# Math 2331 - Linear Algebra <br> 4.5 The Dimension of a Vector Space 

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### 4.5 The Dimension of a Vector Space

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## The Dimension of a Vector Space: Theorems

## Theorem (9)

If a vector space $V$ has a basis $\beta=\left\{\mathbf{b}_{1}, \ldots, \mathbf{b}_{n}\right\}$, then any set in $V$ containing more than $n$ vectors must be linearly dependent.

Proof: Suppose $\left\{\mathbf{u}_{1}, \ldots, \mathbf{u}_{p}\right\}$ is a set of vectors in $V$ where $p>n$. Then the coordinate vectors $\left\{\left[\mathbf{u}_{1}\right]_{\beta}, \cdots,\left[\mathbf{u}_{p}\right]_{\beta}\right\}$ are in $\mathbf{R}^{n}$.

Since $p>n,\left\{\left[\mathbf{u}_{1}\right]_{\beta}, \cdots,\left[\mathbf{u}_{p}\right]_{\beta}\right\}$ are linearly dependent and therefore $\left\{\mathbf{u}_{1}, \ldots, \mathbf{u}_{p}\right\}$ are linearly dependent.

## The Dimension of a Vector Space: Theorems (cont.)

## Theorem (10)

If a vector space $V$ has a basis of $n$ vectors, then every basis of $V$ must consist of $n$ vectors.

Proof: Suppose $\beta_{1}$ is a basis for $V$ consisting of exactly $n$ vectors. Now suppose $\beta_{2}$ is any other basis for $V$. By the definition of a basis, we know that $\beta_{1}$ and $\beta_{2}$ are both linearly independent sets.

By Theorem 9, if $\beta_{1}$ has more vectors than $\beta_{2}$, then $\qquad$ is a linearly dependent set (which cannot be the case).

Again by Theorem 9, if $\beta_{2}$ has more vectors than $\beta_{1}$, then is a linearly dependent set (which cannot be the case).

Therefore $\beta_{2}$ has exactly n vectors also.

## The Dimension of a Vector Space: Definition

## Dimension of a Vector Space

If $V$ is spanned by a finite set, then $V$ is said to be finite-dimensional, and the dimension of $V$, written as $\operatorname{dim} V$, is the number of vectors in a basis for $V$. The dimension of the zero vector space $\{\mathbf{0}\}$ is defined to be 0 . If $V$ is not spanned by a finite set, then $V$ is said to be infinite-dimensional.

## Example

The standard basis for $\mathbf{P}_{3}$ is $\{\quad\}$. So $\operatorname{dim}$
$P_{3}=$ $\qquad$

$$
\text { In general, } \operatorname{dim} \mathbf{P}_{n}=n+1 .
$$

## Example

The standard basis for $\mathbf{R}^{n}$ is $\left\{\mathbf{e}_{1}, \ldots, \mathbf{e}_{n}\right\}$ where $\mathbf{e}_{1}, \ldots, \mathbf{e}_{n}$ are the columns of $I_{n}$. So, for example, $\operatorname{dim} \mathbf{R}^{3}=3$.

## The Dimension of a Vector Space: Example

## Example

Find a basis and the dimension of the subspace

$$
W=\left\{\left[\begin{array}{c}
a+b+2 c \\
2 a+2 b+4 c+d \\
b+c+d \\
3 a+3 c+d
\end{array}\right]: a, b, c, d \text { are real }\right\}
$$

Solution: Since

$$
\left[\begin{array}{c}
a+b+2 c \\
2 a+2 b+4 c+d \\
b+c+d \\
3 a+3 c+d
\end{array}\right]=a\left[\begin{array}{l}
1 \\
2 \\
0 \\
3
\end{array}\right]+b\left[\begin{array}{l}
1 \\
2 \\
1 \\
0
\end{array}\right]+c\left[\begin{array}{l}
2 \\
4 \\
1 \\
3
\end{array}\right]+d\left[\begin{array}{l}
0 \\
1 \\
1 \\
1
\end{array}\right]
$$

## The Dimension of a Vector Space: Example (cont.)

$$
W=\operatorname{span}\left\{\mathbf{v}_{1}, \mathbf{v}_{2}, \mathbf{v}_{3}, \mathbf{v}_{4}\right\}
$$

where $\mathbf{v}_{1}=\left[\begin{array}{l}1 \\ 2 \\ 0 \\ 3\end{array}\right], \mathbf{v}_{2}=\left[\begin{array}{l}1 \\ 2 \\ 1 \\ 0\end{array}\right], \mathbf{v}_{3}=\left[\begin{array}{l}2 \\ 4 \\ 1 \\ 3\end{array}\right], \mathbf{v}_{4}=\left[\begin{array}{l}0 \\ 1 \\ 1 \\ 1\end{array}\right]$.

- Note that $\mathbf{v}_{3}$ is a linear combination of $\mathbf{v}_{1}$ and $\mathbf{v}_{2}$, so by the Spanning Set Theorem, we may discard $\mathbf{v}_{3}$.
- $\mathbf{v}_{4}$ is not a linear combination of $\mathbf{v}_{1}$ and $\mathbf{v}_{2}$. So $\left\{\mathbf{v}_{1}, \mathbf{v}_{2}, \mathbf{v}_{4}\right\}$ is a basis for $W$. Also, $\operatorname{dim} W=\ldots$.-.


## Dimensions of Subspaces of $R^{3}$

## Example (Dimensions of subspaces of $R^{3}$ )

(1) 0 -dimensional subspace contains only the zero vector $\mathbf{0}=(0,0,0)$.
(2) 1-dimensional subspaces. $\operatorname{Span}\{\mathbf{v}\}$ where $\mathbf{v} \neq \mathbf{0}$ is in $\mathbf{R}^{3}$.
(3) These subspaces are $\qquad$ through the origin.
(4) 2-dimensional subspaces. $\operatorname{Span}\{\mathbf{u}, \mathbf{v}\}$ where $\mathbf{u}$ and $\mathbf{v}$ are in $\mathbf{R}^{3}$ and are not multiples of each other.
(5) These subspaces are through the origin.
(6) 3-dimensional subspaces. $\operatorname{Span}\{\mathbf{u}, \mathbf{v}, \mathbf{w}\}$ where $\mathbf{u}, \mathbf{v}, \mathbf{w}$ are linearly independent vectors in $\mathbf{R}^{3}$. This subspace is $\mathbf{R}^{3}$ itself because the columns of $A=\left[\begin{array}{lll}\mathbf{u} & \mathbf{v} & \mathbf{w}\end{array}\right]$ span $\mathbf{R}^{3}$ according to the IMT.

## Dimensions of Subspaces: Theorem

## Theorem (11)

Let $H$ be a subspace of a finite-dimensional vector space V. Any linearly independent set in $H$ can be expanded, if necessary, to a basis for $H$. Also, $H$ is finite-dimensional and

$$
\operatorname{dim} H \leq \operatorname{dim} V
$$

## Example

Let $H=\operatorname{span}\left\{\left[\begin{array}{l}1 \\ 0 \\ 0\end{array}\right],\left[\begin{array}{l}1 \\ 1 \\ 0\end{array}\right]\right\}$. Then $H$ is a subspace of $\mathbf{R}^{3}$ and
$\operatorname{dim} H<\operatorname{dim} \mathbf{R}^{3}$. We could expand the spanning set

$$
\left\{\left[\begin{array}{l}
1 \\
0 \\
0
\end{array}\right],\left[\begin{array}{l}
1 \\
1 \\
0
\end{array}\right]\right\} \text { to }\left\{\left[\begin{array}{l}
1 \\
0 \\
0
\end{array}\right],\left[\begin{array}{l}
1 \\
1 \\
0
\end{array}\right],\left[\begin{array}{l}
0 \\
0 \\
1
\end{array}\right]\right\} \text { for a basis of } \mathbf{R}^{3} .
$$

## The Basis Theorem

## Theorem (12 The Basis Theorem)

Let $V$ be a $p$ - dimensional vector space, $p \geq 1$. Any linearly independent set of exactly $p$ vectors in $V$ is automatically a basis for $V$. Any set of exactly $p$ vectors that spans $V$ is automatically a basis for $V$.

## Example

Show that $\left\{t, 1-t, 1+t-t^{2}\right\}$ is a basis for $\mathbf{P}_{2}$.
Solution: Let

$$
\mathbf{v}_{1}=t, \quad \mathbf{v}_{2}=1-t, \quad \mathbf{v}_{3}=1+t-t^{2} \quad \text { and } \quad \beta=\left\{1, t, t^{2}\right\}
$$

Corresponding coordinate vectors

$$
\left[\mathbf{v}_{1}\right]_{\beta}=\left[\begin{array}{l}
0 \\
1 \\
0
\end{array}\right], \quad\left[\mathbf{v}_{2}\right]_{\beta}=\left[\begin{array}{c}
1 \\
-1 \\
0
\end{array}\right], \quad\left[\mathbf{v}_{3}\right]_{\beta}=\left[\begin{array}{c}
1 \\
1 \\
-1
\end{array}\right]
$$

## The Basis Theorem (cont.)

$\left[\mathbf{v}_{2}\right]_{\beta}$ is not a multiple of $\left[\mathbf{v}_{1}\right]_{\beta}$
$\left[\mathbf{v}_{3}\right]_{\beta}$ is not a linear combination of $\left[\mathbf{v}_{1}\right]_{\beta}$ and $\left[\mathbf{v}_{2}\right]_{\beta}$
$\Longrightarrow\left\{\left[\mathbf{v}_{1}\right]_{\beta},\left[\mathbf{v}_{2}\right]_{\beta},\left[\mathbf{v}_{3}\right]_{\beta}\right\}$ is linearly independent and therefore $\left\{\mathbf{v}_{1}, \mathbf{v}_{2}, \mathbf{v}_{3}\right\}$ is also linearly independent.

Since $\operatorname{dim} \mathbf{P}_{2}=3,\left\{\mathbf{v}_{1}, \mathbf{v}_{2}, \mathbf{v}_{3}\right\}$ is a basis for $\mathbf{P}_{2}$ according to The Basis Theorem.

## Dimensions of $\operatorname{Col} A$ and $\operatorname{Nul} A$ : Example

Recall our techniques to find basis sets for column spaces and null spaces.

## Example

Suppose $A=\left[\begin{array}{llll}1 & 2 & 3 & 4 \\ 2 & 4 & 7 & 8\end{array}\right]$. Find $\operatorname{dim} \operatorname{Col} A$ and $\operatorname{dim} \operatorname{Nul} A$.
Solution

$$
\left[\begin{array}{llll}
1 & 2 & 3 & 4 \\
2 & 4 & 7 & 8
\end{array}\right] \sim\left[\begin{array}{llll}
1 & 2 & 3 & 4 \\
0 & 0 & 1 & 0
\end{array}\right]
$$

So

$$
\{[\quad],[\quad]\}
$$

is a basis for $\operatorname{Col} A$ and $\operatorname{dim} \operatorname{Col} A=2$.

## Dimensions of $\operatorname{Col} A$ and Nul $A$ : Example (cont.)

Now solve $A \mathbf{x}=\mathbf{0}$ by row-reducing the corresponding augmented matrix. Then we arrive at

$$
\begin{gathered}
{\left[\begin{array}{lllll}
1 & 2 & 3 & 4 & 0 \\
2 & 4 & 7 & 8 & 0
\end{array}\right] \sim \cdots \sim\left[\begin{array}{lllll}
1 & 2 & 0 & 4 & 0 \\
0 & 0 & 1 & 0 & 0
\end{array}\right]} \\
x_{1}=-2 x_{2}-4 x_{4} \\
x_{3}=0 \\
{\left[\begin{array}{l}
x_{1} \\
x_{2} \\
x_{3} \\
x_{4}
\end{array}\right]=x_{2}\left[\begin{array}{r}
-2 \\
1 \\
0 \\
0
\end{array}\right]+x_{4}\left[\begin{array}{r}
-4 \\
0 \\
0 \\
1
\end{array}\right]}
\end{gathered}
$$

## Dimensions of $\operatorname{Col} A$ and Nul A: Example (cont.)

So

$$
\left\{\left[\begin{array}{r}
-2 \\
1 \\
0 \\
0
\end{array}\right],\left[\begin{array}{r}
-4 \\
0 \\
0 \\
1
\end{array}\right]\right\}
$$

is a basis for $\operatorname{Nul} A$ and $\operatorname{dim} \operatorname{Nul} A=2$.
Note

$$
\operatorname{dim} \operatorname{Col} A=\text { number of pivot columns of } A
$$

$\operatorname{dim} \operatorname{Nul} A=$ number of free variables of $A$.

