

# Information Theory with Applications

MATH 6397 – Fall 2008

December 1, 2008

## Homework Set 4, due Th Dec 11, 2008

1. Erasures and additive noise. Let  $X$  be a vector-valued random variable in  $\mathbb{R}^k$  with mean zero and covariance matrix  $C_X = I$ . Assume that  $X$  is encoded by an isometry  $V : \mathbb{R}^k \rightarrow \mathbb{R}^n$ ,  $(VX)_j = \langle X, f_j \rangle$  with an associated  $(n, k)$ -frame  $\{f_j\}_{j=1}^n$ . Now assume that zero-mean noise  $N : \Omega \rightarrow \mathbb{R}^n$  with covariance  $C_N = \sigma^2 I$ ,  $\sigma > 0$ , is added to the encoded vector, and that a one-erasure  $E_l$ ,  $l \in \{1, 2, \dots, n\}$  happens with equal probability each time a vector is sent, where the input vector, the noise and the erasures are independent of each other. Find an expression for the mean-square error

$$\text{MSE}(V) = \frac{1}{n} \sum_{l=1}^n \mathbb{E}[\|V^* E_l(VX(\omega) + N(\omega)) - X(\omega)\|^2]$$

in terms of the frame vectors and determine which choice of  $(n, k)$ -frame gives the smallest mean-square error. You may want to introduce  $\mathbb{E}_1$  and  $\mathbb{E}_2$  as averages with respect to  $X$  and  $N$ .

Hints: By the independence of  $X$  and  $N$  and their vanishing means, if  $A$  and  $B$  are linear maps from the ranges of  $X$  and  $N$  to  $\mathbb{R}^k$ , then  $\mathbb{E}[\langle AX(\omega), BN(\omega) \rangle] = 0$ . Also, recall that for an  $(n, k)$ -frame,  $\sum_{j=1}^n \|f_j\|^2 = k$ .

2. Random coding.
  - (a) Write a Matlab function `V=pfgen(n,k)` which generates the analysis operator  $V$  for a random  $(n, k)$ -frame in the following way: First, choose  $n$  random vectors  $\{f_j\}_{j=1}^n$  in  $\mathbb{R}^k$  with i.i.d. Gaussian

entries of variance one, then compute the frame operator  $S$  which is given by the matrix with entries

$$S_{k,l} = \sum_{j=1}^n \langle e_l, f_j \rangle \langle f_j, e_k \rangle$$

where  $k, l \in \{1, 2, \dots, k\}$  and  $\{e_l\}_{l=1}^k$  is the canonical basis for  $\mathbb{R}^k$ . With probability one,  $S$  will be bounded away from zero, which means we can define vectors  $g_j = S^{-1/2} f_j$  for  $j \in \{1, 2, \dots, n\}$ . These vectors  $\{g_j\}_{j=1}^n$  then form a Parseval frame for  $\mathbb{R}^k$ .

- (b) Evaluate the performance of random Parseval frames generated according to the method above, consisting of  $n \in \{12, 25, 50\}$  vectors in  $\mathbb{R}^6$  with a matlab function `pfmse(n)` that does the following: Generate a random  $(n, 6)$ -frame with `pfgen`, pick 500 zero-mean Gaussian random vectors in  $\mathbb{R}^6$  with covariance  $C_X = I$  as input, and 500 zero-mean Gaussian noise vectors in  $\mathbb{R}^n$  with covariance  $C_N = \frac{1}{100}I$  as noise. You may think of these vectors as  $X(\omega_r)$  and  $N(\omega_r)$ , coming from an outcome  $\omega_r$  indexed by  $r \in \{1, 2, \dots, 500\}$ . Compute an estimate for the mean square error by averaging over random inputs and noise

$$\widehat{\text{MSE}}(V) = \frac{1}{500n} \sum_{r=1}^{500} \sum_{l=1}^n \|V^* E_l(VX(\omega_r) + N(\omega_r)) - X(\omega_r)\|^2$$

for the random frame. Repeat this procedure and average the results over 100 randomly chosen  $(n, 6)$ -frames to get an estimate  $\widehat{\text{MSE}}$  for the expected MSE of a random Parseval frame. Compare the results with the value for the mean-square error of optimal frames from the preceding problem.

Attach your matlab code and the resulting values for the estimated mean-square error.