## Advanced Linear AlgebraQuiz 1Math 4377 / 6308 (Spring 2015) February 10, 2015

Name and ID:  $\_$ 

- 10 points 1. Mark each statement True or False. Justify each answer.
  - (1) A vector is an arrow in three-dimensional space.
  - (2) A subset H of a vector space V is a subspace of V if the zero vector is in H.
  - (3) A subspace is also a vector space.
  - (4) If **u** is a vector in a vector space V, then (-1)**u** is the same as the negative of **u**.
  - (5) A vector space is also a subspace.
  - (6)  $\mathbb{R}^2$  is a subspace of  $\mathbb{R}^3$ .
  - (7) If f is a function in the vector space V of all real-valued functions on  $\mathbb{R}$  and if f(t) = 0 for some t, then f is the zero vector in V.
  - (8) If S is a linearly dependent set, then each vector in S is a linear combination of other vectors in S.
  - (9) Any set containing the zero vector is linearly dependent.
  - (10) Subsets of linearly dependent sets are linearly dependent.
- 15 points 2. Let W be the set of all vectors of the form  $\begin{pmatrix} a+2b+4c\\b+2c\\-a+3b+6c \end{pmatrix}$  where a, b and c are arbitrary.
  - a. Find vectors  $\mathbf{u}_1$ ,  $\mathbf{u}_2$ , and  $\mathbf{u}_3$  such that  $W = \mathbf{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ . Why does this show that W is a subspace of  $\mathbb{R}^3$ ?
  - b. Find a basis for W and state the dimension of W.
  - 15 points 3. Suppose  $\mathbf{u}_1, \dots, \mathbf{u}_p$  and  $\mathbf{v}_1, \dots, \mathbf{v}_q$  are vectors in a vector space V, and let

$$H = \operatorname{span}\{\mathbf{u}_1, \cdots, \mathbf{u}_p\}, \quad K = \operatorname{span}\{\mathbf{v}_1, \cdots, \mathbf{v}_q\}.$$

Show that  $H + K = \operatorname{span}{\{\mathbf{u}_1, \cdots, \mathbf{u}_p, \mathbf{v}_1, \cdots, \mathbf{v}_q\}}$ .

## Name and ID: \_ Problem 1.

- (1) False. A vector is an element of a vector space.
- (2) False. A subset H of a vector space V is a subspace of V if (a) the zero vector is in H, (b) H is closed under vector addition, and (c) H is closed under scalar multiplication.
- (3) True. A subspace is also a vector space in its own right.
- (4) True. If **u** is a vector in a vector space V, then, by Theorem 1.2,  $(-1)\mathbf{u} = -(1\mathbf{u}) = -\mathbf{u}$ .
- (5) True. A vector space is also a subspace of itself.
- (6) False.  $\mathbb{R}^2$  is a vector space, but is not a subset of  $\mathbb{R}^3$ .
- (7) False. The function  $f_0$  such that  $f_0(t) = 0$  for ANY t is the UNIQUE zero vector  $f_0$  in V.
- (8) Fasle.  $S = \{v, 0\}$  with  $v \neq 0$  is linear dependent, but v is not a linear combination of 0. If S is a linearly dependent set of two or more vectors, then AT LEAST ONE of the vectors in S is a linear combination of other vectors in S.
- (9) True. Refer to lecture notes for Section 1.5.
- (10) Fasle.  $S = \{v, 0\}$  with  $v \neq 0$  is linear dependent, but subset  $\{v\}$  is not. Refer to Theorem 1.6 in Section 1.5.

## Problem 2.

a. Note that

$$\begin{pmatrix} a+2b+4c\\b+2c\\-a+3b+6c \end{pmatrix} = a \begin{pmatrix} 1\\0\\-1 \end{pmatrix} + b \begin{pmatrix} 2\\1\\3 \end{pmatrix} + c \begin{pmatrix} 4\\2\\6 \end{pmatrix}$$

We have

$$W = \left\{ \begin{pmatrix} a+2b+4c\\b+2c\\-a+3b+6c \end{pmatrix}, \quad a,b,c \in \mathbb{R} \right\} = \operatorname{span}\{\mathbf{u}_1,\mathbf{u}_2,\mathbf{u}_3\},$$

where

$$\mathbf{u}_1 = \begin{pmatrix} 1\\0\\-1 \end{pmatrix}, \quad \mathbf{u}_2 = \begin{pmatrix} 2\\1\\3 \end{pmatrix}, \quad \mathbf{u}_3 = \begin{pmatrix} 4\\2\\6 \end{pmatrix}.$$

W is a subspace of  $\mathbb{R}^3$  since  $\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3$  are in  $\mathbb{R}^3$ , and by Theorem 1.5,  $\mathbf{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$  is a subspace of  $\mathbb{R}^3$ 

b. By row reduction,

$$(\mathbf{u}_1 \, \mathbf{u}_2, \mathbf{u}_3) = \begin{pmatrix} 1 & 2 & 4 \\ 0 & 1 & 2 \\ -1 & 3 & 6 \end{pmatrix} \sim \begin{pmatrix} 1 & 2 & 4 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{pmatrix}$$

The pivot columns  $\{\mathbf{u}_1, \mathbf{u}_2\}$  form a basis for W and  $\dim(W) = 2$ .

Name and ID: \_\_\_\_\_\_ **Problem 3.** (a)  $H + K \subseteq \operatorname{span}\{\mathbf{u}_1, \cdots, \mathbf{u}_p, \mathbf{v}_1, \cdots, \mathbf{v}_q\}$ : For any  $\mathbf{u} \in H = \operatorname{span}\{\mathbf{u}_1, \cdots, \mathbf{u}_p\}$  and  $\mathbf{v} \in K = \operatorname{span}\{\mathbf{v}_1, \cdots, \mathbf{v}_q\}$ , there exist  $c_1, \cdots, c_p$  and  $d_1, \cdots, d_q$  such that

$$\mathbf{u} = c_1 \mathbf{u}_1 + \dots + c_p \mathbf{u}_p, \quad \mathbf{v} = d_1 \mathbf{v}_1 + \dots + d_q \mathbf{v}_q.$$

Then

$$\mathbf{u} + \mathbf{v} = c_1 \mathbf{u}_1 + \dots + c_p \mathbf{u}_p + d_1 \mathbf{v}_1 + \dots + d_q \mathbf{v}_q \in \mathbf{span} \{\mathbf{u}_1, \dots, \mathbf{u}_p, \mathbf{v}_1, \dots, \mathbf{v}_q\}$$

(b)  $\operatorname{span}{\mathbf{u}_1, \cdots, \mathbf{u}_p, \mathbf{v}_1, \cdots, \mathbf{v}_q} \subseteq H + K$ : For any  $\mathbf{w} \in \operatorname{span}{\mathbf{u}_1, \cdots, \mathbf{u}_p, \mathbf{v}_1, \cdots, \mathbf{v}_q}$ , we have

$$\mathbf{w} = (c_1\mathbf{u}_1 + \dots + c_p\mathbf{u}_p) + (d_1\mathbf{v}_1 + \dots + d_q\mathbf{v}_q) \in H + K$$

When you finish this exam, you should go back and reexamine your work for any errors that you may have made.