## **Engineering Mathematics**

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Mathematics 3321



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## Section 6.2 Homogeneous Systems

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We will be concerned with systems of the form

$$\begin{aligned} x_1'(t) &= A_{11}(t)x_1(t) + A_{12}(t)x_2(t) + \dots + A_{1n}(t)x_n(t) \\ x_2'(t) &= A_{21}(t)x_1(t) + A_{22}(t)x_2(t) + \dots + A_{2n}(t)x_n(t) \\ &\vdots \\ x_n'(t) &= A_{n1}(t)x_1(t) + A_{n2}(t)x_2(t) + \dots + A_{nn}(t)x_n(t) \end{aligned}$$

for all t in an interval J. Using vector-matrix notation this becomes

$$X' = AX$$
 or  $X' - AX = \mathbf{0}$ 

where A is the coefficient matrix

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$$A = \begin{pmatrix} A_{11} & A_{12} & \cdots & A_{1n} \\ A_{21} & A_{22} & \cdots & A_{2n} \\ \vdots & \vdots & & \vdots \\ A_{n1} & A_{n2} & \cdots & A_{nn} \end{pmatrix}$$
$$X = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}, \text{ and } X' = \begin{pmatrix} x'_1 \\ x'_2 \\ \vdots \\ x'_n \end{pmatrix}.$$

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The uniqueness and existence theorem for the homogeneous system is as follows.

**Theorem.** Suppose that J is an interval,  $t_0$  is a number in J, E is an *n*-dimensional constant column vector, and A is an  $n \times n$  matrix of continuous functions defined on J. There is a unique *n*-dimensional column vector function X such that

$$X' = AX$$
 on  $J$  and  $X(t_0) = E$ .

Theorem. Every linear combination of solutions to

$$X' = AX$$

is also a solution.  
**Proof.** If 
$$X'_i = AX_i$$
 for  $i = 1, ..., m$  then  
 $(c_1X_1 + c_2X_2 + \dots + c_mX_m)' = c_1X'_1 + c_2X'_2 + \dots + c_mX'_m = c_1AX_1 + c_2AX_2 + \dots + c_mAX_m = A(c_1X_1 + c_2X_2 + \dots + c_mX_m)$ 

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**Definition.** Suppose that  $X_j$  is an *n*-dimensional column vector valued function defined on an interval *j* for j = 1, ..., m. Saying that the list of functions  $(X_1, X_2, ..., X_m)$  is linearly independent over *J* means that if each of  $c_1, c_2, ..., c_m$  is a constant and

$$c_1X_1(t)+c_2X_2(t)+\cdots+c_mX_m(t)={f 0}$$
 for all  $t$  in  $J$ 

then

$$c_1=c_2=\cdots=c_m=0.$$

Saying that  $(X_1, X_2, ..., X_m)$  is linearly dependent over J means that it is not linearly independent.

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**Note.** A list of vector valued functions  $(X_1, X_2, ..., X_m)$  is linearly dependent over J if and only it there is a list of scalars  $(c_1, ..., c_m)$  at least one of which is not zero such that

$$c_1X_1(t) + c_2X_2(t) + \cdots + c_mX_m(t) = \mathbf{0}$$
 for all  $t$  in  $J$ 

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**Definition.** Suppose that  $(X_1, X_2, ..., X_n)$  is a list of *n n*-dimensional column vector valued functions. Their Wronski matrix

$$M_W[X_1, X_2, \ldots, X_n]$$

is the  $n \times n$  matrix of function whose *j*-th column is  $X_j$  for j = 1, 2, ..., n, and their Wronskian

$$W[X_1, X_2, \ldots, X_n]$$

is the determinant of their Wronski matrix. Note that there are **no derivatives** used in the Wronski matrix or the Wronskian.

Example. If

$$X_1(t)=\left(egin{array}{c} e^t\ \sin t\end{array}
ight)$$
 and  $X_2(t)=\left(egin{array}{c} t^2\ \cos t\end{array}
ight)$ 

then

$$M_W[X_1, X_2](t) = \begin{pmatrix} e^t & t^2 \\ \sin t & \cos t \end{pmatrix}$$
 and  $W[X_1, X_2](t) = e^t \cos t - t^2 \sin t$ .

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**Theorem.** (First Wronskian Test) If  $W[X_1, X_2, ..., X_n](t_0) \neq 0$  for some  $t_0$  in J, then  $(X_1, X_2, ..., X_n)$  is linearly independent over J.

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**Theorem.** (Second Wronskian Test) If  $X'_j = AX_j$  for j = 1, ..., n and  $W[X_1, X_2, ..., X_n](t_0) = 0$  for some  $t_0$  in J, then  $(X_1, X_2, ..., X_n)$  is linearly dependent over J

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**Definition.** Suppose that A is  $n \times n$ . A **fundamental list** (or set) for X' = AX is a linearly independent list of *n n*-dimensional column vector valued functions  $(X_1, X_2, ..., X_n)$  such that  $X'_i = AX_j$  for j = 1, ..., n.

**Theorem.** (All Solutions to X' = AX). Suppose that A is an  $n \times n$  matrix of continuous functions defined on an interval J and  $(X_1, X_2, \ldots, X_n)$  is a fundamental list for X' = AX. It follows that X is a solution to X' = AX if and only if

$$X=c_1X_1+c_2X_2+\cdots+c_nX_n.$$

for some list of scalars  $c_1, c_2, \ldots, c_n$ . In the text, this last expression is called the **general solution** to X' = AX.

**Definition.** When A is  $n \times n$ , a **fundamental matrix** for X' = AX is an  $n \times n$  matrix of functions whose columns form a fundamental list for X' = AX.

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**Note.** Multiplying a matrix on the right by a column vector of the correct dimension gives a linear combination of the columns of the matrix. Thus we have the following alternate way to describe all solutions to X' = AX. Suppose that A is an  $n \times n$  matrix of continuous functions defined on an interval J and  $\Phi$  is a fundamental matrix for X' = AX. It follows that X is a solution to X' = AX if and only if

$$X = \Phi C$$

for some n-dimensional constant column vector C.

**Note.** (Initial Value Problems) Suppose that a fundamental list  $(X_1, X_2, \ldots, X_n)$  is known for the equation X' = AX on J, E is an *n*-dimensional constant column vector, and  $t_0$  is a number in J. The solution X to the initial value problem

$$X' = AX$$
 on  $J$  and  $X(t_0) = E$ 

is given by

$$X = c_1 X_1 + c_2 X_2 + \cdots + c_n X_n$$

where the coefficients  $(c_1, c_2, \ldots, c_n)$  are determined by

$$c_1X_1(t_0) + c_2X_2(t_0) + \cdots + c_nX_n(t_0) = E.$$

This is equivalent to

$$\Phi(t_0) \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{pmatrix} = E$$

where  $\Phi$  is the fundamental matrix whose columns are  $X_1, X_2, \ldots, X_n$ . Fundamental matrices are always invertible so

$$\begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{pmatrix} = \Phi^{-1}(t_0)E.$$

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In term of  $\Phi$ , the solution to the initial value problem

$$X' = AX$$
 on  $J$  and  $X(t_0) = E$ 

is given by

$$X(t) = \Phi(t)\Phi^{-1}(t_0)E.$$

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Example. Consider the system

$$X' = AX$$
 on  $(0, \infty)$ 

where

$$A(t) = \left(\begin{array}{cc} 0 & 1 \\ 3/t^2 & 1/t \end{array}\right).$$

Let

$$X_1(t)=\left(egin{array}{c}t^3\3t^2\end{array}
ight)$$
 and  $X_2(t)=\left(egin{array}{c}t^{-1}\-t^{-2}\end{array}
ight)$ 

Then

$$X_1'(t) = \begin{pmatrix} 3t^2 \\ 6t \end{pmatrix} = A(t)X_1(t) \text{ and } X_2'(t) = \begin{pmatrix} -t^{-2} \\ 2t^{-3} \end{pmatrix} = A(t)X_2(t)$$

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$$W[X_1, X_2](t) = \det \left( egin{array}{cc} t^3 & t^{-1} \ 3t^2 & -t^{-2} \end{array} 
ight) = -4t ext{ so } W[X_1, X_2](1) = -4 
eq 0$$

Thus  $(X_1, X_2)$  is a fundamental pair for X' = AX and X is a solution if and only if

$$X(t) = c_1 X_1(t) + c_2 X_2(t) = c_1 \left( egin{array}{c} t^3 \ 3t^2 \end{array} 
ight) + c_2 \left( egin{array}{c} -t^{-2} \ 2t^{-3} \end{array} 
ight)$$

for some pair of numbers  $c_1$  and  $c_2$ .

The fundamental matrix formed by  $(X_1, X_2)$  is  $\Phi$  where

$$\Phi(t)=\left(egin{array}{cc} t^3 & t^{-1}\ 3t^2 & -t^{-2} \end{array}
ight)$$

Note that

So

$$\Phi^{-1}(t) = \frac{1}{-4t} \begin{pmatrix} -t^{-2} & -t^{-1} \\ -3t^2 & t^3 \end{pmatrix} = \begin{pmatrix} 1/4t^3 & 1/4t^2 \\ 3t/4 & -t^2/4 \end{pmatrix}$$

$$\Phi^{-1}(1) = \left( egin{array}{cc} 1/4 & 1/4 \ 3/4 & -1/4 \end{array} 
ight).$$

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The solution to the initial value problem

$$X' = AX$$
 and  $X(1) = \left(egin{array}{c} 1 \ -2 \end{array}
ight)$ 

is given by

$$\begin{aligned} X(t) &= \Phi(t)\Phi^{-1}(1)\begin{pmatrix}1\\-2\end{pmatrix} \\ &= \begin{pmatrix}t^3 & t^{-1}\\3t^2 & -t^{-2}\end{pmatrix}\begin{pmatrix}1/4 & 1/4\\3/4 & -1/4\end{pmatrix}\begin{pmatrix}1\\-2\end{pmatrix} \\ &= \begin{pmatrix}5/4t - t^3/4\\-5/4t^2 - 3t^2/4\end{pmatrix}. \end{aligned}$$

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Additional Examples. See the text and the material that is posted online.

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Suggested Problems. Do the odd numbered problems for Section 6.2.

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