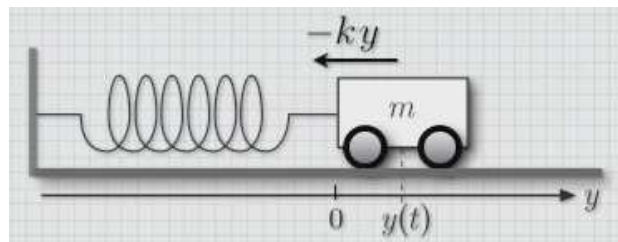


Section 3.6

Simple Applications of Second Order Linear Differential Equations

Spring Mass Systems

Part I: No damping and no external forces - **Simple Harmonic Motion.**



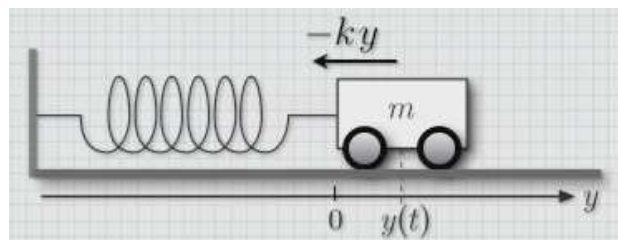
Hooke's law states that for small displacements, the restoring force is proportional to the displacement.

$$m y'' + k y = 0.$$

$$\omega = \sqrt{k/m}$$

Terms: Period, frequency, amplitude, phase shift.

Part II: Damping, but no external forces.



$$m y'' = -k y - \delta y'$$

$$m y'' + \delta y' + k y = 0$$

Terms: Overdamped, underdamped, critically damped.

The Forced System

$$m y'' + \delta y' + k y = F(t)$$

Special Case: $F(t) = F_0 \cos(\gamma t)$

Terms: Natural frequency = $\omega/(2\pi)$, Applied frequency = $\gamma/(2\pi)$.

Higher Order Linear Differential Equations

$$y^{(n)} + p_{n-1}(x)y^{(n-1)} + p_{n-2}(x)y^{(n-2)} + \cdots + p_1(x)y' + p_0(x)y = f(x)$$

$$y^{(n)} + p_{n-1}(x)y^{(n-1)} + p_{n-2}(x)y^{(n-2)} + \cdots + p_1(x)y' + p_0(x)y = 0$$

$$L[y(x)] = y^{(n)}(x) + p_{n-1}(x)y^{(n-1)}(x) + \cdots + p_1(x)y'(x) + p_0(x)y(x)$$

Terms: Nonhomogeneous equation, homogeneous equation, linear differential operator, number of solutions for the homogeneous and nonhomogeneous equations.

Initial Value Problem

$$y^{(n)} + p_{n-1}(x)y^{(n-1)} + p_{n-2}(x)y^{(n-2)} + \cdots + p_1(x)y' + p_0(x)y = f(x);$$

$$y(a) = \alpha_0, y'(a) = \alpha_1, \dots, y^{(n-1)}(a) = \alpha_{n-1}$$

Uniqueness Theorem:

Finding the General Solution to the Homogeneous Equation

$$y^{(n)} + p_{n-1}(x)y^{(n-1)} + p_{n-2}(x)y^{(n-2)} + \cdots + p_1(x)y' + p_0(x)y = 0$$

Terms: Linear combination of solutions, linear independence, Wronskian, fundamental set of solutions.

**Finding the General Solution to the *Constant Coefficient*
Homogeneous Equation**

$$y^{(n)} + a_{n-1}y^{(n-1)} + a_{n-2}y^{(n-2)} + \cdots + a_1y' + a_0y = 0$$

Examples: Find the general solution of the differential equation.

$$y^{(6)} - y'' = 0$$

Examples: Find the solution of the initial value problem.

$$y''' - y'' + 9y' - 9y = 0; \quad y(0) = y'(0) = 0, \quad y''(0) = 2$$

Examples: Find a homogeneous differential equation of least order that has the following function as a solution.

$$y = 2e^{2x} + 3 \sin x - x$$

Finding the General Solution to the Nonhomogeneous Equation

$$y^{(n)} + p_{n-1}(x)y^{(n-1)} + p_{n-2}(x)y^{(n-2)} + \cdots + p_1(x)y' + p_0(x)y = f(x)$$

$$y = C_1y_1(x) + C_2y_2(x) + \cdots + C_ny_n(x) + z(x)$$

Term: Particular solution.

**Finding a Particular Solution in the
Constant Coefficient Case**

$$y^{(n)} + a_{n-1}y^{(n-1)} + \dots + a_1y' + a_0y = f(x)$$

Term: Undetermined coefficients, variation of parameters.

Example: Find the general solution to

$$y^{(4)} - y = 2e^x + \cos x$$

Laplace Transforms

Motivation: Laplace transforms can be used to turn linear constant coefficient differential equations into algebraic equations.

DEFINITION Let f be a continuous function on $[0, \infty)$. The Laplace transform of f , denoted by $\mathcal{L}[f(x)]$, or by $F(s)$, is the function given by

$$\mathcal{L}[f(x)] = F(s) = \int_0^{\infty} e^{-sx} f(x) dx. \quad (1)$$

The domain of F is the set of all real numbers s for which the improper integral converges.

Illustrative Examples:

$$L[f(x)] = \int_0^{\infty} e^{-sx} f(x) dx$$

$$L[e^x] =$$

$$L[e^{2x}] =$$

$$L[e^{ax}] =$$

Recall:

$$L[f(x)] = \int_0^{\infty} e^{-sx} f(x) dx$$

As a result...

1. $L[\alpha f(x)] =$

2. $L[f(x) + g(x)] =$

$$L [y'(x)] =$$

$$L [y''(x)] =$$

Example:

Find the Laplace transform of the solution to

$$y''+3y'-4y = 3e^{-x} + 2, \quad y(0) = 2, \quad y'(0) = -1.$$

We will do this directly, without finding the solution first!!

Recall:

$$L[y'(x)] = -y(0) + sL[y(x)]$$

$$L[y''(x)] = -y'(0) - sy(0) + s^2L[y(x)]$$

More Examples:

$$L[1] =$$

$$L[x] =$$

$$L[\cos(x)] =$$

$$L[\sin(x)] =$$

Table of Laplace Transforms **Add others, or create your own!!**

$f(x)$	$F(s) = \mathcal{L}[f(x)]$
1	$\frac{1}{s}, \quad s > 0$
$e^{\alpha x}$	$\frac{1}{s - \alpha}, \quad s > \alpha$
$\cos \beta x$	$\frac{s}{s^2 + \beta^2}, \quad s > 0$
$\sin \beta x$	$\frac{\beta}{s^2 + \beta^2}, \quad s > 0$
$e^{\alpha x} \cos \beta x$	$\frac{s - \alpha}{(s - \alpha)^2 + \beta^2}, \quad s > \alpha$
$e^{\alpha x} \sin \beta x$	$\frac{\beta}{(s - \alpha)^2 + \beta^2}, \quad s > \alpha$
$x^n, \quad n = 1, 2, \dots$	$\frac{n!}{s^{n+1}}, \quad s > 0$
$x^n e^{rx}, \quad n = 1, 2, \dots$	$\frac{n!}{(s - r)^{n+1}}, \quad s > r$
$x \cos \beta x$	$\frac{s^2 - \beta^2}{(s^2 + \beta^2)^2}, \quad s > 0$
$x \sin \beta x$	$\frac{2\beta s}{(s^2 + \beta^2)^2}, \quad s > 0$

$$L[y'(x)] = -y(0) + sL[y(x)]$$

$$L[y''(x)] = -y'(0) - sy(0) + s^2L[y(x)]$$

$$L[f(x)] = \int_0^{\infty} e^{-sx} f(x) dx$$

$$L[2\sin(x) - 3e^{-x} + 1] =$$

$$L[3e^{2x} \cos(3x) + x \sin(x) - 3x^2] =$$

Note: $L [f(x) g(x)]$ is generally NOT equal to $L [f(x)] L [g(x)]$.

Example: Use the Laplace transform to solve

$$y'' - y' - 6y = e^{-x}, \quad y(0) = 2, \quad y'(0) = 3.$$

(Note: We can do this easier, without Laplace transforms, but I want to illustrate the process.)

Recall:

$$L[y'(x)] = -y(0) + sL[y(x)]$$

$$L[y''(x)] = -y'(0) - sy(0) + s^2L[y(x)]$$

The TRUTH!!

The Laplace Transform is typically used to solve problems of the form

$$\begin{cases} y'' + ay' + by = f(t) \\ y(0) = b, y'(0) = m \end{cases}$$

where $f(t)$ is a piecewise defined function.