Math 3331 Differential Equations

4.4 Harmonic Motion

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4.4 Harmonic Motion

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- Qualitative Features of Harmonic Motion
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 - Critically damped Case
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Harmonic Motion: Mass-Spring System

Mass-spring system:

$$my'' + \mu y' + ky = 0$$

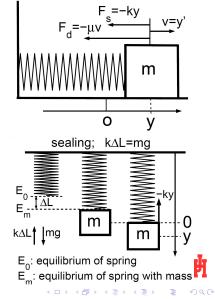
m: mass (kq)

 μ : damping constant (kq/s)

k: spring constant (kg/s^2)

y: deviation of mass position from equilibrium position (m)

y': velocity (m/s)



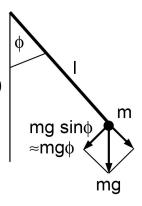
Pendulum for small ϕ :

$$\phi'' + (\mu/m)\phi' + (g/l)\phi = 0$$

 ϕ : angle (no unit)

 $g: 9.8 \, m/s^2$

l: length (m)







Harmonic Motion: RLC-Circuit

RLC-circuit:

$$LQ'' + RQ' + Q/C = 0$$

Q: charge (C)

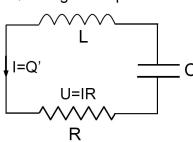
I: current Q'(A)

L: inductivity (H)

R: resistor (Ω)

C: capacity (F)

Q: charge at capacitor







Classification of Harmonic Motion: Mass-Spring System

Mass-Spring System

DE:

$$y'' + \frac{\mu}{m}y' + \frac{k}{m}y = 0,$$

$$m > 0, \quad k > 0, \quad \mu \ge 0$$

Characteristic Eqn:

$$\lambda^2 + \frac{\mu}{m}\lambda + \frac{k}{m} = 0$$

Roots:

$$\lambda_{1,2} = -\frac{\mu}{2m} \pm \frac{1}{2m} \sqrt{\mu^2 - 4km}$$

Classification

Undamped Case:

$$\mu = 0$$

Underdamped Case:

$$0 < \mu^2 < 4km$$

Critically damped Case:

$$\mu^2 = 4km$$

Overdamped Case:

$$\mu^2 > 4km$$

Undamped Case: $\mu = 0$

$$\lambda = \pm i\omega_0$$

$$\omega_0 = \sqrt{k/m}$$

$$y(t) = c_1 \cos(\omega_0 t)$$

$$+c_2 \sin(\omega_0 t)$$

- oscillation
- phase portrait: center
- clockwise direction of rotation





Mass-Spring System: Underdamped Case $(0 < \mu^2 < 4km)$

Underdamped Case: $0 < \mu^2 < 4km$

$$\lambda_{1,2} = -\alpha \pm i\omega$$

$$\alpha = \mu/2m$$

$$\omega = \sqrt{4km - \mu^2/(2m)}$$

$$= \sqrt{\omega_0^2 - \mu^2/4m^2}$$

$$y(t) = e^{-\alpha t}(c_1 \cos(\omega t) + c_2 \sin(\omega t))$$

- damped oscillation
- phase portrait: spiral sink
- clockwise direction of rotation



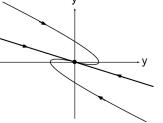


Mass-Spring System: Critically damped Case ($\mu^2 = 4km$)

Critically Damped Case: $\mu^2 = 4km$

$$\lambda_1 = \lambda_2 = -\mu/(2m)$$
$$y(t) = e^{\lambda_1 t} (c_1 + c_2 t)$$

 phase portrait: degenerate nodal sink



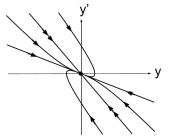




Overdamped Case: $\mu^2 > 4km$

$$\lambda_1 < \lambda_2 < 0$$
$$y(t) = c_1 e^{\lambda_1 t} + c_2 e^{\lambda_2 t}$$

- phase portrait: nodal sink
- both eigenlines: negative slopes







Harmonic Motion: Undamped Case

Undamped Case:

$$y(t) = c_1 \cos(\omega_0 t) + c_2 \sin(\omega_0 t)$$

$$= A[d_1 \cos(\omega_0 t) + d_2 \sin(\omega_0 t)]$$
where
$$\begin{cases} A = \sqrt{c_1^2 + c_2^2} \\ d_1 = c_1/A, \ d_2 = c_2/A \end{cases}$$
Since $d_1^2 + d_2^2 = 1$ we can define ϕ by
$$d_1 = \cos \phi, \ d_2 = \sin \phi$$

$$\Rightarrow d_2/d_1 = c_2/c_1 = \tan \phi$$

$$y(t) = A[\cos \phi \cos(\omega_0 t) + \sin \phi \sin(\omega_0 t)]$$

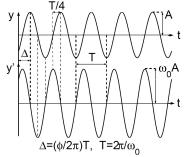
$$= A \cos(\omega_0 t - \phi)$$

$$y'(t) = -\omega_0 A \sin(\omega_0 t - \phi)$$

A: amplitude

 ϕ : **phase angle**, choose $-\pi < \phi < \pi$

$$\phi = \begin{cases} \arctan(c_2/c_1) & \text{if } c_1 > 0 \\ \arctan(c_2/c_1) + \pi & \text{if } c_1 < 0, c_2 \geq 0 \\ \arctan(c_2/c_1) - \pi & \text{if } c_1 < 0, c_2 < 0 \\ \pi/2 & \text{if } c_1 = 0, c_2 > 0 \\ -\pi/2 & \text{if } c_1 = 0, c_2 < 0 \end{cases}$$





Harmonic Motion: Underdamped Case

Underdamped Case:

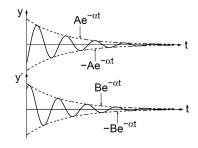
$$y(t) = e^{-\alpha t}[c_1 \cos(\omega t) + c_2 \sin(\omega t)]$$

$$= e^{-\alpha t}A\cos(\omega t - \phi)$$

$$y'(t) = e^{-\alpha t}[(\omega c_2 - \alpha c_1)\cos(\omega t) - (\omega c_1 + \alpha c_2)\sin(\omega t)]$$

$$= e^{-\alpha t}B\cos(\omega t - \psi)$$

$$\pm Ae^{-\alpha t}, \pm Be^{-\alpha t}$$
: envelopes of damped oscillations



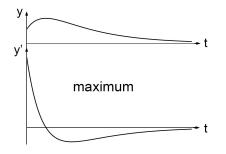


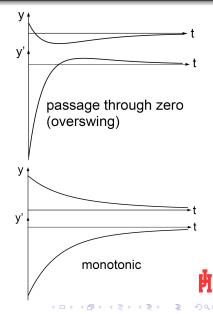


Harmonic Motion: Critically and Overdamped Cases

Critically and Overdamped Cases:

- ullet If y(0) and y'(0) have equal signs, then
 - -y(t) attains maximum or minimum
 - y'(t) crosses zero
- If y(0) and y'(0) have opposite signs, then y(t)
 - crosses zero if |y'(0)/y(0)| is large
 - is monotonic if |y'(0)/y(0)| is small





Exercise 4.4.11

Ex. 4.4.11: Given an undamped mass-spring system with $m=0.2\,kg$, $k=5\,kg/s^2$, $y(0)=0.5\,m$, y'(0)=0, find amplitude, frequency, phase of motion.

Natural frequency: $\omega_0 = \sqrt{5/0.2} = 5/s \Rightarrow$

$$y(t) = c_1 \cos 5t + c_2 \sin 5t, \ y'(t) = -5c_1 \sin 5t + 5c_2 \cos 5t$$

IC:
$$y(0) = c_1 = 0.5$$
, $y'(0) = 5c_2 = 0 \Rightarrow y(t) = 0.5 \cos 5t$
 \Rightarrow amplitude: $A = 0.5 m$, phase: $\phi = 0$





Exercise 4.4.22

Ex. 4.4.22: A mass-spring system with $m=0.1\,kg$, $k=9.8\,kg/s^2$ is placed in a viscous medium with friction force $0.3\,N$ if $v=0.2\,m/s$. Initial data: $y(0)=0.1\,m$, y'(0)=0. Find amplitude, frequency, and phase of motion.

Friction coefficient:
$$F_d = \mu v \Rightarrow 0.3 = \mu 0.2 \Rightarrow \mu = 1.5 \, kg/s$$
.

ODE:
$$0.1y'' + 1.5y' + 9.8y = 0 \Rightarrow y'' + 15y' + 98y = 0 \Rightarrow$$

 $p(\lambda) = \lambda^2 + 15\lambda + 98 = (\lambda + 7.5)^2 + 41.75 \Rightarrow \lambda = -7.5 \pm i\sqrt{41.75} \approx -7.5 \pm 6.461i$
 \Rightarrow Damped motion with frequency $\omega \approx 6.461/s$ of harmonic part \Rightarrow
 $y(t) = e^{-7.5t}(c_1 \cos \omega t + c_2 \sin \omega t)$
 $y'(t) = e^{-7.5t}[(\omega c_2 - 7.5c_1) \cos \omega t - (\omega c_1 + 7.5c_2) \sin \omega t]$
IC: $y(0) = c_1 = 0.1$, $y'(0) = \omega c_2 - 7.5c_1 = 0 \Rightarrow c_2 = 7.5c_1/\omega \approx 0.116$

IC:
$$y(0) = c_1 = 0.1, \ y'(0) = \omega c_2 - 7.5c_1 = 0 \Rightarrow c_2 = 7.5c_1/\omega \approx 0.116$$

 $\Rightarrow y(t) = e^{-7.5t}(0.1\cos\omega t + 0.116\sin\omega t)$





Exercise 4.4.22 (cont.)

Amplitude of harmonic part: $A_0 \approx \sqrt{0.1^2 + 0.116^2} \approx 0.153$. Since $c_1, c_2 > 0$ \Rightarrow phase angle $\phi = \arctan(c_2/c_1) \approx \arctan(1.16) \approx 0.859$ $\Rightarrow u(t) = 0.153e^{-7.5t}\cos(6.461t - 0.859)$

 \Rightarrow amplitude: $A(t) = 0.153e^{-7.5t} m$, frequency: $\omega = 6.461/s$, phase: $\phi = 0.859$



