Name:

FINAL

Math 4377 Linear Algebra

This Final is worth 200 points. You are not allowed to use any books or notes. You have three hours to complete the Final.

- **1**. Label the following statements as true or false.
 - **a**. An injective linear map $T: U \rightarrow V$ maps linear independent vectors to linearly independent vectors. T
 - **b**. Any set of linearly independent vectors $v_1, v_2, ..., v_k$ in \mathbb{R}^n can be extended to a basis by adding n k unit vectors. T
 - **c**. Any subspace of \mathbb{R}^n is the solution-space of a linear system Ax = 0. T
 - **d**. Elementary row operations on an $m \times n$ -matrix A don't change the space generated by the columns of A. F
 - **e**. Elementary row operations on an $m \times n$ -matrix A don't change the space generated by the rows of A. T
 - **f**. A linear system AX = 0 of *m* –equations in *n* –unknowns has always a nontrivial solution if n < m F
 - **g**. If an $m \times n$ -matrix A has r-many linearly independent rows than it also must have n r many linearly independent columns. F
 - **h**. The determinant function det is a linear function on the vector space of $n \times n$ –matrices. F
 - **i**. Let *A* be an $n \times n$ –matrix. Then det(*cA*) = c det(*A*). F
 - **j**. For any $n \times n$ –matrix A one has that $det(A^t) = -det(A)$ (A^t is the transpose of) F
 - **a**. Define that the vectors $\alpha_1, \alpha_2, ..., \alpha_k$ are linearly independent. **Answer**: If $c_1\alpha_1 + ... + c_k\alpha_k = 0$ then $c = ... = c_k = 0$
 - **b**. Prove that $\alpha_1, \alpha_2, ..., \alpha_k$ are linearly independent if $\alpha_1 \neq 0$ and for every $0 < i \le k$ one has that $\alpha_i \notin < \alpha_1, ..., \alpha_{i-1} >$ Answer: By induction. $\alpha_1 \neq 0$ is linearly independent. Assume that $\alpha_1, ..., \alpha_{i-1}$ are linearly independent. Then assume that $c_1\alpha_1 + ... + c_{i-1}\alpha_{i-1} + c_i\alpha_i = 0$. If we have $c_i = 0$ then $c_1\alpha_1 + ... + c_{i-1}\alpha_{i-1} = 0$ and by assumption $c_1 = ... = c_{i-1} = 0$. Thus all $c_j = 0$. But $c_i \neq 0$ yields $\alpha_i = (-c_1/c_i)\alpha_1 ... (c_{i-1}/c_i)\alpha_{i-1}$ that is $\alpha_i \notin < \alpha_1, ..., \alpha_{i-1} >$ which is a contradiction.
- 2. Find a linear system with real coefficients for which the span of

$$\alpha_1 = (1, 0, 1, 0, 1), \alpha_2 = (1, 0, 1, 1, 0), \alpha_3 = (2, 0, 1, 1, 0)$$

is the solution space. Solution: $A = \begin{pmatrix} 1 & 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 1 & 0 \\ 2 & 0 & 1 & 1 & 0 \end{pmatrix}$, row echelon form:

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & -1 \end{pmatrix}, x_1 = 0x_2, x_3 = -x_5, x_4 = x_5, \text{ this gives the basis}$$
$$X_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, X_5 = \begin{pmatrix} 0 \\ 0 \\ -1 \\ 1 \\ 1 \end{pmatrix} \text{ as basis for the solution space of } AX = 0 \text{ and the}$$

matrix for the linear system for *i* the three vectors is $B = \begin{pmatrix} 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & -1 & 1 & 1 \end{pmatrix}$

standing for the equations $x_2 = 0, -x_3 + x_4 + x_5 = 0$

- **3**. Define that **A** is the matrix for the linear map $T : U \to V$ with respect to bases $\alpha_1, \ldots, \alpha_n; \beta_1, \ldots, \beta_m$ of *U* and *V*, respectively.
- **4**. Let $T : \mathbb{R}^4 \to \mathbb{R}^3$ be the linear map such that

$$T(1,0,0,0) = (1,2,3), T(0,1,0,0) = (2,6,10), T(0,0,1,0) = (0,-3,-6), T(0,0,0,1) = (-1,-3,-5)$$

- **a**. Find the matrix of T with respect to the unit vectors.
- **b**. Find a basis for (T).
- **c**. Find a basis for ker(T).
- **d**. Find T(1, 1, 1, 1).

Solution:
$$A = \begin{pmatrix} 1 & 2 & 0 & -1 \\ 2 & 6 & -3 & -3 \\ 3 & 10 & -6 & -5 \end{pmatrix}$$
, row echelon form: $\begin{pmatrix} 1 & 0 & 3 & 0 \\ 0 & 1 & -\frac{3}{2} & -\frac{1}{2} \\ 0 & 0 & 0 & 0 \end{pmatrix}$ the rank of A is 2. $im(T) = < \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$, $\begin{pmatrix} 2 \\ 6 \\ 10 \end{pmatrix}$ > The columns of the matrix A span

the image! Its dimension is the column=row rank of *A* and this rank is two. Any two columns of *A* span the image.

The kernel is the solution space of AX = 0. From the row-echelon form we get $x_1 = -3x_3, x_2 = \frac{3}{2}x_3 + \frac{1}{2}x_4$ and a basis is given by

$$X_{3} == \begin{pmatrix} -3 \\ \frac{3}{2} \\ 1 \\ 0 \end{pmatrix}, X_{4} = \begin{pmatrix} 0 \\ \frac{1}{2} \\ 0 \\ 1 \end{pmatrix}$$

$$T\left(\begin{array}{c}1\\1\\1\\1\end{array}\right) = \left(\begin{array}{c}2\\2\\2\end{array}\right)$$

- **5**. **a**. Define that $T : \mathbf{U} \to \mathbf{V}$ is a linear map from the vector space \mathbf{U} to the vector space \mathbf{V} .
 - **b**. How are null-space and range of a linear map defined?
 - **c**. Let T be a linear map from \mathbb{R}^n to \mathbb{R}^m . Define the matrix **A** for T with respect to the unit vectors.
 - **d**. Express null space and range of T in terms of the matrix **A** for T. In particular relate column and row rank of A to the dimensions of the null space and the range of T. Answers are all in the book! Recall that for $T : \mathbb{R}^n \to \mathbb{R}^m$ the matrix for T is an $n \times m$ –matrix A whose columns are the images of the unit vectors of \mathbb{R}^n . Thus the

columns of A are
$$T(e_1^n) = \begin{pmatrix} a_{11} \\ a_{21} \\ \cdots \\ a_{n1} \end{pmatrix}$$
, $T(e_n^n) = \begin{pmatrix} a_{1n} \\ a_{2n} \\ \cdots \\ a_{nn} \end{pmatrix}$. the null space of T is

the solution space of AX = 0 it has dimension n - r if r is the row-rank of A. But **row-rank=column rank=**dim(*range*(*T*))

6. Assume that the linear map T on \mathbb{R}^3 has matrix

$$\mathbf{A} = \left(\begin{array}{rrr} 2 & 1 & 5 \\ 3 & 1 & 7 \\ 1 & 3 & 5 \end{array} \right)$$

- **a**. Find a basis for the null space of T.
- **b**. Find a basis for the range U of T.

c. Find a matrix *B* such that BX = 0 has *U* as solution space. Solution: $\begin{pmatrix} 2 & 1 & 5 \\ 3 & 1 & 7 \\ 1 & 3 & 5 \end{pmatrix}$, row echelon form: $\begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix}$, $x_1 = -2x_3, x_2 = -x_3$ The null space is of dimension 1 and has basis $X_3 = \begin{pmatrix} -2 \\ -1 \\ 1 \end{pmatrix}$

By the dimension equality: $\dim(\ker(T) + \dim(range(T) = 3. \text{ Thus } rang(T) \text{ has})$ dimension 2 and any two columns of A span the range of

$$T : range(T) = \begin{pmatrix} 2 \\ 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 3 \end{pmatrix} > \text{Now we need to find the matrix } B \text{ such that}$$
$$B \cdot \begin{pmatrix} 2 \\ 3 \\ 1 \end{pmatrix} = 0 \text{ and } B \cdot \begin{pmatrix} 1 \\ 1 \\ 3 \end{pmatrix} = 0 \text{ We solve}$$
$$\begin{pmatrix} 2 & 3 & 1 \\ 1 & 1 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0, \begin{pmatrix} 2 & 3 & 1 \\ 1 & 1 & 3 \end{pmatrix} \text{ has row-echelon form } \begin{pmatrix} 2 & 3 & 1 \\ 1 & 1 & 3 \end{pmatrix},$$
$$row \text{ echelon form: } \begin{pmatrix} 1 & 0 & 8 \\ 0 & 1 & -5 \end{pmatrix}, \text{ that is } x_1 = -8x_3, x_2 = 5x_3 \text{ or } X_3 = \begin{pmatrix} -8 \\ 5 \\ 1 \end{pmatrix}$$

or B = (-8, 5, 1) and the only one equation for the range of *T* is $-8x_1 + 5x_2 + x_3 = 0$

7. **Find** the inverse of the matrix

$$\mathbf{A} = \begin{pmatrix} 1 & 2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$
, inverse: $\frac{1}{A} = \begin{pmatrix} 1 & -2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & \frac{1}{2} \end{pmatrix}$

- a. List the defining properties of the determinant function. Answer: 1) The determinant as function of the rows is 1) n –linear as function of the rows, 2)alternating, interchanging the order of two rows then the determinant changes its sign 3)normed, the determinant of the identity is 1
- **b**. State the Leibnitz formula for determinants and describe how to get for an $n \times n$ -matrix *n*!-many terms. Explain how for a triangular matrix only one term can be non-zero. Wont be on the final
- 8. State and prove Cramer's rule. Just did yesterday