Math 3331 Differential Equations 4.4 Harmonic Motion

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4.4 Harmonic Motion

- Models of Harmonic Motion
 - Mass-Spring System
 - Pendulum For Small ϕ
 - RLC-Circuit
- Classification of Harmonic Motion
 - Undamped Case
 - Underdamped Case
 - Critically damped Case
 - Overdamped Case
- Qualitative Features of Harmonic Motion
 - Undamped Case
 - Underdamped Case
 - Critically damped Case
 - Overdamped Case
- Worked out Examples from Exercises
 - 11, 22

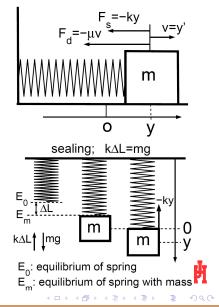


Harmonic Motion: Mass-Spring System

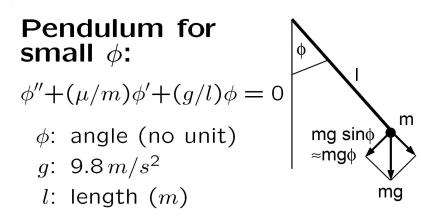
Mass–spring system:

 $my'' + \mu y' + ky = 0$

- m: mass (kg)
 - μ : damping constant (kg/s)
 - k: spring constant (kg/s^2)
 - y: deviation of mass position from equilibrium position (m)
- y': velocity (m/s)

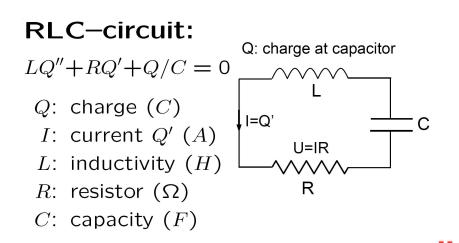


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Harmonic Motion: RLC-Circuit



Classification of Harmonic Motion: Mass-Spring System

Mass-Spring System

DE:

$$egin{aligned} y''+rac{\mu}{m}y'+rac{k}{m}y&=0,\ m>0,\quad k>0,\quad \mu\geq 0 \end{aligned}$$

Characteristic Eqn:

$$\lambda^2 + \frac{\mu}{m}\lambda + \frac{k}{m} = 0$$

Roots:

$$\lambda_{1,2} = -\frac{\mu}{2m} \pm \frac{1}{2m}\sqrt{\mu^2 - 4km}$$

Classification

Undamped Case:

$$\mu = 0$$

② Underdamped Case:

$$0<\mu^2<4$$
 km

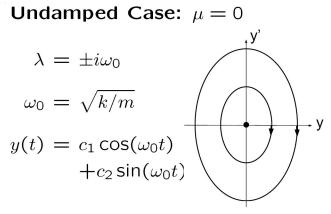
Oritically damped Case:

$$\mu^2 = 4km$$

Overdamped Case:

$$\mu^2 > 4km$$

Mass-Spring System: Undamped Case ($\mu = 0$)



- oscillation
- phase portrait: center
- clockwise direction of rotation



Mass-Spring System: Underdamped Case ($0 < \mu^2 < 4km$)

Underdamped Case: $0 < \mu^2 < 4km$ $\lambda_{1,2} = -\alpha \pm i\omega$ $\alpha = \mu/2m$ $\omega = \sqrt{4km - \mu^2}/(2m)$ $= \sqrt{\omega_0^2 - \mu^2/4m^2}$ $y(t) = e^{-\alpha t}(c_1 \cos(\omega t))$ $+c_2 \sin(\omega t))$

- damped oscillation
- phase portrait: spiral sink
- clockwise direction of rotation



Mass-Spring System: Critically damped Case ($\mu^2 = 4km$)

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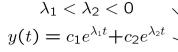
Critically Damped Case: $\mu^2 = 4km$ $\lambda_1 = \lambda_2 = -\mu/(2m)$ y' $y(t) = e^{\lambda_1 t}(c_1 + c_2 t)$

 phase portrait: degenerate nodal sink



Mass-Spring System: Overdamped Case ($\mu^2 > 4km$)





- phase portrait: nodal sink
- both eigenlines: negative slopes

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Harmonic Motion: Undamped Case

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Undamped Case:

$$y(t) = c_1 \cos(\omega_0 t) + c_2 \sin(\omega_0 t)$$

= $A[d_1 \cos(\omega_0 t) + d_2 \sin(\omega_0 t)]$
where
$$\begin{cases} A = \sqrt{c_1^2 + c_2^2} \\ d_1 = c_1/A, \ d_2 = c_2/A \end{cases}$$

Since $d_1^2 + d_2^2 = 1$ we can define ϕ by
 $d_1 = \cos \phi, \ d_2 = \sin \phi$

$$\Rightarrow d_2/d_1 = c_2/c_1 = \tan \phi$$
$$t) = A[\cos \phi \cos(\omega_0 t) + \sin \phi \sin(\omega_0 t)]$$

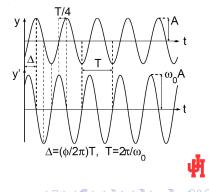
$$= A\cos(\omega_0 t - \phi)$$

$$y'(t) = -\omega_0 A\sin(\omega_0 t - \phi)$$

A: amplitude

 $\phi:$ phase angle, choose $-\pi < \phi \leq \pi$

$$\phi = \begin{cases} \arctan(c_2/c_1) & \text{if } c_1 > 0\\ \arctan(c_2/c_1) + \pi & \text{if } c_1 < 0, c_2 \ge 0\\ \arctan(c_2/c_1) - \pi & \text{if } c_1 < 0, c_2 < 0\\ \pi/2 & \text{if } c_1 = 0, c_2 > 0\\ -\pi/2 & \text{if } c_1 = 0, c_2 < 0 \end{cases}$$

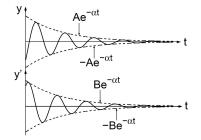


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Harmonic Motion: Underdamped Case

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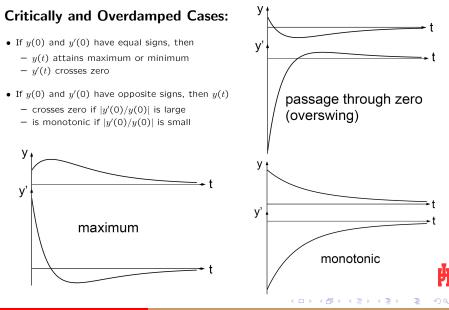
Underdamped Case: $y(t) = e^{-\alpha t} [c_1 \cos(\omega t) + c_2 \sin(\omega t)]$ $= e^{-\alpha t} A \cos(\omega t - \phi)$ $y'(t) = e^{-\alpha t} [(\omega c_2 - \alpha c_1) \cos(\omega t) - (\omega c_1 + \alpha c_2) \sin(\omega t)]$ $= e^{-\alpha t} B \cos(\omega t - \psi)$ $\pm A e^{-\alpha t}, \pm B e^{-\alpha t}: \text{ envelopes of damped oscillations}$



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Harmonic Motion Classification Qualitative Exercise

Harmonic Motion: Critically and Overdamped Cases



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Ex. 4.4.11: Given an undamped mass-spring system with m = 0.2 kg, $k = 5 kg/s^2$, y(0) = 0.5 m, y'(0) = 0, find amplitude, frequency, phase of motion.

4.4

Natural frequency: $\omega_0 = \sqrt{5/0.2} = 5/s \Rightarrow$

$$y(t) = c_1 \cos 5t + c_2 \sin 5t, \quad y'(t) = -5c_1 \sin 5t + 5c_2 \cos 5t$$

IC: $y(0) = c_1 = 0.5, \quad y'(0) = 5c_2 = 0 \Rightarrow \quad y(t) = 0.5 \cos 5t$
 $\Rightarrow \text{ amplitude: } A = 0.5 m, \quad \text{phase: } \phi = 0$



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Ex. 4.4.22: A mass-spring system with m = 0.1 kg, $k = 9.8 kg/s^2$ is placed in a viscous medium with friction force 0.3 N if v = 0.2 m/s. Initial data: y(0) = 0.1 m, y'(0) = 0. Find amplitude, frequency, and phase of motion. Friction coefficient: $F_d = \mu v \Rightarrow 0.3 = \mu 0.2 \Rightarrow \mu = 1.5 kg/s$.

4.4

ODE: $0.1y'' + 1.5y' + 9.8y = 0 \Rightarrow y'' + 15y' + 98y = 0 \Rightarrow$ $p(\lambda) = \lambda^2 + 15\lambda + 98 = (\lambda + 7.5)^2 + 41.75 \Rightarrow \lambda = -7.5 \pm i\sqrt{41.75} \approx -7.5 \pm 6.461i$ \Rightarrow Damped motion with frequency $\omega \approx 6.461/s$ of harmonic part \Rightarrow $y(t) = e^{-7.5t}(c_1 \cos \omega t + c_2 \sin \omega t)$

$$y(t) = e^{-\alpha t} (c_1 \cos \omega t + c_2 \sin \omega t)$$

$$y'(t) = e^{-7.5t} [(\omega c_2 - 7.5c_1) \cos \omega t - (\omega c_1 + 7.5c_2) \sin \omega t]$$

IC: $y(0) = c_1 = 0.1, \ y'(0) = \omega c_2 - 7.5c_1 = 0 \Rightarrow c_2 = 7.5c_1/\omega \approx 0.116$

$$\Rightarrow y(t) = e^{-7.5t} (0.1 \cos \omega t + 0.116 \sin \omega t)$$



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Exercise 4.4.22 (cont.)

Amplitude of harmonic part: $A_0 \approx \sqrt{0.1^2 + 0.116^2} \approx 0.153$. Since $c_1, c_2 > 0$ \Rightarrow phase angle $\phi = \arctan(c_2/c_1) \approx \arctan(1.16) \approx 0.859$ $\Rightarrow y(t) = 0.153e^{-7.5t}\cos(6.461t - 0.859)$

4.4

$$\Rightarrow$$
 amplitude: $A(t) = 0.153e^{-7.5t}m$,
frequency: $\omega = 6.461/s$, phase: $\phi = 0.859$

