Introduction 000000 Non-uniform examples

Unique equilibrium states

Large deviations

▲ロト ▲帰 ト ▲ ヨ ト ▲ ヨ ト ・ ヨ ・ の Q ()

Non-uniform specification properties and large deviations

Vaughn Climenhaga University of Houston

March 20, 2013

Joint work with Daniel J. Thompson (Ohio State) and Kenichiro Yamamoto (Tokyo Denki University)

Unique equilibrium states

Large deviations

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

The talk in one slide

Setting: X a shift space on a finite alphabet (generalises naturally)

Theorem (Known results)

Suppose X has specification. Then

- bounded distortion \Rightarrow unique equilibrium state.
- **2** A large deviations principle holds for every Gibbs measure.

Goal: Same results with non-uniform versions of above properties

Key idea:

- \mathcal{L} the language of X (space of finite orbit segments)
- Only require properties for $\mathcal{G} \subset \mathcal{L}$
- Get results if $\mathcal G$ is "big enough"

Introduction ○●○○○○ Non-uniform examples

Unique equilibrium states

Large deviations

Specification for shift spaces

Shift space: closed, shift-invariant set $X \subset \mathcal{A}^{\mathbb{N}}$

• $A = \{1, \dots, p\}$ a finite alphabet

Every finite word $w \in A^* = \bigcup_{n \ge 0} A^n$ determines a cylinder

$$[w] = \{x \in X \mid x_1 \dots x_n = w\} \qquad (n = |w|)$$

The language of X is $\mathcal{L} = \{ w \in A^* \mid [w] \neq \emptyset \}.$

- X is topologically transitive iff
 - for all $u, v \in \mathcal{L}$ there exists $w \in \mathcal{L}$ such that $uwv \in \mathcal{L}$
- X has specification if
 - there exists τ ∈ N such that w can be chosen with |w| ≤ τ, independently of the length of u, v

Introduction 000000 Non-uniform examples

Unique equilibrium states 000000000

Large deviations

Pressure and equilibrium states

Topological pressure of $\varphi \colon X \to \mathbb{R}$ is

$$\mathcal{P}(\varphi) = \lim_{n \to \infty} \frac{1}{n} \log \left(\sum_{w \in \mathcal{L}_n} e^{\varphi_n(w)} \right),$$

where $\mathcal{L}_n = \{ w \in \mathcal{L} \mid |w| = n \}$ and $\varphi_n(w) = \sup_{x \in [w]} S_n \varphi(x)$.

 $S_n\varphi(x) = \varphi(x) + \varphi(\sigma x) + \cdots + \varphi(\sigma^{n-1}x)$

Variational principle: $P(\varphi) = \sup\{h(\mu) + \int \varphi \, d\mu \mid \mu \in \mathcal{M}_{\sigma}(X)\}$ • $\mathcal{M}_{\sigma}(X) = \{\sigma \text{-invariant probability measures on } X\}$

A measure achieving the supremum is an equilibrium state.

Unique equilibrium states

Large deviations

Unique equilibrium states

arphi has bounded distortions if there exists $V \in \mathbb{R}$ such that

$$|S_n \varphi(x) - S_n \varphi(y)| \le V$$
 for all $w \in \mathcal{L}, x, y \in [w]$ $(n = |w|)$

 $\mu \in \mathcal{M}_{\sigma}(X)$ is Gibbs if there are K, K' > 0 such that

$$\mathcal{K} \leq rac{\mu[w]}{e^{-nP(arphi)+S_narphi(x)}} \leq \mathcal{K}'$$

for all $w \in \mathcal{L}$, n = |w|, $x \in [w]$.

Theorem (Bowen, 1974)

If X has specification and φ has bounded distortions, then φ has a unique equilibrium state μ , and μ has the Gibbs property.

Unique equilibrium states

Large deviations

Empirical measures

 $\mathcal{M}(X) = \{ \text{Borel probability measures on } X \}$

Given $x \in X$ and $n \in \mathbb{N}$, get empirical measure

$$\mathcal{E}_n(x) = \frac{1}{n} \sum_{k=0}^{n-1} \delta_{\sigma^k x} \qquad \qquad \mathcal{E}_n(x)(\varphi) = S_n \varphi(x)$$

Recall $\mathcal{E}_n(x) \to m$ for *m*-a.e. *x* if *m* ergodic

Large deviations studies rate of decay of $m\{x \mid \mathcal{E}_n(x) \in U\}$ for sets $U \subset \mathcal{M}(X)$ not containing m.

Introduction	Non-uniform examples	Unique equilibrium states	Large deviations
00000	0000	000000000	

Large deviations

X satisfies a large deviations principle with reference measure m and rate function $q: \mathcal{M}(X) \to [-\infty, 0]$ if

$$U \subset \mathcal{M}_{\sigma}(X) \text{ open } \Rightarrow \liminf_{n \to \infty} \frac{1}{n} \log m\{x \mid \mathcal{E}_n(x) \in U\} \ge \sup_{\mu \in U} q(\mu)$$
$$F \subset \mathcal{M}_{\sigma}(X) \text{ closed } \Rightarrow \limsup_{n \to \infty} \frac{1}{n} \log m\{x \mid \mathcal{E}_n(x) \in F\} \le \sup_{\mu \in F} q(\mu)$$

Theorem

If X has specification and m is Gibbs for φ , then X satisfies a large deviations principle with reference measure m and rate function

$$q(\mu) = \begin{cases} h(\mu) + \int \varphi \, d\mu - P(\varphi) & \mu \in \mathcal{M}_{\sigma}(X) \\ -\infty & \mu \notin \mathcal{M}_{\sigma}(X) \end{cases}$$

Introduction 000000	Non-uniform examples ●000	Unique equilibrium states	Large deviations
eta-shifts			

For
$$\beta > 1$$
, Σ_{β} is the coding space for the map

$$f_{\beta} \colon [0,1] \to [0,1], \qquad x \mapsto \beta x \pmod{1}$$

 $1_{eta} = a_1 a_2 \cdots$, where $1 = \sum_{n=1}^{\infty} a_n eta^{-n}$



 $\begin{array}{ll} \textbf{Fact:} & x \in \Sigma_{\beta} \Leftrightarrow \sigma^n x \preceq 1_{\beta} \text{ for all } n \\ & \Leftrightarrow x \text{ labels a walk starting at } \textbf{B} \text{ on this graph:} \end{array}$

(Here $1_{\beta} = 2100201...$)



Properties of β -shifts

 Σ_β has specification iff 1_β does not contain arbitrarily long sequences of 0s.

Schmeling (1997): For Leb-a.e. β , Σ_{β} does not have specification

Hofbauer (1979): Σ_{β} has a unique measure of maximal entropy

Walters (1978): Every Lipschitz potential has a unique eq. state

Equilibrium state is not Gibbs – so what about large deviations? And what about more general bounded distortion potentials?



Given $\beta > 1$, $\alpha \in (0,1)$, consider coding space for

$$f_{\alpha,\beta} \colon x \mapsto \alpha + \beta x \pmod{1}.$$

Can be presented on a countable graph, but more complicated. Similarly with any piecewise expanding interval map.

General class of coded systems: two equivalent characterisations

- Can be presented on a countable graph (finitely many labels)
- Countable set G of generating words w^j that can be freely concatenated: L = G^{*} = {subwords of w^{j₁} · · · w^{jn}}

くしゃ 本理 ディヨッ トヨー うらぐ

Given $S \subset \mathbb{N}$, consider the words $w^n = 0^n 1$ for each $n \in S$.

• Σ_S is the coded system with generators $\{w^n \mid n \in S\}$.

 Σ_S has specification iff S is syndetic (bounded gaps)

Unique equilibrium states

Large deviations

Potentials with unbounded distortion

Manneville–Pomeau / Hofbauer-type potentials on Σ_{β} :

- $x \in \Sigma_{\beta}$: k(x) = number of initial 0s in x
- $\varphi(x) = a_{k(x)}$ where $a_n \to 0$ as $n \to \infty$
- If $|\sum a_n| = \infty$, then φ has unbounded distortion and $P(t\varphi)$ can exhibit phase transitions
- Arises from $f(x) = x + \gamma x^{1+\varepsilon} \pmod{1}$ for $\gamma > 0$, $\varphi = -\log f'$

Grid potentials:

• $\varphi(x) = \psi(x) + a_{k(x)}$, where ψ has bounded distortion and $2^{-k(x)}$ is distance from x to some subshift $Y \subset X$

Unique equilibrium states •00000000 Large deviations

Collections of words

X a shift space, \mathcal{L} its language, $\mathcal{D} \subset \mathcal{L}$

Pressure of φ on \mathcal{D} . Let $\mathcal{D}_n = \{w \in \mathcal{D} \mid |w| = n\}$, then

$$P(\mathcal{D}, \varphi) = \overline{\lim} \frac{1}{n} \log \sum_{w \in \mathcal{D}_n} e^{\varphi_n(w)} \qquad h(\mathcal{D}) = P(\mathcal{D}, 0)$$

 \mathcal{D} has specification if there exists $\tau \in \mathbb{N}$ such that for all $w^1, \ldots, w^k \in \mathcal{D}$, there exist $v^1, \ldots, v^{k-1} \in \mathcal{L}$ with $|v^j| \leq \tau$ such that $w^1 v^1 w^2 \cdots v^{k-1} w^k \in \mathcal{L}$.

 φ has bounded distortion on \mathcal{D} if there exists $V \in \mathbb{R}$ such that for all $w \in \mathcal{D}$, n = |w|, $x, y \in [w]$, we have $|S_n \varphi(x) - S_n \varphi(y)| \leq V$.

 μ has the Gibbs property on \mathcal{D} if there are K, K' > 0 such that for all $w \in \mathcal{D}$, $n = |w|, x \in [w]$, we have $K \leq \frac{\mu[w]}{e^{-nP(\varphi) + S_n\varphi(x)}} \leq K'$.

Introduction	Non-uniform examples	Unique equilibrium states	Large deviations
000000	0000	00000000	
Decompos	itions		

Idea: Unique equilibrium state for φ if there is a "large enough" $\mathcal{G} \subset \mathcal{L}$ with specification such that φ has bounded distortion on \mathcal{D} . What does "large enough" mean? Decomposition of \mathcal{L} : sets $\mathcal{C}^p, \mathcal{G}, \mathcal{C}^s \subset \mathcal{L}$ such that $\mathcal{L} = \mathcal{C}^p \mathcal{G} \mathcal{C}^s$.

$$\mathcal{G}^{M} = \{ uvw \in \mathcal{L} \mid u \in \mathcal{C}^{p}, v \in \mathcal{G}, w \in \mathcal{C}^{s}, |u|, |w| \leq M \}$$

Theorem (C.–Thompson, 2012)

Suppose \mathcal{L} has a decomposition such that

- **2** \mathcal{G}^M has specification for every M
- $P(\mathcal{C}^p \cup \mathcal{C}^s, \varphi) < P(\varphi)$

Then φ has a unique equilibrium state μ . It is Gibbs on each \mathcal{G}^{M} .

Unique equilibrium states

Large deviations

Example: β -shift

$$C^{p} = \emptyset$$

$$\mathcal{G} = \{ \text{words (paths) starting and ending at } B \}$$

 $C^{s} = \{ words (paths) starting at B and never returning \}$



• $\mathcal{L}=\mathcal{C}^{p}\mathcal{G}\mathcal{C}^{s}$

G^M corresponds to paths ending in first *M* vertices, so *G^M* has specification for each *M*

•
$$h(\mathcal{C}) = 0$$
, where $\mathcal{C} = \mathcal{C}^p \cup \mathcal{C}^s$

Large deviations

Hölder potentials

To get unique equilibrium state for φ , need $P(\mathcal{C}, \varphi) < P(\varphi)$.

Suppose we know that $h(\mathcal{C}) + \sup_{x \in X} \left(\overline{\lim} \frac{1}{n} S_n \varphi(x) \right) < P(\varphi)$. Then get $P(\mathcal{C}, \varphi) < P(\varphi)$.

Equivalent conditions:

- $\sup_x \overline{\lim} \frac{1}{n} S_n \varphi(x) < P(\varphi) h(\mathcal{C})$
- $\exists n \text{ such that } \sup_x \frac{1}{n} S_n \varphi(x) < P(\varphi) h(\mathcal{C})$
- Every equilibrium state for φ has $h(\mu) > h(\mathcal{C})$

Theorem (C.–Thompson, 2012)

When X is a β -shift, every Hölder continuous potential satisfies the above condition. In particular, it has a unique equilibrium state μ , and μ is Gibbs on each \mathcal{G}^M .

Unique equilibrium states

Large deviations

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

Decompositions for coded systems

Let X be a coded shift: two natural decompositions of \mathcal{L} .

In terms of countable graph presentation

- Fix a finite subset F of the graph
- C^{p} = paths starting outside F and entering it only on the last step, or never
- $\mathcal{G} = \mathsf{paths} \mathsf{ starting} \mathsf{ and} \mathsf{ ending} \mathsf{ in} \mathsf{ F}$
- C^s = paths starting in F and never returning

In terms of generators

• $G \subset A^*$ a set of generators

•
$$\mathcal{G} = \mathcal{G}^* = \{ w^1 \cdots w^n \mid w^j \in \mathcal{G} \}$$

- $C^p =$ suffixes of generators
- $\mathcal{C}^{s} = \text{prefixes of generators}$

Introduction 000000	Non-uniform examples	Unique equilibrium states 000000000	Large deviations

Interval maps

Let f be a piecewise expanding interval map, X the coding space

- \bullet Graph presentation gives decomposition of ${\cal L}$
- $h(\mathcal{C}) > 0$, but can be made arbitrarily small by taking F large

Definition

The entropy of obstructions to specification is

$$h_{\text{spec}}^{\perp}(X) = \inf\{h(\mathcal{C}^{p} \cup \mathcal{C}^{s}) \mid \text{there exists } \mathcal{G} \text{ such that} \\ \mathcal{L} = \mathcal{C}^{p} \mathcal{G} \mathcal{C}^{s} \text{ and every } \mathcal{G}^{M} \text{ has specification}\}$$

Unique equilibrium state for φ , Gibbs on each \mathcal{G}^M , if any (all) of

- $\sup_x \overline{\lim} \frac{1}{n} S_n \varphi(x) < P(\varphi) h_{\text{spec}}^{\perp}$
- $\exists n \text{ such that } \sup_x \frac{1}{n} S_n \varphi(x) < P(\varphi) h_{\text{spec}}^{\perp}$
- Every equilibrium state for φ has $h(\mu) > h_{\text{spec}}^{\perp}$

Unique equilibrium states

Large deviations

Positive entropy equilibrium states

For S-gap shifts the natural decomposition from generators gives

•
$$\mathcal{C}^p = \{0^n 1 \mid n \in \mathbb{N}\}$$

•
$$\mathcal{G} = \{0^{n_1}1\cdots 0^{n_k}1 \mid n_j \in S\}$$

•
$$\mathcal{C}^s = \{0^n \mid n \in \mathbb{N}\}$$

So $h_{\rm spec}^{\perp} = 0$, as with other examples

For S-gap shifts, every Hölder potential has $P(\varphi) > \sup \overline{\lim} \frac{1}{n} S_n \varphi$.

This gives same set of results as for $\beta\text{-shifts:}$ unique equilibrium state, Gibbs on \mathcal{G}^M

Open questions: What about piecewise expanding interval maps? Are there coded systems with $h_{\text{spec}}^{\perp} = 0$ for which some Hölder potentials have zero entropy equilibrium states?

Unique equilibrium states

Large deviations

Unbounded distortion

X a
$$\beta$$
-shift, $\varphi(x) = \psi(x) + a_{k(x)}$

 $\mathcal{G} = \mathsf{paths} \mathsf{ starting} \mathsf{ at } B \mathsf{ and} \mathsf{ ending} \mathsf{ at the next vertex} \mathsf{ from } B$

 C^s = paths starting at the second vertex and never returning to B, and paths starting at B and never getting to the next vertex



- \mathcal{G}^M has specification for each M
- φ has bounded distortion on ${\mathcal G}$
- $P(\mathcal{C}^{s}, \varphi) < P(\varphi)$ whenever $\varphi(0) < P(\varphi)$

Large deviations

Manneville–Pomeau for β -transformations

Conclusion: If $P(\varphi) > \varphi(0)$ then φ has a unique equilibrium state.

Corollary: Let $f(x) = x + \gamma x^{1+\varepsilon} \pmod{1}$ and $\varphi(x) = -\log f'(x)$, where $\gamma > 0$ and $0 < \varepsilon < 1$. Then $t\varphi$ has a unique equilibrium state for every t < 1.

Can get similar results with grid potentials if X has specification.

Large deviations

▲ロト ▲帰 ト ▲ ヨ ト ▲ ヨ ト ・ ヨ ・ の Q ()

Statistical specification properties

Large deviations results have been obtained for β -shift and other systems by using statistical specification properties.

- Pfister, Sullivan (2005)
- Yamamoto (2009)
- Varandas (2012)

All reflect idea that the gluing procedure can be weakened in a way that does not interfere too much with Birkhoff averages.

Introduction	Non-uniform examples	Unique equilibrium states	Large deviations
000000	0000	000000000	0●00000



shifts

Given any $v \in \mathcal{L}$, can transform v into a word $u \in \mathcal{G}$ by making a single change. (Change last non-zero symbol to 0).

Thus given any $v, w \in \mathcal{L}$, the word vw may not be in \mathcal{L} , but can be transformed into a word in \mathcal{L} by making a single change.

General method for getting a word that concatenates statistical properties of v and w, as long as $\frac{\text{number of changes}}{\text{length of word}} \rightarrow 0.$

Introduction 000000	Non-uniform examples	Unique equilibrium states 00000000	Large deviations
Esta analy	:_		

Goal: Define a metric on A^* (set of all finite words) that controls how much Birkhoff sums can vary.

An edit of a word w is any of the following:

Edit metric

- Substition: $w = uav \mapsto w' = ubv$ $u, v \in A^*, a, b \in A$
- Insertion: $w = uv \mapsto w' = ubv$ $u, v \in A^*, b \in A$
- Deletion: $w = uav \mapsto w' = uv$ $u, v \in A^*, a \in A$

 $\hat{d}(v, w) =$ minimum number of edits required to go from v to w.

Key property: Let D be a metric inducing the weak* topology on $\mathcal{M}(X)$. Then for every $\eta > 0$ there is $\delta > 0$ such that if $\frac{\hat{d}(v,w)}{|v|} < \delta$, then $D(\mathcal{E}_{|v|}(x), \mathcal{E}_{|w|}(y)) < \eta$ for all $x \in [v]$ and $y \in [w]$.

Unique equilibrium states

Large deviations

Edit approachability

mistake function: a non-increasing sub-linear function $g: \mathbb{N} \to \mathbb{N}$. $(\frac{g(n)}{n} \to 0)$

 \mathcal{L} is edit approachable by $\mathcal{G} \subset \mathcal{L}$ if there exists a mistake function g such that for every $v \in \mathcal{L}$, there is $w \in \mathcal{G}$ with $\hat{d}(v, w) < g(|v|)$.

Equivalently, $\mathcal{L} = \bigcup_{w \in \mathcal{G}} B_{\hat{d}}(w, g(|w|)).$

Examples: For both the β -shifts and the *S*-gap shifts, \mathcal{L} is edit approachable by the natural choice of \mathcal{G} .

Large deviations

Large deviations

Theorem (C.–Thompson–Yamamoto, 2013)

X a shift space on a finite alphabet, \mathcal{L} its language. Suppose

- **1** \mathcal{L} is edit approachable by \mathcal{G} ,
- *Q G* has specification (with good concatenations),
- 3 $m \in \mathcal{M}(X)$ is Gibbs for φ on \mathcal{G} .

Then X satisfies a LDP with reference measure m and rate f'n

$$q(\mu) = \begin{cases} h(\mu) + \int \varphi \, d\mu - P(\varphi) & \mu \in \mathcal{M}_{\sigma}(X) \\ -\infty & \mu \notin \mathcal{M}_{\sigma}(X) \end{cases}$$

In particular, every Hölder continuous φ on a β -shift or S-gap shift.

Large deviations

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

Key tool in proof

The bulk of the proof is in the following proposition.

X a shift space, $\mathcal L$ edit approachable by $\mathcal G$ with specification

Then \exists an increasing sequence $X_n \subset X$ of subshifts s.t.

- Each X_n has specification
- **2** If *m* is Gibbs on \mathcal{G} , then it is Gibbs on every $\mathcal{L}(X_n)$
- For every $\mu \in \mathcal{M}_{\sigma}(X)$ there are subshifts $Y_n \subset X_n$ s.t. $\mathcal{M}_{\sigma}(Y_n) \to \{\mu\}$ and $\underline{\lim} h(Y_n) \ge h(\mu)$

In particular, ergodic measures are entropy-dense in $\mathcal{M}_{\sigma}(X)$

Introduction 000000	Non-uniform examples 0000	Unique equilibrium states	Large deviations
Moral			

One moral of the story:

Many good consequences of specification (and other properties) can still be obtained as long as properties hold on a "large enough" set of words (orbit segments)

"Large enough" means the ability to get from \mathcal{L} to \mathcal{G} with some "small" tinkering, where meaning of "small" depends on context

- Unique equilibrium state: only need to remove a prefix and a suffix from the word in *L*, and these come from "small" lists
- Large deviations: only need to make a small number of edits
- Hölder \Rightarrow only positive entropy equilibrium states: ????