

Math 3321

Homogeneous Systems of Linear Differential Equations. Part II

University of Houston

Lecture 24

Outline

- 1 Homogeneous Systems of Linear Differential Equations
- 2 Homogeneous Systems - Complex Eigenvalues

Homogeneous Systems of Linear Differential Equations

Recall that a homogeneous systems of linear differential equations has the form

$$\begin{aligned}x_1' &= a_{11}(t)x_1 + a_{12}(t)x_2 + \cdots + a_{1n}(t)x_n(t) \\x_2' &= a_{21}(t)x_1 + a_{22}(t)x_2 + \cdots + a_{2n}(t)x_n(t) \\&\vdots \\x_n' &= a_{n1}(t)x_1 + a_{n2}(t)x_2 + \cdots + a_{nn}(t)x_n(t)\end{aligned}$$

or, in matrix form,

$$x' = A(t)x. \tag{H}$$

where

$$A(t) = \begin{pmatrix} a_{11}(t) & a_{12}(t) & \cdots & a_{1n}(t) \\ a_{21}(t) & a_{22}(t) & \cdots & a_{2n}(t) \\ \vdots & \vdots & \vdots & \\ a_{n1}(t) & a_{n2}(t) & \cdots & a_{nn}(t) \end{pmatrix}$$

Homogeneous Systems with Constant Coefficients

We stated the following results

Theorem

Consider the homogeneous system with constant coefficients

$$x' = Ax$$

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If $\lambda_1, \lambda_2, \dots, \lambda_k$ are **distinct** eigenvalues of A with corresponding eigenvectors v_1, v_2, \dots, v_k , then

$$x_1 = e^{\lambda_1 t} v_1, x_2 = e^{\lambda_2 t} v_2, \dots, x_k = e^{\lambda_k t} v_k$$

are **linearly independent solutions** of the system.

Homogeneous Systems with Constant Coefficients

Corollary

Consider the homogeneous system of n equations with constant coefficients

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Homogeneous Systems with Constant Coefficients

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Consider the homogeneous system of n equations with constant coefficients

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If $\lambda_1, \lambda_2, \dots, \lambda_n$ are n **distinct eigenvalues** of A with corresponding eigenvectors v_1, v_2, \dots, v_n , then

$$x_1 = e^{\lambda_1 t} v_1, x_2 = e^{\lambda_2 t} v_2, \dots, x_n = e^{\lambda_n t} v_n$$

is a fundamental set of solutions of the system and

$$x(t) = C_1 x_1 + C_2 x_2 + \dots + C_n x_n$$

is the general solution.

Homogeneous Systems with Constant Coefficients

Corollary

Consider the homogeneous system of n equations with constant coefficients

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If $\lambda_1, \lambda_2, \dots, \lambda_n$ are n **distinct eigenvalues** of A with corresponding eigenvectors v_1, v_2, \dots, v_n , then

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is a fundamental set of solutions of the system and

$$x(t) = C_1 x_1 + C_2 x_2 + \dots + C_n x_n$$

is the general solution.

This holds for both real and complex distinct eigenvalues.

Homogeneous Systems with Constant Coefficients

In the last lecture, I illustrated the case of n **real distinct eigenvalues**.

Homogeneous Systems with Constant Coefficients

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Homogeneous Systems with Constant Coefficients

In the last lecture, I illustrated the case of n **real distinct eigenvalues**.

In this lecture, I illustrated the case of n **real or complex distinct eigenvalues**.

In the next lecture, I will illustrate the case where there are **no n distinct eigenvalues**.

Homogeneous Systems - Complex Eigenvalues

Example 1: Find the general solution of

$$x' = \begin{pmatrix} -3 & -2 \\ 4 & 1 \end{pmatrix} x.$$

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$$\det(A - \lambda I) = \begin{vmatrix} -3 - \lambda & -2 \\ 4 & 1 - \lambda \end{vmatrix} = \lambda^2 + 2\lambda + 5.$$

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Solving the characteristic equation, we find the eigenvalues:

$$\lambda_1 = -1 + 2i, \quad \lambda_2 = -1 - 2i.$$

Homogeneous Systems - Complex Eigenvalues

To compute the eigenvectors, we examine the matrix

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For $\lambda_1 = -1 + 2i$: Solve

$$\left(\begin{array}{cc|c} -2 - 2i & -2 & 0 \\ 4 & 2 - 2i & 0 \end{array} \right) \rightarrow \left(\begin{array}{cc|c} -1 - i & -1 & 0 \\ 0 & 0 & 0 \end{array} \right)$$

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The solution set is:

$$x_2 = -(1 + i)x_1, \quad x_1 \text{ arbitrary}$$

Homogeneous Systems - Complex Eigenvalues

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Set $x_1 = 1$. Then, for $\lambda_1 = -1 + 2i$:

$$v_1 = \begin{pmatrix} 1 \\ -1 - i \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \end{pmatrix} + i \begin{pmatrix} 0 \\ -1 \end{pmatrix}.$$

Homogeneous Systems - Complex Eigenvalues

For $\lambda_2 = -1 - 2i$: Solve

$$\left(\begin{array}{cc|c} -2+2i & -2 & 0 \\ 4 & 2+2i & 0 \end{array} \right) \rightarrow \left(\begin{array}{cc|c} -1+i & -1 & 0 \\ 0 & 0 & 0 \end{array} \right)$$

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The solution set is:

$$x_2 = (-1 + i)x_1, \quad x_1 \text{ arbitrary}$$

Set $x_1 = 1$. Then, for $\lambda_1 = -1 - 2i$:

$$v_2 = \begin{pmatrix} 1 \\ -1 + i \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \end{pmatrix} - i \begin{pmatrix} 0 \\ -1 \end{pmatrix}.$$

Note that $v_2 = v_1^*$

Homogeneous Systems - Complex Eigenvalues

Hence we find the **solutions**:

$$u_1(t) = e^{(-1+2i)t} \left[\begin{pmatrix} 1 \\ -1 \end{pmatrix} + i \begin{pmatrix} 0 \\ -1 \end{pmatrix} \right]$$

$$u_2(t) = e^{(-1-2i)t} \left[\begin{pmatrix} 1 \\ -1 \end{pmatrix} - i \begin{pmatrix} 0 \\ -1 \end{pmatrix} \right]$$

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Problem: Complex-valued!

Homogeneous Systems - Complex Eigenvalues

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Problem: Complex-valued!

We want real-valued solutions. We will show that we can apply some algebra to derive a real-valued solution set.

Homogeneous Systems - Complex Eigenvalues

Using Euler's formula

$$\begin{aligned} u_1 &= e^{\lambda_1 t} v_1 = \\ &= e^{(-1+2i)t} \left[\begin{pmatrix} 1 \\ -1 \end{pmatrix} + i \begin{pmatrix} 0 \\ -1 \end{pmatrix} \right] \\ &= e^{-t} (\cos 2t + i \sin 2t) \left[\begin{pmatrix} 1 \\ -1 \end{pmatrix} + i \begin{pmatrix} 0 \\ -1 \end{pmatrix} \right] \\ &= e^{-t} \left[\cos 2t \begin{pmatrix} 1 \\ -1 \end{pmatrix} - \sin 2t \begin{pmatrix} 0 \\ -1 \end{pmatrix} \right] \\ &\quad + i e^{-t} \left[\cos 2t \begin{pmatrix} 0 \\ -1 \end{pmatrix} + \sin 2t \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right]. \end{aligned}$$

Homogeneous Systems - Complex Eigenvalues

Similarly,

$$\begin{aligned}u_2 &= e^{\lambda_2 t} v_2 \\&= e^{(-1-2i)t} \left[\begin{pmatrix} 1 \\ -1 \end{pmatrix} - i \begin{pmatrix} 0 \\ -1 \end{pmatrix} \right] \\&= e^{-t} (\cos 2t - i \sin 2t) \left[\begin{pmatrix} 1 \\ -1 \end{pmatrix} - i \begin{pmatrix} 0 \\ -1 \end{pmatrix} \right] \\&= e^{-t} \left[\cos 2t \begin{pmatrix} 1 \\ -1 \end{pmatrix} - \sin 2t \begin{pmatrix} 0 \\ -1 \end{pmatrix} \right] \\&\quad - i e^{-t} \left[\cos 2t \begin{pmatrix} 0 \\ -1 \end{pmatrix} + \sin 2t \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right].\end{aligned}$$

Homogeneous Systems - Complex Eigenvalues

Fundamental set:

$$\begin{aligned}x_1 &= \frac{u_1 + u_2}{2} \\ &= e^{-t} \left[\cos 2t \begin{pmatrix} 1 \\ -1 \end{pmatrix} - \sin 2t \begin{pmatrix} 0 \\ -1 \end{pmatrix} \right]\end{aligned}$$

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General solution:

$$\begin{aligned}x &= C_1 e^{-t} \left[\cos 2t \begin{pmatrix} 1 \\ -1 \end{pmatrix} - \sin 2t \begin{pmatrix} 0 \\ -1 \end{pmatrix} \right] \\&\quad + C_2 e^{-t} \left[\cos 2t \begin{pmatrix} 0 \\ -1 \end{pmatrix} + \sin 2t \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right]\end{aligned}$$

Homogeneous Systems - Complex Eigenvalues

Example 2: Find the general solution of

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Eigenvalues:

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The solution set is:

$$x_2 = \frac{1}{5}(-1 - 3i)x_1, \quad x_1 \text{ arbitrary}$$

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We have the eigenvectors:

$$\lambda_1 = 2 + 3i, \quad v_1 = \begin{pmatrix} 5 \\ -1 \end{pmatrix} - i \begin{pmatrix} 0 \\ 3 \end{pmatrix}$$

$$\lambda_2 = 2 - 3i, \quad v_2 = \begin{pmatrix} 5 \\ -1 \end{pmatrix} + i \begin{pmatrix} 0 \\ 3 \end{pmatrix}$$

Homogeneous Systems - Complex Eigenvalues

As we saw in the example above, we can write a real solution where the real part of the eigenvalue determines the exponent of the exponential and the imaginary part gives the periodicity of the trig function:

$$\lambda = a \pm ib \Rightarrow e^{at}, \cos(bt), \sin(bt)$$

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Hence we have the **Fundamental set**:

$$x_1 = e^{2t} \left[\cos 3t \begin{pmatrix} -1 \\ 2 \end{pmatrix} - \sin 3t \begin{pmatrix} 3 \\ 0 \end{pmatrix} \right]$$

$$x_2 = e^{2t} \left[\cos 3t \begin{pmatrix} 3 \\ 0 \end{pmatrix} + \sin 3t \begin{pmatrix} -1 \\ 2 \end{pmatrix} \right]$$

Homogeneous Systems - Complex Eigenvalues

The **General Solution** of the homogeneous system of linear differential equations is:

$$\begin{aligned} x = & C_1 e^{2t} \left[\cos 3t \begin{pmatrix} -1 \\ 2 \end{pmatrix} - \sin 3t \begin{pmatrix} 3 \\ 0 \end{pmatrix} \right] \\ & + C_2 e^{2t} \left[\cos 3t \begin{pmatrix} 3 \\ 0 \end{pmatrix} + \sin 3t \begin{pmatrix} -1 \\ 2 \end{pmatrix} \right] \end{aligned}$$

Homogeneous Systems - Complex Eigenvalues

Summary: Method to find the solution of $x' = Ax$, where A $n \times n$ is a constant matrix, when $a + ib$, $a - ib$ are complex eigenvalues.

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1. Compute the eigenvectors $\vec{\alpha} + i \vec{\beta}$, $\vec{\alpha} - i \vec{\beta}$.

Homogeneous Systems - Complex Eigenvalues

Summary: Method to find the solution of $x' = Ax$, where A $n \times n$ is a constant matrix, when $a + ib$, $a - ib$ are complex eigenvalues.

1. Compute the eigenvectors $\vec{\alpha} + i \vec{\beta}$, $\vec{\alpha} - i \vec{\beta}$.
2. Write the independent (complex-valued) solutions:

$$u_1 = e^{(a+ib)t} \begin{pmatrix} \vec{\alpha} + i \vec{\beta} \end{pmatrix} \quad u_2 = e^{(a-ib)t} \begin{pmatrix} \vec{\alpha} - i \vec{\beta} \end{pmatrix}$$

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3. Write corresponding real-valued solutions:

$$x_1 = e^{at} \begin{bmatrix} \cos bt \vec{\alpha} - \sin bt \vec{\beta} \end{bmatrix} \quad x_2 = e^{at} \begin{bmatrix} \cos bt \vec{\beta} + \sin bt \vec{\alpha} \end{bmatrix}$$

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4. Write the general solution:

$$x = C_1 e^{at} \begin{bmatrix} \cos bt \vec{\alpha} - \sin bt \vec{\beta} \end{bmatrix} + C_2 e^{at} \begin{bmatrix} \cos bt \vec{\beta} + \sin bt \vec{\alpha} \end{bmatrix}$$

Homogeneous Systems - Complex Eigenvalues

Example 3: Determine a fundamental set of solution vectors of

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$$\begin{aligned} \det(A - \lambda I) &= \begin{vmatrix} 1 - \lambda & -4 & -1 \\ 3 & 2 - \lambda & 3 \\ 1 & 1 & 3 - \lambda \end{vmatrix} = \\ & -\lambda^3 + 6\lambda^2 - 21\lambda + 26 = -(\lambda - 2)(\lambda^2 - 4\lambda + 13). \end{aligned}$$

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The eigenvalues are:

$$\lambda_1 = 2, \quad \lambda_2 = 2 + 3i, \quad \lambda_3 = 2 - 3i.$$

Homogeneous Systems - Complex Eigenvalues

We examine the matrix

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For $\lambda_1 = 2$, we solve

$$\left(\begin{array}{ccc|c} -1 & -4 & -1 & 0 \\ 3 & 0 & 3 & 0 \\ 1 & 1 & 1 & 0 \end{array} \right) \rightarrow \left(\begin{array}{ccc|c} -1 & -4 & -1 & 0 \\ 0 & -12 & 0 & 0 \\ 0 & -4 & 0 & 0 \end{array} \right) \rightarrow \left(\begin{array}{ccc|c} 1 & 4 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

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Hence we have the solution $x_2 = 0$, $x_1 = -x_2$.

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Hence we have the solution $x_2 = 0$, $x_1 = -x_2$.

Choosing $x_2 = 1$, we obtain the eigenvector:

$$v_1 = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$$

Homogeneous Systems - Complex Eigenvalues

The eigenvalue $\lambda_1 = 2$ and the eigenvector $v_1 = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$ are associated with solution vector:

$$x_1 = e^{2t} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix},$$

Homogeneous Systems - Complex Eigenvalues

For $\lambda_2 = 2 + 3i$ we solve

$$\left(\begin{array}{ccc|c} -1-3i & -4 & -1 & 0 \\ 3 & -3i & 3 & 0 \\ 1 & 1 & 1-3i & 0 \end{array} \right) \rightarrow \left(\begin{array}{ccc|c} 1 & -i & 1 & 0 \\ 1 & 1 & 1-3i & 0 \\ -1-3i & -4 & -1 & 0 \end{array} \right) \rightarrow$$

Homogeneous Systems - Complex Eigenvalues

For $\lambda_2 = 2 + 3i$ we solve

$$\begin{pmatrix} -1-3i & -4 & -1 & \left| \begin{array}{c} 0 \\ 0 \\ 0 \end{array} \right. \\ 3 & -3i & 3 & \\ 1 & 1 & 1-3i & \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -i & 1 & \left| \begin{array}{c} 0 \\ 0 \\ 0 \end{array} \right. \\ 1 & 1 & 1-3i & \\ -1-3i & -4 & -1 & \end{pmatrix} \rightarrow$$
$$\begin{pmatrix} 1 & -i & 1 & \left| \begin{array}{c} 0 \\ 0 \\ 0 \end{array} \right. \\ 0 & 1+i & -3i & \\ 0 & -1-i & 3i & \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -i & 1 & \left| \begin{array}{c} 0 \\ 0 \\ 0 \end{array} \right. \\ 0 & 1+i & -3i & \\ 0 & 0 & 0 & \end{pmatrix} \rightarrow$$
$$\begin{pmatrix} 1 & -i & 1 & \left| \begin{array}{c} 0 \\ 0 \\ 0 \end{array} \right. \\ 0 & 1 & -\frac{3}{2}(1+i) & \\ 0 & 0 & 0 & \end{pmatrix}$$

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$$\begin{pmatrix} 1 & -i & 1 & \left| 0 \right. \\ 0 & 1+i & -3i & \left| 0 \right. \\ 0 & -1-i & 3i & \left| 0 \right. \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -i & 1 & \left| 0 \right. \\ 0 & 1+i & -3i & \left| 0 \right. \\ 0 & 0 & 0 & \left| 0 \right. \end{pmatrix} \rightarrow$$
$$\begin{pmatrix} 1 & -i & 1 & \left| 0 \right. \\ 0 & 1 & -\frac{3}{2}(1+i) & \left| 0 \right. \\ 0 & 0 & 0 & \left| 0 \right. \end{pmatrix}$$

Hence, the solution set is:

$$u_1 = \left(-\frac{5}{2} + \frac{3}{2}i\right) u_3, \quad u_2 = \left(\frac{3}{2} + \frac{3}{2}i\right) u_3, \quad u_3 \text{ arbitrary}$$

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Hence the eigenvectors v_2 and v_3 corresponding to the eigenvalues λ_2 and λ_3 are

$$v_2 = \begin{pmatrix} -5 + 3i \\ 3 + 3i \\ 2 \end{pmatrix} = \begin{pmatrix} -5 \\ 3 \\ 2 \end{pmatrix} + i \begin{pmatrix} 3 \\ 3 \\ 0 \end{pmatrix}$$

and

$$v_3 = \begin{pmatrix} -5 - 3i \\ 3 - 3i \\ 2 \end{pmatrix} = \begin{pmatrix} -5 \\ 3 \\ 2 \end{pmatrix} - i \begin{pmatrix} 3 \\ 3 \\ 0 \end{pmatrix}$$

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Therefore the solutions associated with the eigenvectors v_2 and v_3 are

$$z_1 = e^{(2+3i)t} \left[\begin{pmatrix} -5 \\ 3 \\ 2 \end{pmatrix} + i \begin{pmatrix} 3 \\ -3 \\ 0 \end{pmatrix} \right]$$

and

$$z_2 = e^{(2-3i)t} \left[\begin{pmatrix} -5 \\ 3 \\ 2 \end{pmatrix} - i \begin{pmatrix} 3 \\ -3 \\ 0 \end{pmatrix} \right]$$

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As we saw above, we can convert the complex solutions into the real solutions :

$$x_2 = e^{2t} \left[\cos 3t \begin{pmatrix} -5 \\ 3 \\ 2 \end{pmatrix} - \sin 3t \begin{pmatrix} 3 \\ -3 \\ 0 \end{pmatrix} \right]$$

and

$$x_3 = e^{2t} \left[\cos 3t \begin{pmatrix} 3 \\ -3 \\ 0 \end{pmatrix} + \sin 3t \begin{pmatrix} -5 \\ 3 \\ 2 \end{pmatrix} \right]$$

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Combining all solution vectors, we have the fundamental set of solution vectors:

$$x_1 = e^{2t} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix},$$

$$x_2 = e^{2t} \left[\cos 3t \begin{pmatrix} -5 \\ 3 \\ 2 \end{pmatrix} - \sin 3t \begin{pmatrix} 3 \\ -3 \\ 0 \end{pmatrix} \right],$$

$$x_3 = e^{2t} \left[\cos 3t \begin{pmatrix} 3 \\ -3 \\ 0 \end{pmatrix} + \sin 3t \begin{pmatrix} -5 \\ 3 \\ 2 \end{pmatrix} \right].$$

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Combining all solution vectors, we have the fundamental set of solution vectors:

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$$x_3 = e^{2t} \left[\cos 3t \begin{pmatrix} 3 \\ -3 \\ 0 \end{pmatrix} + \sin 3t \begin{pmatrix} -5 \\ 3 \\ 2 \end{pmatrix} \right].$$

General solution:

$$x = C_1 x_1 + C_2 x_2 + C_3 x_3$$