

Notes:

- See the discussion board for curve information and instructions for obtaining a scanned graded copy of your midterm exam.
- Homework is posted.
- **There is no excuse for not having excellent online quiz grades!**



Open EMCF07b.

EMCF07b

$$A = \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}$$

1. One eigen value of the matrix A is 3. What is the other eigenvalue?

- a. 2
- b. -2
- c. -1
- d. 0
- e. None of these.

$$\det(A - \lambda I) = \det \begin{pmatrix} 1-\lambda & 2 \\ 2 & 1-\lambda \end{pmatrix}$$

$$= (-\lambda)^2 - 4$$

$$= 1 - 2\lambda + \lambda^2 - 4$$

$$= \lambda^2 - 2\lambda - 3$$

$$= (\lambda - 3)(\lambda + 1)$$

Eig. vals.

$$\lambda = 3, \lambda = \underline{\underline{-1}}$$

EMCF07b $A = \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}$

2. One eigenvector associated with the eigenvalue 3 of the matrix A has 1 as its first entry. What is its second entry of this eigenvector?

- a. 2
- b. -2
- c. -1
- d. 0
- e. None of these.

$\lambda = 3$: Eig. vectors are nonzero
solns to $Ax = 3x$,
which is eqn. to

$$(A - 3I)x = \vec{0}$$

$$\begin{pmatrix} -2 & 2 \\ 2 & -2 \end{pmatrix}x = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

Aug. Matrix:

$$\begin{pmatrix} -2 & 2 & 0 \\ 2 & -2 & 0 \end{pmatrix}$$

$$R_1 + R_2 \rightarrow R_2$$

$$\begin{pmatrix} -2 & 2 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$-2x_1 + 2x_2 = 0 \Leftrightarrow x_1 = x_2.$$

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} x_2 \\ x_2 \end{pmatrix} = x_2 \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad x_2 \neq 0.$$

$$\text{First entry} = 1 \Rightarrow x_2 = 1$$

$$\Rightarrow \text{Second entry} = 1.$$

Solutions to linear first order systems.

Motivating Example: Solve

$$x' = x - 3y$$

$$y' = -2x + 2y$$

It is understood that x and y are functions of the same independent variable. e.g. $x = x(t)$

$$y = y(t)$$

$$x'(t) = x(t) - 3y(t)$$

$$y'(t) = -2x(t) + 2y(t)$$

we will "drop" the "of t " portion.

$$x' = x - 3y$$

$$y' = -2x + 2y$$

Matrix form:

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} 1 & -3 \\ -2 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

↑
derivative of
my unknown
↑
unknown

Names: $u = \begin{pmatrix} x \\ y \end{pmatrix}$, $A = \begin{pmatrix} 1 & -3 \\ -2 & 2 \end{pmatrix}$

⇒ the system is

$$u' = Au.$$

Let's see how eigenvalues and eigenvectors play a role in solving this type of problem.

$$\boxed{u' = Au}$$

Motivation: If A is just a real number then At
 $u(t) = Ce^{\lambda t}$

But, it is not. Still, you might think the exponential function plays a role. It does!!.

Guess: A sol'n could look like

$$u = \vec{v} e^{kt}$$

$$\text{If so, } u' = Au$$

$$\Leftrightarrow \vec{v} \cancel{k} e^{kt} = A \vec{v} e^{kt}$$

$$A\vec{v} = k\vec{v}$$

If $\vec{v} \neq \vec{0}$ then \vec{v} is an eigenvector assoc. with the eigenvalue k .

Back to

$$\begin{aligned}x' &= x - 3y \\y' &= -2x + 2y\end{aligned}$$

$$u = \begin{pmatrix} x \\ y \end{pmatrix}$$

$$u' = \begin{pmatrix} 1 & -3 \\ -2 & 2 \end{pmatrix} u$$

Eigen pairs of $A = \begin{pmatrix} 1 & -3 \\ -2 & 2 \end{pmatrix}$.

eigen values and associated eigen vectors

The characteristic polynomial of A is given by

$$\det(A - zI) = -4 - (3)z + z^2$$

The eigenvalues of A are the roots, which are -1 and 4.

$A - (-1)I$ is

$$\begin{pmatrix} 2 & -3 \\ -2 & 3 \end{pmatrix}$$

The augmented matrix for $(A - (-1)I)x = 0$

$$\begin{pmatrix} 2 & -3 & 0 \\ -2 & 3 & 0 \end{pmatrix}$$

The rref is

$$\begin{pmatrix} 1 & -3/2 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$\rightarrow x_1 = \frac{3}{2}x_2$

$$\Rightarrow \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} \frac{3}{2}x_2 \\ x_2 \end{pmatrix} = x_2 \begin{pmatrix} \frac{3}{2} \\ 1 \end{pmatrix},$$

$$x_2 \neq 0$$

$x = -1$

$$\therefore x_1 = \frac{3}{2}x_2 \Rightarrow \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} \frac{3}{2}x_2 \\ x_2 \end{pmatrix} = x_2 \begin{pmatrix} \frac{3}{2} \\ 1 \end{pmatrix},$$

$$x_2 \neq 0$$

$A - (4)I$ is

$$\begin{pmatrix} -3 & -3 \\ -2 & -2 \end{pmatrix}$$

The augmented matrix for $(A - 4I)x = 0$ is

$$\begin{pmatrix} -3 & -3 & 0 \\ -2 & -2 & 0 \end{pmatrix}$$

The rref is

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$\rightarrow x_1 = -x_2$

$$\Rightarrow \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} -x_2 \\ x_2 \end{pmatrix} = x_2 \begin{pmatrix} -1 \\ 1 \end{pmatrix},$$

$$x_2 \neq 0$$

$x = 4$

$$\therefore x_1 = -x_2 \Rightarrow \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} -x_2 \\ x_2 \end{pmatrix} = x_2 \begin{pmatrix} -1 \\ 1 \end{pmatrix},$$

$$x_2 \neq 0$$

$\therefore \begin{pmatrix} 3/2 \\ 1 \end{pmatrix} e^{-t}$ and $\begin{pmatrix} -1 \\ 1 \end{pmatrix} e^{4t}$ are sol'n to $x' = x - 3y$
 $y' = -2x + 2y$ $\Leftrightarrow u' = Au$

Linearly

So what?

You can show that

$$u = c_1 \begin{pmatrix} 3/2 \\ 1 \end{pmatrix} e^{-t} + c_2 \begin{pmatrix} -1 \\ 1 \end{pmatrix} e^{4t}$$

is the general sol'n to the system of ODE's.

Recall: $u = \begin{pmatrix} x \\ y \end{pmatrix} \Rightarrow$

$$x = \frac{3}{2}c_1 e^{-t} - c_2 e^{4t}$$

$$y = c_1 e^{-t} + c_2 e^{4t}$$

Here c_1 and c_2 are arbitrary constants.

Solve the Initial Value Problem

system of ODEs

$$\begin{cases} x' = x - 3y \\ y' = -2x + 2y \end{cases}$$

$$\begin{cases} x(0) = -1 \\ y(0) = 2 \end{cases}$$

Initial Data

$$x = \frac{3}{2}c_1 e^{-t} - c_2 e^{4t}$$

$$y = c_1 e^{-t} + c_2 e^{4t}$$

Goal: Find c_1, c_2 so that the initial data is satisfied.

$$\begin{cases} \frac{3}{2}c_1 - c_2 = -1 \\ c_1 + c_2 = 2 \end{cases} \rightarrow \begin{aligned} \frac{3}{2}(2 - c_2) - c_2 &= -1 \\ 3 - \frac{5}{2}c_2 &= -1 \\ \frac{5}{2}c_2 &= 4 \end{aligned}$$

$$c_1 = 2 - c_2$$

$$c_2 = \frac{8}{5}$$

$$c_1 = \frac{2}{5}$$

∴

$$x = \frac{3}{5}e^{-t} - \frac{8}{5}e^{4t}$$

$$y = \frac{2}{5}e^{-t} + \frac{8}{5}e^{4t}$$

First Order Linear Systems of Differential Equations

$$u'(t) = Au(t)$$

A is an $n \times n$ real matrix.

A is known.

$u(t)$ is an $n \times 1$ unknown function.

Goal: Find $u(t)$.

Terms: General solution, initial value problem, fundamental matrix.

$$\rightarrow t_0 \quad u'(t) = Au(t)$$

An expression for $u(t)$ in terms of n arbitrary constants, so that whenever $u(t_0)$ is specified, we

can find unique ^{given} values of the arb. constants so that $u(t)$ satisfies this data.

$$\begin{cases} u'(t) = Au(t) \\ u(t_0) = \vec{u}_0 \end{cases} \quad \begin{matrix} \text{system of ODEs} \\ \text{initial data.} \end{matrix}$$

known

A fundamental matrix for $u'(t) = Au(t)$

which is nonsingular and has columns that solve $u'(t) = Au(t)$.

Note: If $\mathbf{U}(t)$ is a fundamental matrix then the general sol'n to $u' = Au$ is

$$\mathbf{U}(t) \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{pmatrix}.$$

Note: $x' = x - 3y$ has a fundamental

$$y' = -2x + 2y$$

matrix given by

$$\begin{pmatrix} e^{-t} & -e^{4t} \\ e^{-t} & e^{4t} \end{pmatrix}$$

Question: Is there a relation to higher order scalar linear differential equations?

A: Yes

e.g. Consider

$$\text{charact poly is } \lambda^2 - 2\lambda - 3$$

$$y'' - 2y' - 3y = 0.$$

Note: If we rename

$$\begin{aligned} v &= y \quad \text{and} \quad w = y' \\ \text{Then} \quad \begin{cases} v' = y' \\ w' = y'' = 3y + 2y' = 3v + 2w \end{cases} &= w \end{aligned}$$

$$\begin{cases} v' = w \\ w' = 3v + 2w \end{cases} \quad \text{companion matrix}$$

$$\begin{pmatrix} v' \\ w' \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 3 & 2 \end{pmatrix} \begin{pmatrix} v \\ w \end{pmatrix}$$

Note: characteristic poly of $\begin{pmatrix} 0 & 1 \\ 3 & 2 \end{pmatrix}$

$$\begin{aligned} \det \begin{pmatrix} -\lambda & 1 \\ 3 & 2-\lambda \end{pmatrix} &= -\lambda(2-\lambda) - 3 \\ &= \lambda^2 - 2\lambda - 3 \end{aligned}$$



In General...

special case

How do we solve $\mathbf{u}' = A\mathbf{u}$ when A is a real $n \times n$ matrix with n distinct real eigenvalues?

Setting: $\lambda_1, \lambda_2, \dots, \lambda_n$ distinct real eigenvalues
These will be linearly independent. $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_n$ representative eigen vectors.

Term: Fundamental Matrix

$$\Rightarrow \widetilde{\mathbf{U}(t)} = \begin{pmatrix} \vec{u}_1 e^{\lambda_1 t} & \vec{u}_2 e^{\lambda_2 t} & \dots & \vec{u}_n e^{\lambda_n t} \end{pmatrix}$$

AND the general sol'n is given by

$$\mathbf{U}(t) \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{pmatrix} = c_1 \vec{u}_1 e^{\lambda_1 t} + c_2 \vec{u}_2 e^{\lambda_2 t} + \dots + c_n \vec{u}_n e^{\lambda_n t}$$

5 min

Example: Solve

$$u'(t) = \underbrace{\begin{pmatrix} 2 & 2 & 3 \\ 1 & 2 & 1 \\ 2 & -2 & 1 \end{pmatrix}}_A u(t)$$

First: Find eigen pairs.

charact poly:

$$\det(A - \lambda I) = \det \begin{pmatrix} 2-\lambda & 2 & 3 \\ 1 & 2-\lambda & 1 \\ 2 & -2 & 1-\lambda \end{pmatrix}$$



A is now

$$\begin{pmatrix} 2 & 2 & 3 \\ 1 & 2 & 1 \\ 2 & -2 & 1 \end{pmatrix}$$

The characteristic polynomial of A is given by
 $\det(A - zI) = -8 + (-2)z + (5)z^2 + (-1)z^3$

The eigenvalues of A are

$$-1.0000000000000013 + 0i \iff \lambda = -1$$

$$4.000000000000001 + 0i \iff \lambda = 4$$

$$1.999999999999993 + 0i \iff \lambda = 2$$

(1) $A - (-1)I$ is

$$\begin{pmatrix} 3 & 2 & 3 \\ 1 & 3 & 1 \\ 2 & -2 & 2 \end{pmatrix}$$

the Display Matrix is now

$$\begin{pmatrix} 3 & 2 & 3 & 0 \\ 1 & 3 & 1 & 0 \\ 2 & -2 & 2 & 0 \end{pmatrix}$$

The rref of the Display Matrix is

$$\begin{pmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

(1) $A - (4)I$ is

$$\begin{pmatrix} -2 & 2 & 3 \\ 1 & -2 & 1 \\ 2 & -2 & -3 \end{pmatrix}$$

the Display Matrix is now

$$\begin{pmatrix} -2 & 2 & 3 & 0 \\ 1 & -2 & 1 & 0 \\ 2 & -2 & -3 & 0 \end{pmatrix}$$

The rref of the Display Matrix is

$$\begin{pmatrix} 1 & 0 & -4 & 0 \\ 0 & 1 & -5/2 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

(1) $A - (2)I$ is

$$\begin{pmatrix} 0 & 2 & 3 \\ 1 & 0 & 1 \\ 2 & -2 & -1 \end{pmatrix}$$

the Display Matrix is now

$$\begin{pmatrix} 0 & 2 & 3 & 0 \\ 1 & 0 & 1 & 0 \\ 2 & -2 & -1 & 0 \end{pmatrix}$$

The rref of the Display Matrix is

$$\begin{pmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 3/2 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\left(\begin{array}{c} x_1 \\ x_2 \\ x_3 \end{array} \right) = \left(\begin{array}{c} -x_3 \\ 0 \\ x_3 \end{array} \right) = x_3 \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}, x_3 \neq 0$$

$$\left(\begin{array}{c} x_1 \\ x_2 \\ x_3 \end{array} \right) = \left(\begin{array}{c} 4x_3 \\ \frac{5}{2}x_3 \\ x_3 \end{array} \right) = x_3 \begin{pmatrix} 4 \\ \frac{5}{2} \\ 1 \end{pmatrix}, x_3 \neq 0$$

$$\left(\begin{array}{c} x_1 \\ x_2 \\ x_3 \end{array} \right) = \left(\begin{array}{c} -\frac{3}{2}x_3 \\ -x_3 \\ x_3 \end{array} \right) = x_3 \begin{pmatrix} -\frac{3}{2} \\ -1 \\ 1 \end{pmatrix}, x_3 \neq 0$$

$x_3 \neq 0$

∴ a fundamental matrix is

$$U(t) = \begin{pmatrix} e^{-t} & 4e^{4t} & -e^{2t} \\ 0 & \frac{5}{2}e^{4t} & -\frac{3}{2}e^{2t} \\ e^{-t} & e^{4t} & e^{2t} \end{pmatrix} \quad \text{AND}$$

The general sol'n is

$$U(t) \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = c_1 \begin{pmatrix} e^{-t} \\ 0 \\ e^{-t} \end{pmatrix} + c_2 \begin{pmatrix} 4e^{4t} \\ \frac{5}{2}e^{4t} \\ e^{4t} \end{pmatrix} + c_3 \begin{pmatrix} -e^{2t} \\ -\frac{3}{2}e^{2t} \\ e^{2t} \end{pmatrix}$$

Example: Solve the initial value problem

$$\left\{ \begin{array}{l} u'(t) = \begin{pmatrix} 2 & 2 & 3 \\ 1 & 2 & 1 \\ 2 & -2 & 1 \end{pmatrix} u(t) \\ u(0) = \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix} \end{array} \right. \quad \begin{array}{l} \text{The ODE we just viewed} \\ \text{Initial data} \end{array}$$

General sol'n

$$\begin{pmatrix} -e^{-t} & 4e^{4t} & -e^{2t} \\ 0 & \frac{5}{2}e^{4t} & -\frac{3}{2}e^{2t} \\ e^{-t} & e^{4t} & e^{2t} \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix}$$

we need

$$\begin{pmatrix} -1 & 4 & -1 \\ 0 & \frac{5}{2} & -\frac{3}{2} \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix}$$

The augmented matrix is

$$\begin{matrix} -1, & 4, & -1, & -1; \\ 0, & 5/2, & -3/2, & 1; \\ 1, & 1, & 1, & 2; \\ \text{The rref is} \\ 1, & 0, & 0, & 32/15; \\ 0, & 1, & 0, & 1/5; \\ 0, & 0, & 1, & -1/3; \end{matrix}$$

$$\Rightarrow c_1 = \frac{32}{15}, c_2 = \frac{1}{5}, c_3 = -\frac{1}{3}$$

∴

$$u(t) = \frac{32}{15} \begin{pmatrix} -e^{-t} \\ 0 \\ e^{-t} \end{pmatrix} + \frac{1}{5} \begin{pmatrix} 4e^{4t} \\ \frac{5}{2}e^{4t} \\ e^{4t} \end{pmatrix} - \frac{1}{3} \begin{pmatrix} -e^{2t} \\ -\frac{3}{2}e^{2t} \\ e^{2t} \end{pmatrix}$$

Note: If $u = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$ then

$$x = -\frac{32}{15}e^{-t} + \frac{4}{5}e^{4t} + \frac{1}{3}e^{2t}$$

$$y = \frac{1}{2}e^{4t} + \frac{1}{2}e^{2t}$$

$$z = \frac{32}{15}e^{-t} + \frac{1}{5}e^{4t} - \frac{1}{3}e^{2t}$$

How do we solve $\mathbf{u}' = A\mathbf{u}$ when A is a real $n \times n$ matrix and A has either complex eigenvalues or not enough real eigenvectors (perhaps because some eigenvalues are repeated and we don't have enough linearly independent eigenvectors)?

I'll discuss complex here. I'll discuss the repeated ones later or in a video.

For each complex eigenvalue $a + bi$ (and its conjugate) we have the pair of solutions

a, b real numbers

~~2 min.~~ 2 eig. vals $\underline{a+bi}$ and $\underline{a-bi}$
we expect 2 sol'n pieces to cover these.

$$\begin{array}{l} \xrightarrow{\text{2 linearly}} \\ \text{ind. solns} \end{array} C_1 e^{at} (\cos(bt)\vec{\mathbf{u}} - \sin(bt)\vec{\mathbf{v}})$$

$$\xrightarrow{\quad} C_2 e^{at} (\cos(bt)\vec{\mathbf{v}} + \sin(bt)\vec{\mathbf{u}})$$

Here $\vec{\mathbf{u}}$ and $\vec{\mathbf{v}}$ are real vectors, and $\vec{\mathbf{u}} + i\vec{\mathbf{v}}$ is an eig. vector assoc. with the eig. value $a + bi$.

General sol'n: sum of these -

$$C_1 e^{at} (\cos(bt)\vec{\mathbf{u}} - \sin(bt)\vec{\mathbf{v}}) + C_2 e^{at} (\cos(bt)\vec{\mathbf{v}} + \sin(bt)\vec{\mathbf{u}})$$

where C_1, C_2 are
 a, b . constants.

Example: Solve

$$\begin{aligned}x'(t) &= 2x(t) + y(t) \\y'(t) &= -x(t) + 2y(t)\end{aligned}$$

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3. Find the characteristic polynomial of the coefficient matrix in the system above, and evaluate it at $\lambda = 1$.

- a. 1
- b. 2**
- c. 3
- d. 4
- e. None of these.

$$A = \begin{pmatrix} 2 & 1 \\ -1 & 2 \end{pmatrix}$$

$$\det \begin{pmatrix} 2-\lambda & 1 \\ -1 & 2-\lambda \end{pmatrix} = (2-\lambda)^2 + 1$$

Eval at $\lambda = 1 \Rightarrow$

$$1^2 + 1 = 2$$

Roots of $(2-\lambda)^2 + 1 = 0$:

$$\begin{aligned}\text{Solve } (2-\lambda)^2 + 1 &= 0 \\(2-\lambda)^2 &= -1 \\2-\lambda &= \pm i\end{aligned}$$

$$\Rightarrow \lambda = 2 \mp i$$

Eig. vals:

$$\lambda = 2+i, \lambda = 2-i$$

$\lambda = 2+i$: Solve for nonzero solns of
 $(A - (2+i)\mathbf{I})\mathbf{z} = \vec{0}$

$$\left(\begin{pmatrix} 2 & 1 \\ -1 & 2 \end{pmatrix} - \begin{pmatrix} 2+i & 0 \\ 0 & 2+i \end{pmatrix} \right) \mathbf{z} = \vec{0}$$

$$\begin{pmatrix} -i & 1 \\ -1 & -i \end{pmatrix} \mathbf{z} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

Aug. matrix: $\begin{pmatrix} -i & 1 & 0 \\ -1 & -i & 0 \end{pmatrix}$

$$iR_1 + R_2 \rightarrow R_2 \quad \begin{pmatrix} -i & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$-iz_1 + z_2 = 0 \quad \Leftrightarrow z_2 = iz_1$$

$$\begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = \begin{pmatrix} z_1 \\ iz_1 \end{pmatrix} = \mathbf{z}_1 \begin{pmatrix} 1 \\ i \end{pmatrix}, z_1 \neq 0.$$

representative eig. vector

Note: $\begin{pmatrix} 1 \\ i \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} + i \begin{pmatrix} 0 \\ 1 \end{pmatrix}$.

$$\vec{u} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \vec{v} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\lambda = 2+i \quad a=2, b=1$$

General sol'n:

$$\begin{aligned}
 & C_1 e^{at} (\cos(bt) \vec{u} - \sin(bt) \vec{v}) + C_2 e^{at} (\cos(bt) \vec{v} + \sin(bt) \vec{u}) \\
 &= C_1 e^{2t} \left(\cos(t) \begin{pmatrix} 1 \\ 0 \end{pmatrix} - \sin(t) \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right) + C_2 e^{2t} \left(\cos(t) \begin{pmatrix} 0 \\ 1 \end{pmatrix} + \sin(t) \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right) \\
 &= \begin{pmatrix} C_1 e^{2t} \cos(t) + C_2 e^{2t} \sin(t) \\ -C_1 e^{2t} \sin(t) + C_2 e^{2t} \cos(t) \end{pmatrix} \\
 &= \begin{pmatrix} e^{2t} \cos(t) & e^{2t} \sin(t) \\ -e^{2t} \sin(t) & e^{2t} \cos(t) \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \end{pmatrix} \\
 &\qquad\qquad\qquad \underbrace{\qquad\qquad}_{\text{Fundamental Matr. } X}
 \end{aligned}$$

What if we do not have enough linearly independent eigenvectors?

Example: $\begin{aligned}x'(t) &= 11x(t) - 25y(t) \\y'(t) &= 4x(t) - 9y(t)\end{aligned}$

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} 11 & -25 \\ 4 & -9 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

If $u = \begin{pmatrix} x \\ y \end{pmatrix}$ then
 $u' = \begin{pmatrix} 11 & -25 \\ 4 & -9 \end{pmatrix} u = A u$.

11, -25;
4, -9;

The characteristic polynomial of A is given by

$$\det(A - zI) = 1 - (2z + z^2)^2 = (z-1)^2$$

The only eigenvalue of A is 1, and it is repeated.

$A - (1)I$ is

10, -25;

4, -10;

The augmented matrix for $(A - I)z = 0$

10, -25, 0;

4, -10, 0;

The rref is

1, -5/2, 0;

0, 0, 0;

$$\lambda = 1$$

$$z_1 = \frac{5}{2}z_2 \Rightarrow \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = \begin{pmatrix} \frac{5}{2}z_2 \\ z_2 \end{pmatrix} = z_2 \begin{pmatrix} \frac{5}{2} \\ 1 \end{pmatrix}$$

Taking $z_2 = 2$ gives $\begin{pmatrix} 5 \\ 2 \end{pmatrix}$ as a rep. eig. vector.

Hm... we get one column.

$$\begin{pmatrix} 5 \\ 2 \end{pmatrix} e^t$$

So, we need a strategy to get a second lin. ind. sol'n.

Let's look for a second sol'n in the form $(\vec{v} + \vec{w})e^t$

we need $(\vec{v} + \vec{w})e^t = A(\vec{v} + \vec{w})e^t$

$$\vec{v}e^t + (\vec{v} + \vec{w})e^t = A\vec{v}e^t + A\vec{w}e^t$$

$$\vec{v} + \vec{w} + t\vec{v} = tA\vec{v} + A\vec{w}$$

i.e. $A\vec{v} = \vec{v}$
and $A\vec{w} = \vec{w} + \vec{v}$ \Leftrightarrow $\begin{cases} A\vec{v} = \vec{v} \\ (A-I)\vec{w} = \vec{v} \end{cases}$

Try $\vec{v} = \begin{pmatrix} 5 \\ 2 \end{pmatrix}$ \Leftrightarrow $\begin{cases} \vec{v} \text{ is an eig. vector assoc.} \\ \text{with } \lambda = 1. \end{cases}$

$$(A-I)\vec{w} = \begin{pmatrix} 5 \\ 2 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} 10 & -25 \\ 4 & -10 \end{pmatrix} \vec{w} = \begin{pmatrix} 5 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} 10 & -25 \\ 4 & -10 \end{pmatrix} \vec{\omega} = \begin{pmatrix} 5 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} 10 & -25 & 5 \\ 4 & -10 & 2 \end{pmatrix}$$

10, -25, 5;
4, -10, 2;
The rref of the _Display_Matrix is
1, -5/2, 1/2;
0, 0, 0;

$$\Rightarrow \omega_1 = \frac{5}{2}\omega_2 + \frac{1}{2}$$

$$\Rightarrow \begin{pmatrix} \omega_1 \\ \omega_2 \end{pmatrix} = \begin{pmatrix} \frac{5}{2}\omega_2 + \frac{1}{2} \\ \omega_2 \end{pmatrix}. \quad \text{use any}$$

ω_2 value. I just need $\vec{\omega}$
that works. Use $\omega_2 = 0$

$$\vec{\omega} = \begin{pmatrix} \frac{1}{2} \\ 0 \end{pmatrix}. \quad \text{Recall } \vec{v} = \begin{pmatrix} 5 \\ 2 \end{pmatrix}$$

$$\text{2nd Sol'n: } (\vec{v}t + \vec{\omega})e^t = \begin{pmatrix} (st + \frac{1}{2})e^t \\ 2te^t \end{pmatrix}$$

Putting this with $\begin{pmatrix} 5 \\ 2 \end{pmatrix}e^t$ gives

2 Lin. Ind. Sol'n's. \Rightarrow

Fundamental Matrix

$$U(t) = \begin{pmatrix} st & (st + \frac{1}{2})e^t \\ 2e^t & 2te^t \end{pmatrix}$$

General Sol'n is

$$U(t) \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = c_1 \begin{pmatrix} 5e^t \\ 2e^t \end{pmatrix} + c_2 \begin{pmatrix} (st + \frac{1}{2})e^t \\ 2te^t \end{pmatrix}.$$

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- 4. A
- 5. B
- 6. C