

Vector Functions; Calculus: (13.1, 13.2)

Given functions $f_1(t)$, $f_2(t)$, $f_3(t)$ defined on some t -interval I .

The vector

$$\begin{aligned} \mathbf{f}(t) &= (f_1(t), f_2(t), f_3(t)) \\ &= f_1(t) \mathbf{i} + f_2(t) \mathbf{j} + f_3(t) \mathbf{k} \end{aligned}$$

is called *vector-valued function* or *vector function*.

Note: Same definition in 2-space and in n -space.

Examples:

1. $\mathbf{f}(t) = (f_1(t), f_2(t), f_3(t))$

$$f_1(t) = 2 + 3t, \quad f_2(t) = -1 + 4t, \quad f_3(t) = 3 - 2t,$$

$$I : -\infty < t < \infty$$

2. $\mathbf{f}(t) = (f_1(t), f_2(t), f_3(t))$

$$f_1(t) = 3 \sin 2t, \quad f_2(t) = 4 \cos 2t, \quad f_3(t) = 0$$

$$I : 0 \leq t \leq 2\pi$$

3. $\mathbf{f}(t) = (f_1(t), f_2(t), f_3(t))$

$$f_1(t) = 4 \cos 2t, \quad f_2(t) = 4 \sin 2t, \quad f_3(t) = 2t$$

$$I : 0 \leq t \leq 4\pi$$

NOTE: as t increases on I the tip of \mathbf{f} traces out an oriented curve C in "space."

Calculus of Vector Functions

I. Limits: Let $c \in I$.

$$\lim_{t \rightarrow c} \mathbf{f}(t) = \mathbf{L} = L_1 \mathbf{i} + L_2 \mathbf{j} + L_3 \mathbf{k}$$

if and only if

$$\lim_{t \rightarrow c} \|\mathbf{f}(t) - \mathbf{L}\| = 0$$

if and only if

$$\lim_{t \rightarrow c} f_1(t) = L_1, \lim_{t \rightarrow c} f_2(t) = L_2, \lim_{t \rightarrow c} f_3(t) = L_3$$

That is: limits are calculated "component-wise."

Example:

$$\mathbf{f}(t) = 2 \cos t \mathbf{i} + 2 \sin t \mathbf{j} + 2t \mathbf{k}$$

$$\lim_{t \rightarrow 2\pi/3} \mathbf{f}(t) = -\mathbf{i} + \sqrt{3} \mathbf{j} + 4\pi/3 \mathbf{k}$$

Arithmetic of limits:

Let f and g be vector functions and let u be a scalar function.

Suppose $f(t) \rightarrow \mathbf{L}$, $g(t) \rightarrow \mathbf{M}$ $u(t) \rightarrow A$.

1. $f(t) + g(t) \rightarrow \mathbf{L} + \mathbf{M}$

2. $f(t) - g(t) \rightarrow \mathbf{L} - \mathbf{M}$

3. $f(t) \cdot g(t) \rightarrow \mathbf{L} \cdot \mathbf{M}$

4. $f(t) \times g(t) \rightarrow \mathbf{L} \times \mathbf{M}$

5. $\alpha f(t) \rightarrow \alpha \mathbf{L}$

6. $u(t)f(t) \rightarrow A\mathbf{L}$

II. Continuity

$\mathbf{f}(t) = f_1(t)\mathbf{i} + f_2(t)\mathbf{j} + f_3(t)\mathbf{k}$ is continuous at $t = c$ if and only if

$$\lim_{t \rightarrow c} \mathbf{f}(t) = \mathbf{f}(c).$$

\mathbf{f} is continuous on an interval I if and only if it is continuous at each point $c \in I$.

\mathbf{f} is a continuous vector function if and only if each of its components

$$f_1, f_2, f_3$$

is a continuous function.

III. Differentiation:

$f(t) = f_1(t)\mathbf{i} + f_2(t)\mathbf{j} + f_3(t)\mathbf{k}$ is differentiable at t if and only if

$$\lim_{h \rightarrow 0} \frac{1}{h} [f(t+h) - f(t)] \text{ exists.}$$

Notation: $f'(t)$

$f(t) = f_1(t)\mathbf{i} + f_2(t)\mathbf{j} + f_3(t)\mathbf{k}$ is differentiable at t if and only if each of f_1 , f_2 , f_3 is differentiable at t and, if so,

$$f'(t) = f'_1(t)\mathbf{i} + f'_2(t)\mathbf{j} + f'_3(t)\mathbf{k}$$

Example:

$$f(t) = e^{2t}\mathbf{i} + \cos 3t\mathbf{j} + \ln t\mathbf{k}$$

$$f'(t) = 2e^{2t}\mathbf{i} - 3\sin 3t\mathbf{j} + \frac{1}{t}\mathbf{k}$$

Integration: $\mathbf{f} = f_1 \mathbf{i} + f_2 \mathbf{j} + f_3 \mathbf{k}$ is integrable if and only if each of f_1, f_2, f_3 is integrable and, if so,

$$\int \mathbf{f}(t) dt = \left(\int f_1(t) dt, \int f_2(t) dt, \int f_3(t) dt \right)$$

Example:

$$\mathbf{f}(t) = e^{2t} \mathbf{i} + \cos 3t \mathbf{j} + \ln t \mathbf{k}$$

$$\int \mathbf{f}(t) dt =$$

$$\frac{1}{2}e^{2t} \mathbf{i} + \frac{1}{3} \sin 3t \mathbf{j} + (t \ln t - t) \mathbf{k} + \mathbf{C}$$

Differentiation formulas: Suppose \mathbf{f} and \mathbf{g} are differentiable vector functions and u is a differentiable scalar function.

$$1. (\mathbf{f} \pm \mathbf{g})'(t) = \mathbf{f}'(t) \pm \mathbf{g}'(t)$$

$$2. (\alpha \mathbf{f})'(t) = \alpha \mathbf{f}'(t) \quad (\alpha \text{ constant})$$

$$3. (u \mathbf{f})'(t) = u(t) \mathbf{f}'(t) + u'(t) \mathbf{f}(t)$$

$$4. (\mathbf{f} \cdot \mathbf{g})'(t) = \mathbf{f}(t) \cdot \mathbf{g}'(t) + \mathbf{g}(t) \cdot \mathbf{f}'(t)$$

$$5. (\mathbf{f} \times \mathbf{g})'(t) = \mathbf{f}(t) \times \mathbf{g}'(t) + \mathbf{f}'(t) \times \mathbf{g}(t)$$

NOTE: the order in 5!!

$$6. [\mathbf{f}(u(t))]' = \mathbf{f}'[u(t)] u'(t) \quad \text{the chain rule}$$

Examples: If

$$\mathbf{f}(t) = 2t^2 \mathbf{i} + (3t + 1) \mathbf{j} + t^3 \mathbf{k},$$

$$\mathbf{g}(t) = \mathbf{i} + t^2 \mathbf{j} + 2t^4 \mathbf{k},$$

$$u(t) = e^{2t},$$

then

- $(\mathbf{f} + \mathbf{g})'(t) = \mathbf{f}'(t) + \mathbf{g}'(t)$

$$= 4t \mathbf{i} + (3 + 2t) \mathbf{j} + (3t^2 + 8t^3) \mathbf{k}$$

- $(\mathbf{f} \cdot \mathbf{g})'(t) = \mathbf{f}(t) \cdot \mathbf{g}'(t) + \mathbf{f}'(t) \cdot \mathbf{g}(t)$

$$= 6t + 9t^2 + 14t^6$$

- $(\mathbf{f}[u(t)])' = \mathbf{f}'[u(t)]u'(t)$

$$= 8e^{4t} \mathbf{i} + 6e^{2t} \mathbf{j} + 6e^{6t} \mathbf{k}$$

- **Important property:**

If \mathbf{f} has constant norm, then

$$\mathbf{f} \perp \mathbf{f}'$$

Proof: Suppose $\|\mathbf{f}(t)\| \equiv C$, constant.

Curves; Tangent Vector, etc. (13.3)

Given

$$x = x(t), \quad y = y(t), \quad z = z(t)$$

differentiable functions on a t -interval I .

Let

$$\mathbf{r}(t) = x(t) \mathbf{i} + y(t) \mathbf{j} + z(t) \mathbf{k}$$

As t ranges over the interval I , the tip of \mathbf{r} traces out a curve \mathcal{C} .

\mathcal{C} is a *differentiable curve* parametrized by \mathbf{r} with parameter t .

\mathcal{C} is an *oriented* curve. The positive direction on I induces an orientation on \mathcal{C} .

Tangent vector:

Choose a point $c \in I$. The vector

$$\mathbf{r}'(c) = x'(c)\mathbf{i} + y'(c)\mathbf{j} + z'(c)\mathbf{k}$$

is a direction vector for the line tangent to \mathcal{C} at the point $P : (x(c), y(c), z(c))$ on \mathcal{C} (provided $\mathbf{r}'(c) \neq \mathbf{0}$).

$\mathbf{r}'(c)$ points in the direction of increasing t .

Tangent line: The line through P with direction vector

$$\mathbf{r}'(c) = x'(c)\mathbf{i} + y'(c)\mathbf{j} + z'(c)\mathbf{k}$$

is tangent to \mathcal{C} at P .

Examples:

1. Find a vector equation for the line tangent to

$$\mathbf{r}(t) = 2 \cos 2t \mathbf{i} + 2 \sin 2t \mathbf{j} + 3t \mathbf{k}$$

at the point where $t = \pi/3$.

2. Find parametric equations for the line tangent to

$$\mathbf{r}(t) = 2t \mathbf{i} + t^2 \mathbf{j} + \frac{1}{3}t^3 \mathbf{k}$$

at the point $(6, 9, 9)$.

Unit tangent vector, principal normal vector:

Given

$$\mathbf{r}(t) = x(t) \mathbf{i} + y(t) \mathbf{j} + z(t) \mathbf{k}$$

Assume $\|\mathbf{r}'(t)\| \neq 0$ for all t .

The vector

$$\mathbf{T}(t) = \frac{\mathbf{r}'(t)}{\|\mathbf{r}'(t)\|}$$

is called the *unit tangent vector*.

\mathbf{T} and \mathbf{r}' have the same direction.

Since \mathbf{T} has constant norm

$$\mathbf{T} \perp \mathbf{T}'$$

(see slide 10)

The unit vector

$$\mathbf{N}(t) = \frac{\mathbf{T}'(t)}{\|\mathbf{T}'(t)\|}$$

is called the *principal normal vector*

Examples:

1. Find the unit tangent vector and the principal normal vector to

$$\mathbf{r}(t) = 2 \cos 2t \mathbf{i} + 2 \sin 2t \mathbf{j} + 3t \mathbf{k}$$

2. Find the unit tangent vector and the principal normal vector to

$$\mathbf{r}(t) = 2t \mathbf{i} + t^2 \mathbf{j} + \frac{1}{3} t^3 \mathbf{k}$$

at the point where $t = 1$.

Let $P : (x_0, y_0, z_0)$ be a point on \mathcal{C} . The line through P with direction vector \mathbf{N} is the *normal line* to \mathcal{C} at P .

Example: Find parametric equations for the normal line to

$$\mathbf{r}(t) = 2 \cos 2t \mathbf{i} + 2 \sin 2t \mathbf{j} + 3t \mathbf{k}$$

at the point where $t = \pi/3$.

Osculating plane:

Fix a point P on the curve \mathcal{C} . The unit tangent and principal normal vectors determine a plane \mathcal{P} called the *osculating plane* at P .

If $P : (x_0, y_0, z_0)$ is a point on \mathcal{C} corresponding to $t = t_0$ and

$$\mathbf{T}(t_0) \times \mathbf{N}(t_0) = M_1 \mathbf{i} + M_2 \mathbf{j} + M_3 \mathbf{k},$$

then

$$M_1(x - x_0) + M_2(y - y_0) + M_3(z - z_0) = 0$$

is an equation for the osculating plane.

Examples:

1. Find an equation for the osculating plane to the curve

$$\mathbf{r}(t) = 2 \cos 2t \mathbf{i} + 2 \sin 2t \mathbf{j} + 3t \mathbf{k}$$

at the point where $t = \pi/3$.

2. Find an equation for the osculating plane to the curve

$$\mathbf{r}(t) = 2t \mathbf{i} + t^2 \mathbf{j} + \frac{1}{3} t^3 \mathbf{k}$$

at the point where $t = 1$.

Arc Length (13.5)

Given

$$x = x(t), \quad y = y(t), \quad z = z(t), \quad I : a \leq t \leq b$$

differentiable functions on I .

Let

$$\mathbf{r}(t) = x(t) \mathbf{i} + y(t) \mathbf{j} + z(t) \mathbf{k}$$

\mathbf{r} determines a differentiable, oriented curve \mathcal{C} . The *length* of \mathcal{C} is given by

$$\mathcal{L} = \int_a^b \sqrt{[x'(t)]^2 + [y'(t)]^2 + [z'(t)]^2} dt$$

Examples:

1. $\mathbf{r}(t) = t^2 \mathbf{i} + 2t \mathbf{j} + \frac{1}{3}t^3 \mathbf{k}, \quad 1 \leq t \leq 4$

2. $\mathbf{r}(t) = 3 \sin t \mathbf{i} + 3 \cos t \mathbf{j} + \frac{4}{3}t^{3/2} \mathbf{k},$
 $0 \leq t \leq 4$

3. $\mathbf{r}(t) = \ln t \mathbf{i} + 2t \mathbf{j} + t^2 \mathbf{k}, \quad 1 \leq t \leq e$

Special Cases:

1: A plane curve, parametric form:

$$x = x(t), \quad y = y(t), \quad a \leq t \leq b :$$

$$\mathcal{L} = \int_a^b \sqrt{[x'(t)]^2 + [y'(t)]^2} dt$$

2. A plane curve, $y = f(x)$ $a \leq x \leq b$:

$$\mathcal{L} = \int_a^b \sqrt{1 + [f'(x)]^2} dx$$

3. A polar curve, $r = g(\theta)$ $\alpha \leq \theta \leq \beta$:

$$\mathcal{L} = \int_\alpha^\beta \sqrt{[g(\theta)]^2 + [g'(\theta)]^2} d\theta$$

Examples:

1. $\mathbf{r}(t) = 2 \cos t \mathbf{i} + 2 \sin t \mathbf{j}, \quad 0 \leq t \leq 2\pi$

2. $\mathbf{r}(t) = 2 \cos 2t \mathbf{i} + 2 \sin 2t \mathbf{j}, \quad 0 \leq t \leq 2\pi$

3. $f(x) = \frac{1}{3}(x^2 + 2)^{3/2}, \quad 0 \leq x \leq 3$

4. $r = 1 + \cos \theta, \quad 0 \leq \theta \leq \pi$

Distance and speed:

$$\mathcal{C} : \mathbf{r}(t) = x(t) \mathbf{i} + y(t) \mathbf{j} + z(t) \mathbf{k}, \quad a \leq t \leq b.$$

The *distance* traveled by an object moving along the curve \mathcal{C} at time t is given by:

$$s(t) = \int_a^t \sqrt{[x'(u)]^2 + [y'(u)]^2 + [z'(u)]^2} du.$$

The rate of change of distance with respect to time is called the *speed*:

$$\frac{ds}{dt} = \sqrt{[x'(t)]^2 + [y'(t)]^2 + [z'(t)]^2}.$$

Curvature:

The *curvature* of a curve is a measure of the rate at which the curve is "curving."

The curvature of \mathcal{C} is the magnitude of the change of the unit tangent vector with respect to arc length.

$$\kappa = \left\| \frac{d\mathbf{T}}{ds} \right\|$$

Special cases – plane curves:

1. $C : y = f(x)$:

$$\kappa = \frac{|f''(t)|}{(1 + [f']^2)^{3/2}}$$

2. $C : x = x(t), \quad y = y(t)$:

$$\kappa = \frac{|x'(t)y''(t) - y'(t)x''(t)|}{([x']^2 + [y']^2)^{3/2}}$$

Examples:

1. $f(x) = mx + b$; a straight line.

2. $x = a \cos t$, $y = a \sin t$; circle, centered at the origin, radius a .

3. $x = 4 \cos t$, $y = 3 \sin t$; an ellipse.

General case:

$$\kappa = \left\| \frac{d\mathbf{T}}{ds} \right\| = \frac{\|d\mathbf{T}/dt\|}{ds/dt}$$

Examples:

1.

$$\mathbf{r}(t) = 2 \cos 2t \mathbf{i} + 2 \sin 2t \mathbf{j} + 3t \mathbf{k}$$

2.

$$\mathbf{r}(t) = (\cos t + t \sin t) \mathbf{i} + (\sin t - t \cos t) \mathbf{j} + \frac{\sqrt{3}}{2} t^2 \mathbf{k}$$

“Mechanics”

Let

$$\mathbf{r}(t) = x(t) \mathbf{i} + y(t) \mathbf{j} + z(t) \mathbf{k}, \quad t \in I$$

denote the position of an object at time t

The object moves along the curve \mathcal{C} .

Velocity: The rate of change of position with respect to time.

$$\mathbf{r}'(t) = \mathbf{v}(t) = x'(t) \mathbf{i} + y'(t) \mathbf{j} + z'(t) \mathbf{k}$$

Speed: The magnitude of velocity.

$$\|\mathbf{r}'(t)\| = \|\mathbf{v}(t)\| = \sqrt{[x'(t)]^2 + [y'(t)]^2 + [z'(t)]^2}$$

NOTE: $\|\mathbf{r}'(t)\| = \frac{ds}{dt}$

Acceleration: The rate of change of velocity with respect to time.

$$\mathbf{a}(t) = \mathbf{r}''(t) = x''(t)\mathbf{i} + y''(t)\mathbf{j} + z''(t)\mathbf{k}$$

Examples: Find the velocity, speed and acceleration of the particle whose position at time t is:

1. $\mathbf{r}(t) = 2t\mathbf{i} + t^2\mathbf{j} + \frac{1}{3}t^3\mathbf{k}$

2.

$$\mathbf{r}(t) = (\cos t + t \sin t)\mathbf{i} + (\sin t - t \cos t)\mathbf{j} + \frac{\sqrt{3}}{2}t^2\mathbf{k}$$

Tangential and normal components of acceleration:

The acceleration vector

$$\mathbf{a}(t) = \mathbf{r}''(t) = x''(t)\mathbf{i} + y''(t)\mathbf{j} + z''(t)\mathbf{k}$$

is a linear combination of the unit tangent and principal normal vectors; i.e., the acceleration vector lies in the osculating plane:

$$\mathbf{a}(t) = a_T \mathbf{T} + a_N \mathbf{N}$$

The coefficients a_T and a_N are called the *tangential* and *normal* components of acceleration.

a_T and a_N are given by:

$$a_T = \frac{d^2s}{dt^2}, \quad a_N = \kappa \left(\frac{ds}{dt} \right)^2$$

Examples:

1. $\mathbf{r}(t) = e^t \cos t \mathbf{i} + e^t \sin t \mathbf{j} + e^t \mathbf{k}$

$$\frac{ds}{dt} = \sqrt{3} e^t, \quad \kappa = \frac{\sqrt{2}}{3} e^{-t}$$

$$a_T = \sqrt{3} e^t, \quad a_N = \sqrt{2} e^t$$

$$\mathbf{a} = \sqrt{3} e^t \mathbf{T} + \sqrt{2} e^t \mathbf{N}$$

2. $\mathbf{r}(t) = 2t \mathbf{i} + t^2 \mathbf{j} + \frac{1}{3}t^3 \mathbf{k}$

Find tangential and normal components at the point where $t = 1$.

$$\frac{ds}{dt} = 3, \quad \kappa = \frac{2}{9}$$

$$a_T = 2, \quad a_N = 2$$

$$\mathbf{a} = 2\mathbf{T} + 2\mathbf{N}$$