

Math 2331 Homework Solutions

1. $v_1 = \begin{pmatrix} 2 \\ 0 \\ 3 \end{pmatrix}, v_2 = \begin{pmatrix} 1 \\ 3 \\ 0 \end{pmatrix}, v_3 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, A = [v_1 \ v_2 \ v_3] = \begin{pmatrix} 2 & 1 & 1 \\ 0 & 3 & 1 \\ 3 & 0 & 1 \end{pmatrix}$

A is row equivalent to $\begin{pmatrix} 1 & 1 & 1 \\ 0 & 3 & 1 \\ 0 & -2 & -1 \end{pmatrix} \sim \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & \frac{1}{3} \\ 0 & 1 & \frac{1}{3} \end{pmatrix} \sim \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & \frac{1}{3} \\ 0 & 0 & 0 \end{pmatrix}$

(6)

A has 3 pivot positions and $Ax=0$ has no free variables.

So the column vectors of A, $\{v_1, v_2, v_3\}$, are linearly independent.

2. $v_1 = \begin{pmatrix} 2 \\ 0 \\ 3 \end{pmatrix}, v_2 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \{v_1, v_2\}$ is a subset of a linearly independent

(7) Set. So $\{v_1, v_2\}$ is linearly independent.

Alt. $A = [v_1 \ v_2]$ has 2 pivots + no free variables.

3. $v_1 = \begin{pmatrix} 2 \\ 3 \end{pmatrix}, v_2 = \begin{pmatrix} 1 \\ -5 \end{pmatrix}, v_3 = \begin{pmatrix} 3 \end{pmatrix}$

(8) 3 vectors in \mathbb{R}^2 must be linearly dependent.

Alternate: $A = [v_1 \ v_2 \ v_3]$ has 2 pivots + 1 free variable.

4. $v_1 = \begin{pmatrix} 3 \\ 0 \\ 1 \end{pmatrix}, v_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, v_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$.

(9) Any set that contains the 0 vector is linearly dependent.

5. $T\left(\begin{pmatrix} u \\ v \end{pmatrix}\right) = \begin{pmatrix} u \\ 4 \end{pmatrix}, T\left(\begin{pmatrix} v \\ w \end{pmatrix}\right) = \begin{pmatrix} 5 \\ w \end{pmatrix}, T$ is linear

(10) a. Then $T(3w) = 3Tw = 3T\begin{pmatrix} v \end{pmatrix} = 3 \cdot \begin{pmatrix} 4 \end{pmatrix} = \begin{pmatrix} 12 \end{pmatrix}$

(11) b. $T(u-2v) = Tw-2Tv = \begin{pmatrix} 4 \end{pmatrix} - 2 \begin{pmatrix} 5 \end{pmatrix} = \begin{pmatrix} -6 \end{pmatrix}$

(12) c. $T(2u+v) = 2Tu+Tv = 2 \cdot \begin{pmatrix} 4 \end{pmatrix} + \begin{pmatrix} 5 \end{pmatrix} = \begin{pmatrix} 13 \end{pmatrix}$

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6. A has reduced echelon form $R = \begin{pmatrix} 1 & 5 & 0 & 2 & 0 & 5 \\ 0 & 0 & 1 & 3 & 0 & 2 \\ 0 & 0 & 0 & 0 & 1 & -3 \end{pmatrix}$

a. Describe the solution set ($b = Ax = 0$).

Solution: $A \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{pmatrix} = 0$ iff $x_1 + 5x_2 = 0$
 $x_3 + 3x_4 + 2x_5 = 0$
 $x_5 - 3x_6 = 0$

(8)

Then $\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{pmatrix} = \begin{pmatrix} -5x_2 \\ x_2 \\ -3x_4 - 2x_5 \\ x_4 \\ x_5 \\ 3x_6 \end{pmatrix} = x_2 \begin{pmatrix} -5 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} 0 \\ 0 \\ -3 \\ 1 \\ 0 \\ 0 \end{pmatrix} + x_5 \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}$

b. Find the solution with $x_2 = 1, x_4 = 0, x_6 = 0$.

(2) Solution: $\begin{pmatrix} -5 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$.

c. Suppose the first column of A is $\begin{pmatrix} 2 \\ -1 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$.

What is the second column?

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Solution: Let A have columns $\{a_1, \dots, a_6\}$.

Then $A \begin{pmatrix} 2 \\ -1 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} = -5a_1 + a_2 = 0$. So $a_2 = 5a_1 = \begin{pmatrix} 10 \\ -5 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$

(2) d. Find the solution with $x_2 = 0, x_4 = 1, x_6 = 0$.

Solution: $\begin{pmatrix} 0 \\ 0 \\ -3 \\ 1 \\ 0 \\ 0 \end{pmatrix}$.

e. If, in addition to the above, $\vec{a}_3 = \begin{pmatrix} 1 \\ 2 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$, find a_4 .

(6)

Solution: Now $\{a_1, \dots, a_6\} \begin{pmatrix} 1 \\ 2 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} = -3a_1 + a_4 = 0$

So $a_4 = 3a_1 = \begin{pmatrix} 3 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$

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6F Are the pivot columns of R linearly independent or dependent?

Solution The pivot columns of any matrix are linearly independent.

(6) The pivot columns of R are $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ which are clearly independent.

Because $RX=0$ if and only if $Ax=0$,

the columns of R have the same dependence relations

as the columns of A . The pivot columns of R

have no dependence relations, so neither do the

pivot columns of A .

7. Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ (be a linear transformation) and suppose

$\{v_1, \dots, v_p\}$ is a set of vectors such that $\{T(v_1), \dots, T(v_p)\}$

is linearly independent. Show that $\{v_1, \dots, v_p\}$ is linearly independent.

Proof One method: Use the contrapositive. That is, show

(8) that if $\{v_1, \dots, v_p\}$ is linearly dependent then $\{T(v_1), \dots, T(v_p)\}$ is linearly dependent.

If $\{v_1, \dots, v_p\}$ is linearly dependent, then there are scalars

c_1, \dots, c_p , not all zero, such that

$$c_1v_1 + \dots + c_pv_p = 0$$

$$\text{Then } 0 = T(0) = T(c_1v_1 + \dots + c_pv_p) = c_1T(v_1) + \dots + c_pT(v_p)$$

Since c_1, \dots, c_p are not all zero, the vectors $\{T(v_1), \dots, T(v_p)\}$ are linearly dependent.

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8 $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is linear & first rotates points counterclockwise $\pi/3$.

then performs a horizontal shear that maps e_2 to $e_2 + 3e_1$

and leaves e_1 unchanged. Find the standard matrix.

$$\text{Method 1. } T(e_1) = S(R(\delta)) \quad S = \text{shear, R = rotation}$$

$$= S \left(\begin{pmatrix} e_1 \\ \sqrt{3}e_2 \end{pmatrix} \right) = S \left(\begin{pmatrix} e_1 \\ e_2 \end{pmatrix} + \begin{pmatrix} 0 \\ \sqrt{3}e_2 \end{pmatrix} \right) = \begin{pmatrix} e_1 \\ e_2 \end{pmatrix} + \sqrt{3}e_1 \left(e_2 + 3e_1 \right)$$

$$(8) \quad = \begin{pmatrix} e_1 + 3\sqrt{3}e_2 \\ \sqrt{3}e_1 \end{pmatrix}$$

$$T(e_2) = S \left(\begin{pmatrix} -\frac{\sqrt{3}}{2} \\ \frac{1}{2} \end{pmatrix} \right) = S \left(-\frac{\sqrt{3}}{2}e_1 + e_2 \right) = -\frac{\sqrt{3}}{2}e_1 + e_2 (e_2 + 3e_1)$$

$$= \begin{pmatrix} -\frac{\sqrt{3}}{2} \\ e_2 \end{pmatrix}$$

Then T has standard matrix $\begin{pmatrix} e_1 + 3\sqrt{3}e_2 & -\frac{\sqrt{3}}{2} \\ \sqrt{3}e_1 & e_2 \end{pmatrix}$

$$\text{Method 2 } R \text{ has standard matrix } \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} = \begin{pmatrix} e_1 & -\sqrt{3}e_2 \\ \sqrt{3}e_1 & e_2 \end{pmatrix}$$

S has standard matrix $\begin{pmatrix} 1 & 3 \\ 0 & 1 \end{pmatrix}$

Then $T = SOR$ has standard matrix $\begin{pmatrix} 1 & 3 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} e_1 & -\sqrt{3}e_2 \\ \sqrt{3}e_1 & e_2 \end{pmatrix}$

$$= \begin{pmatrix} e_1 + 3\sqrt{3}e_2 & -\frac{\sqrt{3}}{2} \\ \sqrt{3}e_1 & e_2 \end{pmatrix}$$

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9. If the columns of AB are independent

$AB = [Ab_1 \dots Ab_p]$ so $\{Ab_1, \dots, Ab_p\}$ is linearly independent

then $\{b_1, \dots, b_p\}$ must be linearly independent by problem 7.

(8)