Name and ID: _____

1. Find the solution of the initial-value problem

(a)

$$x' = 2x + 4y + 4z$$

$$y' = x + 2y + 3z$$

$$z' = -3x - 4y - 5z$$

with x(0) = 1, y(0) = -1 and z(0) = 0.

Solution. In matrix form, the system is

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix}' = \begin{pmatrix} 2 & 4 & 4 \\ 1 & 2 & 3 \\ -3 & -4 & -5 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

The eigen-pairs of $A = \begin{pmatrix} 2 & 4 & 4 \\ 1 & 2 & 3 \\ -3 & -4 & -5 \end{pmatrix}$ are

$$\lambda_1 = -1, \quad \lambda_2 = 2i, \quad \lambda_3 = -2i$$

 $v_1 = (0, -1, 1)^T, \quad v_2 = (-2, -1 - i, 2)^T, \quad v_3 = (-2, -1 + i, 2)^T.$

Using Euler's formula

$$w(t) = e^{2it} \begin{pmatrix} -2\\ -1-i\\ 2 \end{pmatrix} = (\cos 2t + i \sin 2t) \left(\begin{pmatrix} -2\\ -1\\ 2 \end{pmatrix} + i \begin{pmatrix} 0\\ -1\\ 0 \end{pmatrix} \right)$$
$$= \left(\cos 2t \begin{pmatrix} -2\\ -1\\ 2 \end{pmatrix} - \sin 2t \begin{pmatrix} 0\\ -1\\ 0 \end{pmatrix} \right) + i \left(\cos 2t \begin{pmatrix} 0\\ -1\\ 0 \end{pmatrix} + \sin 2t \begin{pmatrix} -2\\ -1\\ 2 \end{pmatrix} \right)$$

The real and imaginary parts of w are solutions and we can write the general solution

$$\begin{pmatrix} x(t)\\ y(t)\\ z(t) \end{pmatrix} = c_1 e^{-t} \begin{pmatrix} 0\\ -1\\ 1 \end{pmatrix} + c_2 \begin{pmatrix} -2\cos 2t\\ -\cos 2t + \sin 2t\\ 2\cos 2t \end{pmatrix} + c_3 \begin{pmatrix} -2\sin 2t\\ -\cos 2t - \sin 2t\\ 2\sin 2t \end{pmatrix}$$

If x(0) = 1, y(0) = -1 and z(0) = 0, then

$$\begin{pmatrix} 1\\-1\\0 \end{pmatrix} = c_1 \begin{pmatrix} 0\\-1\\1 \end{pmatrix} + c_2 \begin{pmatrix} -2\\-1\\2 \end{pmatrix} + c_3 \begin{pmatrix} 0\\-1\\0 \end{pmatrix}$$

We find that $c_1 = 1$, $c_2 = -1/2$, and $c_3 = 1/2$. Hence the solution is

$$\begin{pmatrix} x(t) \\ y(t) \\ z(t) \end{pmatrix} = e^{-t} \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} -2\cos 2t \\ -\cos 2t + \sin 2t \\ 2\cos 2t \end{pmatrix} + \frac{1}{2} \begin{pmatrix} -2\sin 2t \\ -\cos 2t - \sin 2t \\ 2\sin 2t \end{pmatrix}$$
$$= \begin{pmatrix} \cos 2t - \sin 2t \\ -e^{-t} - \sin 2t \\ e^{-t} - \cos 2t + \sin 2t \end{pmatrix}$$

(b)

$$x' = 6x - 4z$$
$$y' = 8x - 2y$$
$$z' = 8x - 2z$$

with x(0) = -2, y(0) = -1 and z(0) = 0.

Solution. In matrix form, the system is

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix}' = \begin{pmatrix} 6 & 0 & -4 \\ 8 & -2 & 0 \\ 8 & 0 & -2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

The eigen-pairs of $A = \begin{pmatrix} 6 & 0 & -4 \\ 8 & -2 & 0 \\ 8 & 0 & -2 \end{pmatrix}$ are
$$\lambda_1 = -2, \quad \lambda_2 = 2 + 4i, \quad \lambda_3 = 2 - 4i$$
$$v_1 = (0, 1, 0)^T, \quad v_2 = (1 + i, 2, 2)^T, \quad v_3 = (1 - i, 2, 2)^T$$

The general solution is

$$\begin{pmatrix} x(t) \\ y(t) \\ z(t) \end{pmatrix} = c_1 e^{-2t} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + c_2 e^{2t} \begin{pmatrix} \cos 4t - \sin 4t \\ 2\cos 4t \\ 2\cos 4t \end{pmatrix} + c_3 e^{2t} \begin{pmatrix} \cos 4t + \sin 4t \\ 2\sin 4t \\ 2\sin 4t \end{pmatrix}$$

If x(0) = -2, y(0) = -1 and z(0) = 0, then

$$\begin{pmatrix} -2\\ -1\\ 0 \end{pmatrix} = c_1 \begin{pmatrix} 0\\ 1\\ 0 \end{pmatrix} + c_2 \begin{pmatrix} 1\\ 2\\ 2 \end{pmatrix} + c_3 \begin{pmatrix} 1\\ 0\\ 0 \end{pmatrix}$$

We find that $c_1 = -1$, $c_2 = 0$, and $c_3 = -2$. Hence the solution is

$$\begin{pmatrix} x(t) \\ y(t) \\ z(t) \end{pmatrix} = -e^{-2t} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} - 2e^{2t} \begin{pmatrix} \cos 4t + \sin 4t \\ 2\sin 4t \\ 2\sin 4t \end{pmatrix} = \begin{pmatrix} -2e^{2t}(\cos 4t + \sin 4t) \\ -e^{-2t} - 4e^{2t}\sin 4t \\ -4e^{2t}\sin 4t \end{pmatrix}$$

(c)

r

$$x' = -4x + 8y + 8z$$
$$y' = -4x + 4y + 2z$$
$$z' = 2z$$

with x(0) = 1, y(0) = 0 and z(0) = 0.

Solution. In matrix form, the system is

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix}' = \begin{pmatrix} -4 & 8 & 8 \\ -4 & 4 & 2 \\ 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

The eigen-pairs of $A = \begin{pmatrix} -4 & 8 & 8 \\ -4 & 4 & 2 \\ 0 & 0 & 2 \end{pmatrix}$ are
$$\lambda_1 = 2, \quad \lambda_2 = 4i, \quad \lambda_3 = -4i$$
$$v_1 = (0, -1, 1)^T, \quad v_2 = (1 - i, 1, 0)^T, \quad v_3 = (1 + i, 1, 0)^T.$$

The general solution is

$$\begin{pmatrix} x(t) \\ y(t) \\ z(t) \end{pmatrix} = c_1 e^{2t} \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix} + c_2 \begin{pmatrix} \cos 4t + \sin 4t \\ \cos 4t \\ 0 \end{pmatrix} + c_3 \begin{pmatrix} -\cos 4t + \sin 4t \\ \sin 4t \\ 0 \end{pmatrix}$$

If x(0) = 1, y(0) = 0 and z(0) = 0, then

$$\begin{pmatrix} 1\\0\\0 \end{pmatrix} = c_1 \begin{pmatrix} 0\\-1\\1 \end{pmatrix} + c_2 \begin{pmatrix} 1\\1\\0 \end{pmatrix} + c_3 \begin{pmatrix} -1\\0\\0 \end{pmatrix}$$

We find that $c_1 = 0$, $c_2 = 0$, and $c_3 = -1$. Hence the solution is

$$\begin{pmatrix} x(t) \\ y(t) \\ z(t) \end{pmatrix} = \begin{pmatrix} \cos 4t - \sin 4t \\ -\sin 4t \\ 0 \end{pmatrix}$$

2. Find the general solution of the system

$$x' = 6x - 5y + 10z$$
$$y' = -x + 2y - 2z$$
$$z' = -x + y - z$$

Solution. The eigen-pairs of
$$A = \begin{pmatrix} 6 & -5 & 10 \\ -1 & 2 & -2 \\ -1 & 1 & -1 \end{pmatrix}$$
 are
 $\lambda_1 = 5, \quad \lambda_2 = \lambda_3 = 1 \qquad v_1 = (-5, 1, 1)^T, \quad v_2 = (1, 1, 0)^T,$

Proceed to the solution on your own!

3. Find the general solution of the system

$$x' = -2x + y - z$$
$$y' = x - 3y$$
$$z' = 3x - 5$$

Solution. Note that this linear system is **not** homogeneous, therefore we cannot solve it yet! You can skip it. Or if you like the challenge, substitute the last equation with z' = 3x or z' = 3x - 5y or z' = 3x - 5z.

4. Classify the equilibrium point of the system y' = Ay. Sketch the phase portrait by hand.

(a)
$$A = \begin{pmatrix} -16 & 9 \\ -18 & 11 \end{pmatrix}$$
 (b) $A = \begin{pmatrix} 8 & 3 \\ -6 & -1 \end{pmatrix}$ (c) $A = \begin{pmatrix} -11 & -5 \\ 10 & 4 \end{pmatrix}$
(d) $A = \begin{pmatrix} 2 & -4 \\ 8 & 6 \end{pmatrix}$ (e) $A = \begin{pmatrix} 6 & -5 \\ 10 & -4 \end{pmatrix}$ (f) $A = \begin{pmatrix} -4 & 10 \\ -2 & 4 \end{pmatrix}$

Solution. Please practice how to solve 2×2 linear systems and how to classify them. In the exam you will be asked to solve one such linear system.

Also practice how to graph:

- 1. Nodal Source(both eigenvalues are positive and distinct),
- 2. Nodal Sink (both eigenvalues are negative and distinct),
- 3. Saddle Point (one eigenvalue is positive, the other negative),
- 4. Center (eigenvalues are complex of form $z = \pm bi$),
- 5. Spiral Source (eigenvalues are complex of form $z = a \pm bi$ with a > 0),
- 6. Spiral Sink (eigenvalues are complex of form $z = a \pm bi$ with a < 0).

You have to know how to explain!

(a) is SADDLE: To show why, you can either find the eigenvalues, which will be one positive, the other negative, hence the classification is done, or you can show as follows: If

$$A = \begin{pmatrix} -16 & 9\\ -18 & 11 \end{pmatrix}$$

 $v_3 = (-2, 0, 1)^T$.

then the trace is T = -5 and the determinant is D = -14 < 0. Hence, the equilibrium point at the origin is a saddle. Hence the classification is done!

In order to sketch the SADDLE portrait, you solve it:

The characteristic polynomial is

$$p(\lambda) = \lambda^2 - T\lambda + D = \lambda^2 + 5\lambda - 14$$

which produces eigenvalues $\lambda_1 = -7$ and $\lambda_2 = 2$. Because

$$A - \lambda_1 I = A + 7I = \begin{pmatrix} -9 & 9\\ -18 & 18 \end{pmatrix} \rightarrow v_1 = (1, 1)^T$$

leading to the exponential solution

$$y_1(t) = e^{\lambda_1 t} v_1 = e^{-7t} \begin{pmatrix} 1\\ 1 \end{pmatrix}$$

Because

$$A - \lambda_2 I = A - 2I = \begin{pmatrix} -18 & 9 \\ -18 & 9 \end{pmatrix} \rightarrow v_2 = (1, 2)^T$$

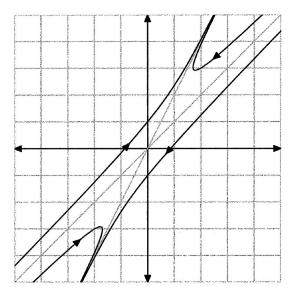
leading to the exponential solution

$$y_2(t) = e^{\lambda_2 t} v_2 = e^{2t} \begin{pmatrix} 1\\2 \end{pmatrix}$$

The general solution is

$$y(t) = c_1 y_1(t) + c_2 y_2(t) = c_1 e^{-7t} \begin{pmatrix} 1\\1 \end{pmatrix} + c_2 e^{2t} \begin{pmatrix} 1\\2 \end{pmatrix}$$

Solutions approach the halfline generated by $c_2(1,2)^T$ as they move forward in time, but they approach the halfline generated by $c_1(1,1)^T$ as they move backward in time. A hand sketch follows



The answers for the rest are:

- (b)NODAL SOURCE
- (c)NODAL SINK
- (d)SPIRAL SINK, the motion is counterclockwise
- (e)SPIRAL SOURCE, the motion is counterclockwise
- (f)CENTER, the motion is clockwise.