

## Solutions, Assignment #7

### Section 5.1

**3.** The set  $V_3$  is a subspace of  $R^3$  since the solution set to any equation  $Ax = 0$  is a space. This is demonstrated by the principle of superposition introduced in Section ???. Also,  $V_3 = V_1$ .

We can show that  $V_3 = V_1$  by row reducing to find the solutions to  $Ax = 0$ :

$$\begin{pmatrix} 1 & 1 & 0 \\ 1 & -1 & 1 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 0 & \frac{1}{2} \\ 0 & 1 & -\frac{1}{2} \end{pmatrix}.$$

So all vectors in  $V_3$  are of the form  $x = s(-\frac{1}{2}, \frac{1}{2}, 1)$ , where  $s \in \mathbb{R}$ . The vector  $x$  is an element of  $V_1$  for each  $s$ .

**5. Answer:**  $W$  is not a subspace of  $V$ .

*SOLUTION* The subset  $W$  is closed neither under addition nor under scalar multiplication. For example, let  $w_1 = (1, 4, 2)$  and  $w_2 = (1, -1, 3)$  be elements of  $W$ . Then,

$$w_1 + w_2 = (1, 4, 2) + (1, -1, 3) = (2, 3, 5)$$

which is not an element of  $W$ .

**6. Answer:**  $W$  is not a subspace of  $V$ .

*SOLUTION* The subset  $W$  is closed neither under addition nor under scalar multiplication. For example, let  $w_1 = (3, -2)$  and  $w_2 = (0, 1)$  be elements of  $W$ . Then,

$$w_1 + w_2 = (3, -2) + (0, 1) = (3, -3).$$

The sum of the elements  $3 - 3 = 0 \neq 1$ .

**7.**  $W$  is a subspace of  $V$ , since  $W$  is closed under addition and scalar multiplication.

**8.**  $W$  is a subspace of  $V$ , since  $W$  is closed under addition and scalar multiplication.

**9.**  $W$  is a subspace of  $V$ , since  $W$  is closed under addition and scalar multiplication.

**10. Answer:**  $W$  is not a subspace of  $V$ .

*SOLUTION* The subset  $W$  is closed neither under addition nor under scalar multiplication. For example, let  $w_1(t) = t$  and let  $w_2(t) = t^2$ .

$$(w_1 + w_2)(1) = w_1(1) + w_2(1) = 1 + 1 = 2,$$

so  $(w_1 + w_2)(t)$  is not an element of  $W$ .

**11. Answer:** The set  $S$  is not a subspace.

*SOLUTION* The set  $S$  is closed under addition but not under scalar multiplication. To demonstrate, let  $x = (1, 4, 2)$  be an element of  $S$ . Then

$$-2x = -2(1, 4, 2) = (-2, -8, -4)$$

which is not an element of  $S$ .

**13.** The set  $S$  is a subspace, since it is closed under addition and scalar multiplication.

## Section 5.2

**2. Answer:** The subspace of solutions can be spanned by the vectors  $(1, 1, 0)^t$  and  $(-3, 0, 1)^t$ .

*SOLUTION* All solutions to  $x - y + 3z = 0$  can be written in the form

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} y - 3z \\ y \\ z \end{pmatrix} = y \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + z \begin{pmatrix} -3 \\ 0 \\ 1 \end{pmatrix}.$$

**5. Answer:** The subspace of solutions is spanned by the vectors

$$(-2, 1, 0, 0, 0)^t \quad \text{and} \quad (-1, 0, -4, 1, 0)^t.$$

*SOLUTION* Let  $x = (x_1, \dots, x_5)$  be a solution to  $Ax = 0$ . All solutions to this equation have the form

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix} = \begin{pmatrix} -2x_2 - x_4 \\ x_2 \\ -4x_4 \\ x_4 \\ 0 \end{pmatrix} = x_2 \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} -1 \\ 0 \\ -4 \\ 1 \\ 0 \end{pmatrix}.$$

**7. Answer:** The subspace of solutions to  $Ax = 0$  is spanned by the vector  $(-2, -1, 1)^t$ .

*SOLUTION* Let  $x = (x_1, x_2, x_3)$  be a solution to  $Ax = 0$ . All solutions to this equation have the form

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} -2x_3 \\ -x_3 \\ x_3 \end{pmatrix} = x_3 \begin{pmatrix} -2 \\ -1 \\ 1 \end{pmatrix}.$$

**9. Answer:** The matrix  $A$  whose subspace of solutions in  $\mathbb{R}^4$  is the span of  $v_1$  and  $v_2$  is

$$A = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{pmatrix}.$$

*SOLUTION* Note that all vectors  $x$  in the spanning set of  $v_1$  and  $v_2$  are of the form:

$$x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = a \begin{pmatrix} 1 \\ -1 \\ 0 \\ 0 \end{pmatrix} + b \begin{pmatrix} 0 \\ 0 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} a \\ -a \\ b \\ -b \end{pmatrix}.$$

Therefore,  $x_1 = -x_2$  and  $x_3 = -x_4$ . So,

$$\begin{aligned} x_1 + x_2 &= 0 \\ x_3 + x_4 &= 0. \end{aligned}$$

The matrix of this system is  $A$ .

**11. Answer:** The vector  $(2, 20, 0)^t$  is in the span of  $w_1$  and  $w_2$ . Specifically,  $v = -4w_1 + 6w_2$ .

*SOLUTION* Note that, for some real numbers  $a$  and  $b$ ,

$$(2, 20, 0)^t = aw_1 + bw_2 = a(1, 1, 3)^t + b(1, 4, 2)^t$$

if  $v$  is in the span of  $w_1$  and  $w_2$ . This corresponds to the linear system

$$\begin{aligned} a + b &= 2 \\ a + 4b &= 20 \\ 3a + 2b &= 0 \end{aligned}$$

To find  $a$  and  $b$ , row reduce the augmented matrix of the system:

$$\left( \begin{array}{cc|c} 1 & 1 & 2 \\ 1 & 4 & 20 \\ 3 & 2 & 0 \end{array} \right) \rightarrow \left( \begin{array}{cc|c} 1 & 0 & -4 \\ 0 & 1 & 6 \\ 0 & 0 & 0 \end{array} \right).$$

The system is consistent;  $a = -4$  and  $b = 6$ .

**12. Answer:** The function  $y(t) = 1 - t^2$  is an element of  $W$  and the set  $\{y(t), x_2(t)\}$  is a spanning set for  $W$ .

*SOLUTION* The space  $W$  equals  $\text{span}\{x_1(t), x_2(t)\}$  where  $x_1(t) = 1$  and  $x_2(t) = t^2$ . To show that  $y(t)$  is an element of  $W$ , let  $a = 1$  and  $b = -1$ , and compute

$$ax_1(t) + bx_2(t) = x_1(t) - x_2(t) = 1 - t^2 = y(t).$$

To show that  $\{y(t), x_2(t)\}$  is a spanning set for  $W$ , rewrite every linear combination of  $x_1(t)$  and  $x_2(t)$  in terms of  $y(t)$  and  $x_2(t)$ , as follows:

$$ax_1(t) + bx_2(t) = a + bt^2 = a(1 - t^2) + (a + b)t^2 = ay(t) + (a + b)x_2(t).$$

**13.** The function  $y(t) = t^4$  is not in  $W$ .

**14.** The function  $y(t) = \sin(t)$  is not in  $W$ .

**15. Answer:** The function  $y(t) = 0.5t^2$  is an element of  $W$ , but the set  $\{y(t), x_2(t)\}$  does not span  $W$ .

*SOLUTION* When  $a = 0$  and  $b = 0.5$ ,

$$ax_1(t) + bx_2(t) = 0.5x_2(t) = 0.5t^2 = y(t).$$

In this case, there exist functions in  $W$  that are not in  $\text{span}\{y(t), x_2(t)\}$ . For example, the function  $x_1(t) = 1$  cannot be written as a linear combination of  $x_2(t)$  and  $y(t)$ .

### Section 5.3

**1.** Type `null(A)` in MATLAB to find that the set of solutions to  $Ax = 0$  is spanned by the vectors

$$\begin{pmatrix} 0.3225 \\ 0.8931 \\ -0.0992 \\ 0.2977 \end{pmatrix} \quad \text{and} \quad \begin{pmatrix} 0 \\ -0.1961 \\ 0.5883 \\ 0.7845 \end{pmatrix}.$$

**2. Answer:** The solution to  $Ax = 0$  is the vector  $(0, 0)$ .

*SOLUTION* This can be demonstrated by typing `null(A)` in MATLAB, which yields

ans =

Empty matrix: 2-by-0

5. **Answer:** The solution set of  $Bx = 0$  is

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} -x_3 + \frac{3}{4}x_4 \\ -3x_3 + 2x_4 \\ x_3 \\ x_4 \end{pmatrix} = x_3 \begin{pmatrix} -1 \\ -3 \\ 1 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} \frac{3}{4} \\ 2 \\ 0 \\ 1 \end{pmatrix}.$$

*SOLUTION* Row reduce  $B$ :

$$\begin{pmatrix} -4 & 0 & 4 & 3 \\ -4 & 1 & -1 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 1 & -\frac{3}{4} \\ 0 & 1 & 3 & -2 \end{pmatrix}.$$

The solution obtained by row reduction is not the same as the one obtained using `null`, but the solution vectors are linear combinations of the MATLAB solution vectors, so the answers are equivalent. By row reducing the matrix `[null(B) x]`, where  $x = (-1, -3, 1, 0)$ , we find that

$$\begin{pmatrix} -1 \\ -3 \\ 1 \\ 0 \end{pmatrix} = -3.1009 \begin{pmatrix} 0.3225 \\ 0.8931 \\ -0.0992 \\ 0.2977 \end{pmatrix} + 1.1767 \begin{pmatrix} 0 \\ -0.1961 \\ 0.5883 \\ 0.7845 \end{pmatrix}.$$

By row reducing the matrix `[null(B) y]` where  $y = (\frac{3}{4}, 2, 0, 1)$  we find that:

$$\begin{pmatrix} \frac{3}{4} \\ 2 \\ 0 \\ 1 \end{pmatrix} = 2.3257 \begin{pmatrix} 0.3225 \\ 0.8931 \\ -0.0992 \\ 0.2977 \end{pmatrix} + 0.3922 \begin{pmatrix} 0 \\ -0.1961 \\ 0.5883 \\ 0.7845 \end{pmatrix}.$$