Q_n v) = Q_n H_n v = \lambda(Q_n v)$$

So  $\lambda$  is an ev of  $A$  with  $Q_n v$  the corresponding ev.

### 1.d) Alternative proof: If $A$ is nonsingular, from 1.c)

$H_n$  is nonsingular.

$$b = \|b\| f_1, \quad f_1 = Q_n e_1$$

The solution

$$\downarrow \qquad \qquad \downarrow$$

$$\begin{aligned} x^* &= A^{-1} b = A^{-1} \|b\| f_1 = \|b\| A^{-1} Q_n e_1 \\ &= \|b\| A^{-1} (Q_n H_n) H_n^{-1} e_1 = \|b\| A^{-1} (A Q_n) H_n^{-1} e_1 \\ &= \|b\| Q_n H_n^{-1} e_1 \in K_n \end{aligned}$$

### 1.d) Alternative proof.

$$\text{Let } x^* = \|b\| Q_n H_n^{-1} e_1 \in K_n$$

It can be shown that  $x^*$  is the solution.

$$\begin{aligned} A x^* &= \|b\| (A Q_n) H_n^{-1} e_1 = \|b\| Q_n H_n H_n^{-1} e_1 \\ &= \|b\| Q_n e_1 = \|b\| f_1 = b. \end{aligned}$$

1.d) Alternative Proof:

Look for  $x^* \in \mathcal{K}_n$  s.t.  $Ax^* = b$ .  
"  $Q_n y$ .

We need to find  $y$  s.t.

$$A Q_n y = b$$

From 1.a).

$$Q_n H_n y = b$$

Since  $b = \|b\| f_1 \in \mathcal{R}(Q_n)$ , we have

$$H_n y = \|b\| e_1$$

From 1.c), if  $A$  is invertible so it is  $H_n$

and  $y = \|b\| H_n^{-1} e_1$

Therefore  $x^* = \|b\| Q_n H_n^{-1} e_1$

is the solution to  $Ax = b$ .

21. The GMRES method at step  $n$  provides a computed solution

$$x_n = Q_n y \in K_n$$

where  $y$  minimizes the residual  $\|Ax_n - b\|$ , i.e.

$$\|A Q_n y - b\| = \text{minimum.}$$

From 1.a), ~~if~~ a breakdown occurs at step  $n$ ,

$$A Q_n = Q_n H_n$$

then

$$\|Q_n H_n y - b\| = \text{minimum}$$

Note that  $b = \|b\| f_1$ , we have

$$\|H_n y - \|b\| e_1\| = \text{minimum} \quad \text{with } e_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \end{pmatrix} \in \mathbb{R}^n$$

which is equivalent to

$$H_n y = \|b\| e_1$$

$$\text{Then } y = \|b\| H_n^{-1} e_1$$

Therefore the computed solution at step  $n$  is

$$x_n = \|b\| Q_n H_n^{-1} e_1$$

which coincides with the exact solution to the system as given in 1.d)

$$x^* = \|b\| Q_n H_n^{-1} e_1$$

## 2/ Alternative Proof

The GMRES method at step  $n$  provides a computed solution  $x_n \in K_n$  s.t.

$$(\ast) \quad \|Ax_n - b\| = \min_{x \in K_n} \|Ax - b\|$$

From 1.d), if a breakdown occurs at step  $n$ , the exact solution  $x^\ast$  to  $Ax = b$  lies in  $K_n$ , i.e.,  $x^\ast \in K_n$ .

It follows from  $(\ast)$  that

$$0 \leq \|Ax_n - b\| \leq \|Ax^\ast - b\| = 0$$

which implies

$$x_n = x^\ast.$$



3. a). First we show that

$$\alpha_n = \frac{r_{n-1}^T r_{n-1}}{\phi_{n-1}^T A \phi_{n-1}}$$

It suffices to show that

$$r_{n-1}^T r_{n-1} = \phi_{n-1}^T r_{n-1}. \quad (*)$$

Note that  $\phi_{n-1} = r_{n-1} + \beta_{n-1} \phi_{n-2}$

$$\begin{aligned} \text{Then } \phi_{n-1}^T r_{n-1} &= (r_{n-1}^T + \beta_{n-1} \phi_{n-2}^T) r_{n-1} \\ &= r_{n-1}^T r_{n-1} + \beta_{n-1} \phi_{n-2}^T r_{n-1} \end{aligned}$$

Since  $r_{n-1} \perp K_{n-1}$  and  $\phi_{n-2} \in K_{n-1}$ ,  
 $\phi_{n-2}^T r_{n-1} = 0$ .

$$\text{Then } \phi_{n-1}^T r_{n-1} = r_{n-1}^T r_{n-1}$$

So the result follows.

Next we show that

$$\beta_n = \frac{r_n^T r_n}{r_{n-1}^T r_{n-1}}$$

Note that  $r_n = r_{n-1} - \alpha_n A \phi_{n-1}$

$$\text{i.e. } -A \phi_{n-1} = \frac{r_n - r_{n-1}}{\alpha_n} \quad (**)$$

$$\begin{aligned} \text{Then } \beta_n &= - \frac{r_n^T (-A \phi_{n-1})}{\phi_{n-1}^T (-A \phi_{n-1})} = - \frac{r_n^T \left( \frac{r_n - r_{n-1}}{\alpha_n} \right)}{\phi_{n-1}^T \left( \frac{r_n - r_{n-1}}{\alpha_n} \right)} \\ &= \frac{r_n^T r_n - r_n^T r_{n-1}}{\phi_{n-1}^T r_{n-1} - \phi_{n-1}^T r_n} \end{aligned}$$

Note that

$$r_n \perp K_n, \quad r_{n-1} \in K_n, \quad r_n^T r_{n-1} = 0$$
$$\varphi_{n-1} \in K_n, \quad r_n^T \varphi_{n-1} = 0$$

And as proved above,  $(*)$ ,

$$\varphi_{n-1}^T r_{n-1} = r_{n-1}^T r_{n-1}$$

We have

$$\beta_n = \frac{r_n^T r_n}{r_{n-1}^T r_{n-1}}$$

3. b).

$$\begin{aligned} \text{RHS} &= -\frac{1}{\alpha_{n+1}} r_{n+1} + \left( \frac{1}{\alpha_{n+1}} + \frac{\beta_n}{\alpha_n} \right) r_n - \frac{\beta_n}{\alpha_n} r_{n-1} \\ &= -\frac{r_{n+1} - r_n}{\alpha_{n+1}} - \beta_n \left( -\frac{r_n - r_{n-1}}{\alpha_n} \right) \end{aligned}$$

It follows from  $(*)$  in 3. a).

$$\begin{aligned} \text{RHS} &= A \varphi_n - \beta_n A \varphi_{n-1} \\ &= A (\varphi_n - \beta_n \varphi_{n-1}) \\ &= A r_n = \text{LHS}. \end{aligned}$$