FINAL

Math 5331 Linear Algebra Online This Final is worth 200 points. You are not allowed to use any books or notes.

You have three hours to complete the test.

- **1**. Define that **U** is a subspace of the vector space **V**. **Answer**: *U* is non-empty and closed under addition, that is if $u, v \in U$ then $u + v \in U$ and $\alpha . u \in U$.
- **2**. Proof that the solution space of a linear homogeneous system AX = 0 of *m* equations in *n* unknowns with real coefficients is a subspace of \mathbb{R}^n **Answer**: We always have AO = 0, that is the solution space is never empty. And AX = 0 and AY = 0, then $A(X + Y) = AX + AY = 0 + 0 = 0, A\alpha X = \alpha AX = \alpha 0 = 0$
- **3**. **a**. Define that the vectors $v_1, v_2, ..., v_k$ are linearly independent. Answer: $c_1v_1 + ... + c_kv_k = 0$ only if $c_1 = ... = c_k = 0$
 - **b**. Define the span of vectors $v_1, v_2, ..., v_k$. Answer: $span\{v_1, ..., v_k\} = \{c_1v_1 + ... + c_kv_k | c_1 \in \mathbb{R} ... c_k \in \mathbb{R}\}$ The span is the set of all linear combinations.
- **4**. Define that the vectors $v_1, v_2, ..., v_k$ are a basis of the vector space **V**. Answer: The vectors have to be linearly independents and generating.
- **5**. Find a basis of all solutions for the linear homogeneous system

Answer: The matrix is already in row echelon form

 $x_1 = x_2 - 5x_4, x_3 = -2x_4 - 2x_6, x_5 = -2x_6$. Free variables are x_2, x_4, x_6 . This gives us a three dimensional solution space:

 $X_2 = (1, 1, 0, 0, 0), X_4 = (-5, 0, -2, 1, 0, 0), X_6 = (0, 0, -2, 0, -2, 1)$ are a basis. SNB check:

Name:

- **6**. If **A** is an $m \times n$ matrix of rank *r*, what is then the dimension of the solution space of the linear homogeneous system $\mathbf{A}X = 0$? Answer: n r
- 7. **a**. Define that $T : \mathbf{U} \to \mathbf{V}$ is a linear map from the vector space \mathbf{U} to the vector space \mathbf{V} . Answer: $T(\alpha + \beta) = T(\alpha) + T(\beta), T(c\alpha) = cT(\alpha)$
 - **b**. How are null-spaces and range of a linear map defined? Answer: $N(T) = \{\alpha | T(\alpha) = 0\}, R(T) = \{\beta | \beta = T(\alpha) \text{ for some } \alpha\}$
 - **c**. Let *T* be a linear map from \mathbb{R}^n to \mathbb{R}^m . How is the matrix **A** for *T* with respect to the unit vectors defined? Answer: The matrix *A* for *T* is an $m \times n$ matrix where you have in the i^{th} column the m tuple $T(e_i^n) \in \mathbb{R}^m$, i = 1, ..., n.
 - **d**. Express null space and range of *T* in terms of the matrix **A** for *T*. In particular relate column and row rank of **A** to the dimensions of null space and range of *T*. Answer: The null-space of *T* is the solution space for AX = 0. The range of *T* is the space generated by the columns of *A*. We have *column rank=dimension of the range*, *dimension of null space=n row rank*.
- **8**. Let $T : \mathbf{U} \to \mathbf{V}$ be a linear map from the vector space \mathbf{U} to the vector space \mathbf{V} . Prove that if the vectors $T(v_1), T(v_2), \dots, T(v_k)$ are linearly independent, then v_1, v_2, \dots, v_k are linearly independent. Answer: We can prove this in contraposition. Assume that v_1, v_2, \dots, v_k are linearly dependent. Then without loss of generality one has that $c_1 = c_2v_2 + \ldots + c_kv_k$. But then $T(c_1) = c_2T(v_2)\ldots + c_kT(v_k)$ that is $T(c_1),\ldots, T(c_k)$ are linearly dependent.
- **9**. Assume that the linear map T on \mathbb{R}^3 has matrix

$$\mathbf{A} = \left(\begin{array}{rrr} 2 & 1 & 5 \\ 3 & 1 & 7 \\ 1 & 3 & 5 \end{array} \right)$$

- **a**. Find a basis for the null space of *T*. Answer: null-space basis (-2, -1, 1) Trivial calculation
- **b**. Find a basis for the range of *T*. Answer: any two columns are are basis.
- **10**. Let *T* be a linear map from $\mathbb{R}^n \to \mathbb{R}^n$ and let $\lambda \in \mathbb{R}$.
 - **a**. Define the characteristic polynomial $c_T(x)$ of *T*. What is the characteristic polynomial of the identity map on \mathbb{R}^n and what is the characteristic polynomial of the zero map on \mathbb{R}^n ? Answer: Let *A* be the matrix of $A. c_T(x) = \det(A xI_n); c_{I_n}(x) = \det(I_n xI_n) = (1 x)^n; \det(0_{n \times n} xI_n) = (-1)^n x^n$
 - $A.c_{T}(x) = dct(A xI_{n}), c_{I_{n}}(x) = dct(I_{n} xI_{n}) = (1 x), dct(O_{n \times n} xI_{n})$
 - **b**. Define that λ is an eigenvalue of *T*. Answer: $c_T(\lambda) = 0$;
 - **c**. Define that \mathbf{E}_{λ} is the eigenspace for λ . Answer: $E_{\lambda} = \{v | T(v) = \lambda v\}$