

Linear Systems and the Span of Vectors

Given a set S of vectors, the problem of finding a basis for the span is an important problem in Linear Algebra. It has a straight-forward solution. If $S = \{v_1, v_2, \dots, v_k\}$ then let A the matrix which has the v_i as its rows. It is easy to see that the elementary row operations on A do not change the $\text{span}(S)$. That is, the non-zero rows of $\text{REF}(A)$ form a basis and its number gives us also $\dim(\text{span}(S))$. The following example should look familiar:

$$S = \{v_1 = (1, 0, -1, 0), v_2 = (0, 1, 1, 1), v_3 = (5, 4, -1, 4)\}$$

$$\text{Then } A = \begin{pmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & 1 & 1 \\ 5 & 4 & -1 & 4 \end{pmatrix} \text{ has the row echelon form: } \begin{pmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Thus, $u_1 = (1 \ 0 \ -1 \ 0)$ and $u_2 = (0 \ 1 \ 1 \ 1)$ form a basis and $\dim(\text{span}(S)) = 2$.

Because v_1 and v_2 are linearly independent, they too form a basis. Or any two of the three v_i 's.

One could also start with the observation that the first two vectors are linearly independent and check for $v_3 \in \text{span}\{v_1, v_2\}$. That amounts to solving

$$x_1 v_1 + x_2 v_2 = v_3. \text{ This is a linear system : } x_1 \begin{pmatrix} 1 \\ 0 \\ -1 \\ 0 \end{pmatrix} + x_2 \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 5 \\ 4 \\ -1 \\ 4 \end{pmatrix}. \text{ It can be}$$

$$\text{solved now by computing the row echelon form of } B = \begin{pmatrix} 1 & 0 & 5 \\ 0 & 1 & 4 \\ -1 & 1 & -1 \\ 0 & 1 & 4 \end{pmatrix} \text{ This is a}$$

4×2 – matrix with an augmented right column.

Again, an easy calculation yields:

$$\begin{pmatrix} 1 & 0 & 5 \\ 0 & 1 & 4 \\ -1 & 1 & -1 \\ 0 & 1 & 4 \end{pmatrix} \text{ has row echelon form: } \begin{pmatrix} 1 & 0 & 5 \\ 0 & 1 & 4 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \text{ and this means, } x_1 = 5 \text{ and}$$

$$x_2 = 4. \text{ Indeed, } 5 \begin{pmatrix} 1 \\ 0 \\ -1 \\ 0 \end{pmatrix} + 4 \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 5 \\ 4 \\ -1 \\ 4 \end{pmatrix}$$

Coming back to A , what is the meaning of $AX = 0$? It stands for the homogeneous system:

$x_1 - x_3 = 0, x_2 + x_3 + x_4 = 0, 5x_1 + 4x_2 - x_3 + 4x_4 = 0$. From its row echelon form we see that $x_1 = x_3, x_2 = -x_3 - x_4$ and we get the general solution X as linear combinations of two basis solutions:

$$X_3 = \begin{pmatrix} 1 \\ -1 \\ 1 \\ 0 \end{pmatrix}, X_4 = \begin{pmatrix} 0 \\ -1 \\ 0 \\ 1 \end{pmatrix}, X = x_3 \begin{pmatrix} 1 \\ -1 \\ 1 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} 0 \\ -1 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} x_3 \\ -x_3 - x_4 \\ x_3 \\ x_4 \end{pmatrix}$$

Now comes the question: What have X_3 and X_4 to do with $\text{span}(S)$? These two vectors span a two-dimensional subspace of \mathbb{R}^4 , but certainly not $\text{span}(S)$.

What we have is this: $v_1 X_3 = 0, v_1 X_4 = 0; v_2 X_1 = 0, v_2 X_2 = 0$ (we can omit similar equations with v_3) The products are matrix products of rows v_i 's and columns X_j . Of course, $v_i X_j = 0$ is the same as $X_j^t v_i^t = 0$. This says that the system $CX = 0$ where the rows are X_3^t, X_4^t has as $\text{span}(S)$ as its solution space:

$$\begin{pmatrix} 1 & -1 & 1 & 0 \\ 0 & -1 & 0 & 1 \end{pmatrix} X = 0 \text{ has solution space } \text{span}(S). \text{ Check:}$$

$$\begin{pmatrix} 1 & -1 & 1 & 0 \\ 0 & -1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 5 \\ 0 & 1 & 4 \\ -1 & 1 & -1 \\ 0 & 1 & 4 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

This example can be generalized to a theorem.

Theorem Any subspace U of \mathbb{R}^n is the solution set of a linear system $CX = 0$.

Proof. Let $S = \{\alpha_1, \dots, \alpha_k\}$ be a basis of U . Then solve the linear system $AX = 0$ which has the k -vectors $\alpha_i \in \mathbb{R}^n$ as rows. A is an $k \times n$ -matrix. The rank of B is k and therefore the null-space is of dimension $n - k$. We get $(n - k)$ -many linearly independent solution vectors X_1, \dots, X_{n-k} . These are column vectors with n -many components. We form the matrix C which has the X_i as rows. Then C has rank $n - k$ and therefore the null space has dimension k . This null space contains S and therefore is equal to U .

Example.

Let $S = \{u = (1, 0, 1, 2, 3), (2, 1, 3, 4, -1)\}$ be two vectors in \mathbb{R}^5 . They are obviously independent and the span is 2-dimensional.

$U = \{su + tv \mid s, t \in \mathbb{R}\}$ is a plane in \mathbb{R}^5 . Then let

$$A = \begin{pmatrix} 1 & 0 & 1 & 2 & 3 \\ 2 & 1 & 3 & 4 & -1 \end{pmatrix}, \text{ } A \text{ has nullspace basis: } \left[\begin{pmatrix} -1 \\ -1 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -2 \\ 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -3 \\ 7 \\ 0 \\ 0 \\ 1 \end{pmatrix} \right]$$

Then let C be the matrix which has these 3 columns as rows:

$$C = \begin{pmatrix} -1 & -1 & 1 & 0 & 0 \\ -2 & 0 & 0 & 1 & 0 \\ -3 & 7 & 0 & 0 & 1 \end{pmatrix}, \text{ } C \text{ has nullspace basis: } \left[\begin{pmatrix} \frac{1}{2} \\ \frac{3}{14} \\ \frac{5}{7} \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ -\frac{1}{7} \\ -\frac{1}{7} \\ 0 \\ 1 \end{pmatrix} \right]$$

It is not immediate that U has these two vectors as basis. We want to confirm that there are s, t such that

$$s \begin{pmatrix} 1 \\ 0 \\ 1 \\ 2 \\ 3 \end{pmatrix} + t \begin{pmatrix} 2 \\ 1 \\ 3 \\ 4 \\ -1 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} \\ \frac{3}{14} \\ \frac{5}{7} \\ 1 \\ 0 \end{pmatrix} \quad \text{The augmented matrix of this linear system is}$$

$$\begin{pmatrix} 1 & 2 & \frac{1}{2} \\ 0 & 1 & \frac{3}{14} \\ 1 & 3 & \frac{5}{7} \\ 2 & 4 & 1 \\ 3 & -1 & 0 \end{pmatrix} \quad \text{and this system is solved via the row echelon form:}$$

$$\begin{pmatrix} 1 & 2 & \frac{1}{2} \\ 0 & 1 & \frac{3}{14} \\ 1 & 3 & \frac{5}{7} \\ 2 & 4 & 1 \\ 3 & -1 & 0 \end{pmatrix}, \text{ row echelon form: } \begin{pmatrix} 1 & 0 & \frac{1}{14} \\ 0 & 1 & \frac{3}{14} \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \text{ That is}$$

$$\frac{1}{14} \begin{pmatrix} 1 \\ 0 \\ 1 \\ 2 \\ 3 \end{pmatrix} + \frac{3}{14} \begin{pmatrix} 2 \\ 1 \\ 3 \\ 4 \\ -1 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} \\ \frac{3}{14} \\ \frac{5}{7} \\ 1 \\ 0 \end{pmatrix} \text{ which is correct.}$$

$$\text{And similarly, } \begin{pmatrix} 1 & 2 & 0 \\ 0 & 1 & -\frac{1}{7} \\ 1 & 3 & -\frac{1}{7} \\ 2 & 4 & 0 \\ 3 & -1 & 1 \end{pmatrix} \text{ has row echelon form: } \begin{pmatrix} 1 & 0 & \frac{2}{7} \\ 0 & 1 & -\frac{1}{7} \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \text{ which should}$$

$$\text{give } \frac{2}{7} \begin{pmatrix} 1 \\ 0 \\ 1 \\ 2 \\ 3 \end{pmatrix} - \frac{1}{7} \begin{pmatrix} 2 \\ 1 \\ 3 \\ 4 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ -\frac{1}{7} \\ -\frac{1}{7} \\ 0 \\ 1 \end{pmatrix}$$

So, indeed, C is a matrix for U in the sense that U is the solution space for $CX = 0$

We also can interpret $CX = 0$ as finding a base for the kernel of the linear map $T : X \mapsto CX$ and we get the

Theorem Any subspace U is the kernel of some linear map T .