

LECTURE 13

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Say $I \subset \mathbb{R}$ is a maximal interval of existence if $\nexists J \supsetneq I$ s.t. $x: J \rightarrow U$ solving IVP exists

[Thm] Let $U \subset \mathbb{R}^n$ open, $f: U \rightarrow \mathbb{R}^n \in C^1$, $x(t)$ solve IVP on maximal interval of existence.

Then I is open & if $\sup I < \infty$, then $\nexists$ cpt $K \subset U \ni t \in I$ s.t. $x(t) \notin K$

[Rmk] "as $t \rightarrow \beta = \sup I$, either $x \rightarrow \partial U$ or $|x| \rightarrow \infty$ "

[Pf] If closed at either end then can extend using $\Sigma P-2.2$. Let $I = (\alpha, \beta)$, fix $\gamma \in (\alpha, \beta)$. Let $M = \max_{x \in K} |f(x)|$ and suppose $x \in K \forall t \in I$.

$$\text{Then } |x(t_0) - x(t_1)| = \left| \int_{t_0}^{t_1} \dot{x}(s) ds \right| \leq \int_{t_0}^{t_1} |f(x(s))| ds \leq M(t_1 - t_0)$$

$\therefore x$ is Lipschitz $\therefore$ extends to its map $x: [\gamma, \beta] \rightarrow K \subset U$

Furthermore, $\frac{d}{dt} x(t)|_{\beta^-} = f(x(\beta))$ & $\dot{y} = f(y)$, $y(\beta) = x(\beta)$ has unique solution on $(\beta - \tau, \beta + \tau)$ $\therefore x = y$ on $(\beta - \tau, \beta]$ $\therefore$

$x = y$ on $(\beta, \beta + \tau)$ extends solution contradicting maximality. $\square$

What about continuity w.r.t. IC on maximal interval of existence? (not just local intervals)

[Thm] Let $f \in C^1(U, \mathbb{R}^n)$ & $x(t)$ solve (1) $\dot{x} = f(x)$ on $[t_0, t_1]$ & $x(t_0) = x_0$.

$[t_0, t_1]$. Then $\exists$ nbhd $x_0 \in V \subset U$ & const K s.t. $\forall y_0 \in V$

$\exists! y: [t_0, t_1] \rightarrow U$. Further, $|x - y| \leq |x_0 - y_0| e^{K(t-t_0)} \forall t \in [t_0, t_1]$.

[Rmk] Gives both existence-uniqueness & continuity.

[Lemma] If $f: A \rightarrow \mathbb{R}^n$ is loc Lip & A is cpt then f is Lip.

[Pf] If not then $\exists |f(x_n) - f(y_n)| \geq n|x_n - y_n| \forall n$, relabel so

$$x_n \rightarrow x^*, y_n \rightarrow y^*, |f(x)| \leq M \forall x \in A \Rightarrow |x^* - y^*| \leq \frac{1}{n} 2M \forall n \nexists \square$$

(alternate pf: $L: A \times A \setminus \Delta \rightarrow \mathbb{R}, (x, y) \mapsto \frac{|f(x) - f(y)|}{|x - y|}$
extends to upper semicont $L: A \times A \rightarrow \mathbb{R} \therefore$ achieves max)

Pf of Thm. $[t_0, t_1]$ cpt $\Rightarrow \exists \varepsilon > 0$ s.t. $|z - x(t)| \leq \varepsilon$
 $\Rightarrow z \in U \forall t \in [t_0, t_1]$. $A := B(x([t_0, t_1]), \varepsilon)$ is cpt
 $\therefore f|_A$ is Lip, let $k = \text{const.}$

Choose $\delta > 0$ s.t. $\delta \leq \varepsilon, \delta e^{k|t_1 - t_0|} \leq \varepsilon$.

Fix $|y_0 - x_0| < \delta$. Because $y_0 \in U, \exists$ soln on
max interval $[t_0, \beta)$. If $\beta \leq t_1$, then by Gronwall
every $t \in [\beta, t_1)$ has $|y(t) - x(t)| \leq \delta e^{k|t - t_0|} < \varepsilon$

$\therefore y \in A \&$ (prev. thm). Thus y def on $[t_0, t_1]$
(Rmk: this implies $B(x_0)$ is LSC)

Gronwall $\Rightarrow |y - x| \leq |y_0 - x_0| e^{k|t - t_0|}$ & this
implies uniqueness, continuity ▀

Rmk If $U = \mathbb{R}^n$ (so $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$) & $|f(x)| \leq M_0 + M_1|x|$,
then all solns defined for all time
Or if y_0 is such that soln $y(t)$ is known to stay
in cpt set A — then defined $\forall t$.

FLOW of a ODE $f \in C^1(U, \mathbb{R}^n)$
autonomous ODE $\dot{x} = f(x) \Rightarrow$ solutions $\phi(t, x)$
time t , IC x . Let $J(x) = \text{max int of existence.}$
 $\Omega \subset \mathbb{R} \times U, \Omega = \{(t, x) \mid t \in J(x)\}, \phi: \Omega \rightarrow U$
 ϕ is the flow of the ODE. (vcc field).
Often we write $\phi(t, x) := \phi_t(x)$

[Thm] $\phi_{s+t}(x) = \phi_s(\phi_t(x))$ - if one side is defined, so is the other.

(Pf) Mostly exercise. Do 1 case: $s, t > 0$ & $\phi_s(\phi_t(x))$ def
 $\Rightarrow t \in J(x)$ & $s \in J(\phi_t(x))$, say $J(x) = (\alpha, \beta]$,
 show $\beta > s+t$. Define $\gamma: (\alpha, s+t] \rightarrow W$ by

$$\gamma(r) = \begin{cases} \phi(r, x) & \alpha < r \leq t \\ \phi(r-t, \phi_t(x)) & t \leq r \leq t+s \end{cases}$$

Then γ solves $\therefore s+t \in J(x)$ etc... $\square$

LECTURE 14

10/11

[Thm] Ω is open & ϕ is cts.

(Pf) Given $(t_0, x_0) \in \Omega$ ($t_0 \geq 0$), get $J(x_0) > t_0$
 $\therefore x$ def on $[-\varepsilon, t_0 + \varepsilon]$ $\therefore \exists$ nbhd $V \ni x_0$ s.t.
 soln defined on $[-\varepsilon, t_0 + \varepsilon]$ i.e. $J(y) > t_0 \forall y \in V$.
 $\therefore (-\varepsilon, t_0 + \varepsilon) \times V \subset U$.

cts: V as above s.t. $\bar{V} \subset U$, K Lip const for $f|_A$,
 $A = [-\varepsilon, t_0 + \varepsilon] \times \bar{V}$, $M = \max \{ |f(x)| : x \in A \}$

Fix δ s.t. $\delta < \varepsilon$ & $B(x_0, \delta) \subset U$. Now $\Delta t, \Delta x_0 < \delta$
 $\Rightarrow |\phi(t_1, x_1) - \phi(t_0, x_0)| \leq |\phi(t_1, x_1) - \phi(t_1, x_0)| + | - |$
 $\leq \delta e^{K\delta} + (\rightarrow 0)$ $\square$

(Rmk)

In fact if $f \in C^r$ then ϕ is C^r ($r=1$ as before).

Given $(t, x_0) \in \Omega \exists V \ni x_0, V \subset U$ s.t. $t \times V \subset \Omega$, & $\phi_t: V \rightarrow U$

[Thm] $\phi_t(V) =: W$ is open, $\phi_{-t}: W \rightarrow V$. $\phi_{-t}\phi_t = \text{Id}_V$, $\phi_t\phi_{-t} = \text{Id}_W$

(Pf) $y \in \phi_t(V) \Rightarrow t \in J(x)$, $-t \in J(y)$

$V^* \supset V = \{z \in U \mid -t \in J(z)\}$ is open since Ω is
 also ϕ_{-t} is cts. So $V = (\phi_{-t})^{-1}(U)$ is open $\square$

STABILITY OF EQUILIBRIA

So far results have been very abstract, don't say much about a particular system.

Natural steps in studying a particular system $\dot{x} = f(x)$: (1)

- ① find fixed points & determine their stability
- ② find periodic orbits (if possible) & stability
- ③ determine what other types of orbits there are.

Def $\bar{x} \in U$ is an equilibrium (or fixed) point of (1)

(stationary pt, zero, singular pt) if $f(\bar{x}) = 0$.

Then $x(t) = \bar{x}$ is only soln through $\bar{x}$. (NEEDS Lipschitz)

Def

The linear part of f at $\bar{x}$ is $Df(\bar{x}) = \left[\frac{\partial f_i}{\partial x_j}(\bar{x}) \right]_{i,j} \in M_{n \times n}(\mathbb{R})$

$\bar{x}$ is a sink of f if $f(\bar{x}) = 0$ & all signals of $Df(\bar{x})$ have negative real parts, and a source if $f(\bar{x}) = 0$ & all signals of $Df(\bar{x})$ have pos. real parts, saddle if all $\text{Re} \lambda \neq 0$ & some $+$ & some $-$

Def

A f.p. $\bar{x}$ is stable if $\forall \epsilon > 0 \exists \delta > 0$ s.t.

$$(2) |x_0 - \bar{x}| < \delta \Rightarrow |\phi_t(x_0) - \bar{x}| < \epsilon \quad \forall t \geq 0.$$

It is asymptotically stable if (2) holds and also

$$(3) |x_0 - \bar{x}| < \delta \Rightarrow \phi_t(x_0) \rightarrow \bar{x} \text{ as } t \rightarrow \infty.$$

It is exponentially stable if $\exists C, \alpha > 0$ s.t.

$$(4) |x_0 - \bar{x}| < \delta \Rightarrow |\phi_t(x_0) - \bar{x}| \leq C e^{-\alpha t} \quad \forall t \geq 0.$$

It is unstable if not stable.

Remark * "unstable" $\neq$ "stable in backwards time"

* (4) $\Rightarrow$ (3) but (3) $\nRightarrow$ (2).



Exp St $\Rightarrow$ Asy St $\Rightarrow$ Lya Sta

$\Leftarrow$

$\Leftarrow$

Examples • A center for a linear system is Lyapunov stable but not asymptotically stable.

$$\dot{x} = -x^3 \Rightarrow -\frac{dx}{x^3} = dt \Rightarrow \frac{1}{2}x^{-2} = t + c$$

$$\Rightarrow x(t) = \sqrt{2(t+c)} \rightarrow 0 \text{ as } t \rightarrow \infty$$

but the convergence is subexponential.

LECTURE 15

10/16

Thm Sinks are exponentially stable

Prf Put $y = x - \bar{x}$, $g(y) = f(x - \bar{x})$, $A = Df(\bar{x}) = Dg(0)$

Choose $0 < b < b < |\operatorname{Re} \lambda| \forall$ eigenvals λ of A .

Let $Q \in M_{n \times n}$ be symmetric, pos. def, & solve Lyapunov's eqn $A^T Q + Q A = -I$.

(Take $B(t) = e^{tA^T} e^{tA}$, $Q = \int_0^\infty B(t) dt$)

Let $V(y) = y^T Q y$. Then

$$\dot{V}(y) = \dot{y}^T Q y + y^T Q \dot{y} = g(y)^T Q y + y^T Q g(y)$$

Write $g(y) = Ay + R(y)$, where $R(y) = o(|y|)$, then

$$\begin{aligned} \dot{V}(y) &= y^T A^T Q y + R(y)^T Q y + y^T Q A y + y^T Q R(y) \\ &= -|y|^2 + R(y)^T Q y + y^T Q R(y) \end{aligned}$$

For small $|y|$ this is $\leq -(1-\epsilon)|y|^2$

BETTER APPROACH: Choose basis in which $A = D + N$

with D diag & $\|N\| \leq \epsilon$ (in L^2 -norm for that basis). This can be done by #2(c) from HW1. Then if $\epsilon = \min(|\operatorname{Re} \lambda| - b)$, $\dim n$ times

$$\langle Ay, y \rangle = \langle Dy, y \rangle + \langle Ny, y \rangle \leq -a|y|^2 + \epsilon|y|^2 < -b|y|^2$$

By def of derivative, $|g(y) - Ay| = o(|y|) \therefore$ by Cauchy-Schwarz

$$\frac{\langle g(y) - Ay, y \rangle}{|y|^2} \rightarrow 0, \text{ so take } \delta \text{ with}$$

$$\langle g(y), y \rangle \leq -c|y|^2 \quad \forall y \in B(0, \delta)$$

Then $\frac{d}{dt}|y| = \frac{1}{|y|} \langle \dot{y}, y \rangle \leq -c|y|$ is defined $\forall t \geq 0$ & $|y| \leq e^{-ct}|y_0|$ 

What about initial conditions far from $\bar{x}$? Or signals with 0 real part? basin of $\bar{x}$ is $\{x \mid \phi_t x \rightarrow \bar{x}\}$

Did on 10/11

Let $V: U \rightarrow \mathbb{R}$ be C^1 & denote $\dot{V}(x) = \langle \nabla V(x), f(x) \rangle$,
then $\dot{V}(x) = \frac{d}{dt} V(\phi_t x) |_{t=0}$

[Thm 1] (Lyapunov) Let $\bar{x}$ be an eq pt & $V: W \rightarrow \mathbb{R}$ a cto
fn s.t. V is C^1 on $W \setminus \{\bar{x}\}$ & $(x \in W \subset U)$

(a) $V(\bar{x}) = 0, \quad V(x) > 0 \quad \forall x \neq \bar{x}$

(b) $\dot{V}(x) \leq 0 \quad \forall x \neq \bar{x}$

Then $\bar{x}$ is stable. If in addition

(c) $\dot{V}(x) < 0 \quad \forall x \neq \bar{x}$

then $\bar{x}$ is asymptotically stable.

Def P is positively invariant if $x \in P \Rightarrow \phi_t x$ defined & $\in P \quad \forall t \geq 0$.
entire orbit is $\{\phi_t x \mid t \in \mathbb{R}\}$

[Thm 2] (Lyap) $\bar{x}$ a f.p., V a Lyap fn on W .
Let $P \subset W$ be a nbhd of $\bar{x}$ closed in W . compact
sps P is pos inv & $\nexists$ entire orbit in $P \setminus \{\bar{x}\}$ on
which V is constant. Then $\bar{x}$ is asymp stable
& $P \subset \mathcal{B}(\bar{x})$.

[Rmk] Gives results w/o need to solve equations, but
finding a good Lyap fn can be an art. (Often an energy)

[Pf of 1] δ s.t. $B(\bar{x}, \delta) \subset W$, $\alpha = \min \{V(x) \mid x \in \partial B(\bar{x}, \delta)\} > 0$.
 $U_1 = \{x \in B(\bar{x}, \delta) \mid V(x) < \alpha\}$, so $x_0 \in U_1 \Rightarrow \phi_t x \in B(\bar{x}, \delta) \quad \forall t \geq 0$.

Now assume (C) & prove asymptotic stability. Suppose $t_n \rightarrow \infty$ is s.t. $x(t_n) \rightarrow z_0 \in B(\bar{x}, \delta)$. Then

$V(x(t)) \geq V(z_0) \forall t \geq 0$. If $z_0 \neq \bar{x}$, then we have $V(\phi_t z_0) < V(z_0) \forall t \geq 0$, & by continuity of V, ϕ_t , $V(\phi_t y) < V(z_0) \forall y \sim z_0$. $\square$

Pf of [2]. Fix $x_0 \in P$ & suppose $x(t) \rightarrow \bar{x}$, then $\exists a \neq \bar{x}, a \in P, x(t_n) \rightarrow a$.

$$\alpha := V(a) = \inf \{ V(x(t)) \mid t \geq 0 \}$$

ω -limit set

$$L = \{ a \in W \mid \exists t_n \rightarrow \infty, x(t_n) \rightarrow a \} =: \omega(x_0)$$

$L \subset P$ & $a \in L \Rightarrow \phi_t a$ defined & in $L \forall t \geq 0$.

Also defined & in L for every $t \leq 0$, since defined on $[-t_n, 0]$ as $\lim_k \phi_t(x(t_k))$ (valid for $t_k \geq t_n$)

$$\& x(t_n) \rightarrow a \Rightarrow x(t_n + s) \rightarrow \phi_s(a) \in L.$$

(ω -limit sets are pos- & neg-inv. & def. $\forall$ time).

$V(a) = \alpha \forall a \in L \Rightarrow V$ const on entire orbit $\square$

(Def'n) $\omega(x)$ & $\alpha(x) \leftarrow (t_n \rightarrow -\infty)$

ω -limit set & α -limit set.

Did on 10/11

Example

$$\dot{x} = -y - x^3$$

$$\dot{y} = x - y^3$$

$$Df(0) = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \lambda = \pm i$$

Linear part gives no information. Let $V(x, y) = x^2 + y^2$

$$\begin{aligned} \text{then } \dot{V} &= 2x\dot{x} + 2y\dot{y} = 2x(-y - x^3) + 2y(x - y^3) \\ &= -2xy - 2x^4 + 2xy - 2y^4 = -2(x^4 + y^4) < 0 \end{aligned}$$

so V is a strict Lyapunov fn on $\mathbb{R}^2$ & $(0, 0)$ is asymptotically stable with $B = \mathbb{R}^2$.

LECTURE 16 10/18

What about positive signals?

(A-S p. 187) ← but if there are errors

[Thm] If $\exists \lambda, \operatorname{Re} \lambda > 0$ then not stable.

Pf WLOG $\bar{x} = 0, \quad \mathbb{R}^n = E^u \oplus E^{cs}$

Let $a < \min(\operatorname{Re} \lambda) (> 0), \quad 0 < b < a$

$$A = Df(0)|_{E^u}, \quad B = Df(0)|_{E^{cs}}$$

Then $\exists$ norm s.t. $\langle Ax, x \rangle \geq a|x|^2 \quad \forall x \in E^u,$

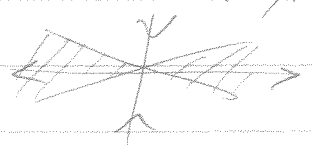
$-c|y|^2 \leq \langle By, y \rangle \leq b|y|^2 \quad \forall y \in E^{cs} \quad c > 0$

$$f(x, y) = (Ax + R(x, y), By + S(x, y)) \\ = (f_1, f_2),$$

$$z = (x, y), \quad Q(z) = (R, S)$$

$$\forall \varepsilon > 0 \exists \delta > 0 \text{ s.t. } |z| < \delta \Rightarrow |Q(z)| \leq \varepsilon |z|$$

Fix $\gamma > 0$, let $C_\gamma = \{(x, y) \in E^u \oplus E^{cs} \mid |y| \leq \gamma |x|\}$ be the unstable cone of width γ .



Lemma $\exists \delta > 0$ s.t. $\forall z \in C_\gamma \cap \overline{B(0, \delta)},$

① $\gamma^2 \langle x, f_1(x, y) \rangle - \langle y, f_2(x, y) \rangle > 0$ if $x \neq 0$.

② $\exists \alpha > 0$ with $\langle f(z), z \rangle \geq \alpha |z|^2$

Pf $\langle f(z), z \rangle = \langle Ax, x \rangle + \langle By, y \rangle + \langle Q(z), z \rangle$

$$\geq a|x|^2 - c|y|^2 - \varepsilon |z|^2$$

$$\geq (a - c\gamma^2)|x|^2 - \varepsilon |z|^2$$

$$|z|^2 \leq |x|^2 + |y|^2$$

②:

$$\geq \left(\frac{a - c\gamma^2}{1 + \gamma^2} - \varepsilon \right) |z|^2$$

$$\leq (1 + \gamma^2) |x|^2$$

$\geq \alpha |z|^2$ as long as γ, ε small enough

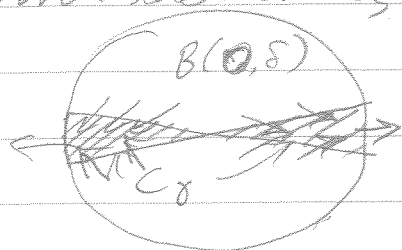
& $0 < \alpha < a$.

LHS of ① $= \gamma^2 \langle x, Ax \rangle - \langle y, By \rangle + \gamma^2 \langle x, R \rangle - \langle y, S \rangle \rightarrow \leq 2Kz, Q(z) \rangle$

$$\geq \gamma^2 a |x|^2 - b |y|^2 - 2\varepsilon |z|^2$$

$$\geq \left(\frac{a - b\gamma^2}{1 + \gamma^2} - 2\varepsilon \right) |z|^2 > 0 \text{ for small } \gamma, \varepsilon.$$

Given the Lemma, get the Thm as follows:



Let $g(x, y) = \frac{1}{2}(x^2|y|^2 - |y|^2)$
 then $C_\gamma = g^{-1}(0, \infty)$ & $g^{-1}(0) = \partial C_\gamma$.

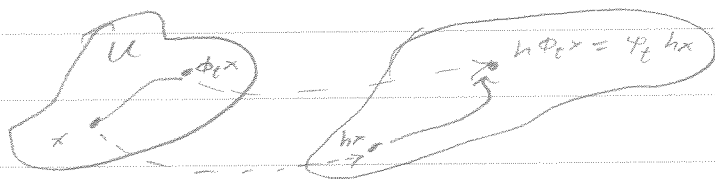
① $\Rightarrow \dot{g} = \langle \dot{g}, f \rangle = \langle x^2 \dot{x}, -y \rangle \cdot \langle f_1, f_2 \rangle = x^2 \langle \dot{x}, f_1 \rangle - \langle y, f_2 \rangle > 0$ in $B(0, \delta)$
 $\therefore$ cannot leave C_γ w/o first leaving $B(0, \delta)$

② $\Rightarrow \frac{d}{dt}|z|^2 \geq \alpha|z|^2 \Rightarrow |z|^2$ grows exponentially until leaves ball

Do THIS AFTER STABLE MFD

Changes of coordinates ^{can} often put things in a nicer form -
 e.g. JNF, change to basis of gen eigvec. What can we do in the nonlinear setting?

Def 2 flows $\phi_t, \psi_t: U \rightarrow U$ are topologically conjugate
 (C^0 -conj) if $\exists$ homeomorphism $h: U \rightarrow U$ s.t. $h \circ \phi_t = \psi_t \circ h \quad \forall t$.
 (also $\phi_t: U \rightarrow U, \psi_t: U' \rightarrow U', h: U \rightarrow U'$)



Prop h takes f.p. to f.p. & periodic orbs to per orbs

Pf $\phi_t x = x \Rightarrow (h x) = h \phi_t x = \psi_t(h x)$ $\square$
 (& period is preserved)

Def C^k -conjugacy: same, but require h, h^{-1} to be C^k diff, not just C^0 .